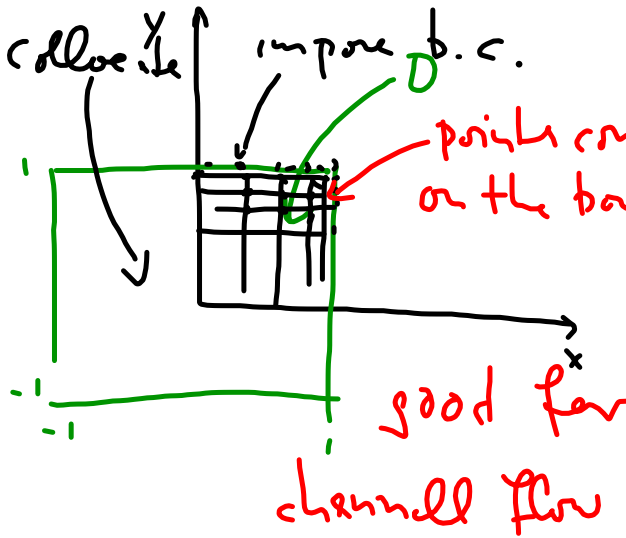


§ 6.2 2D Boundary value probl.

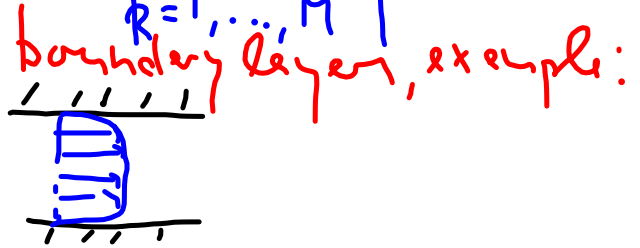
Ex.: $u_{xx} + u_{yy} = f(x,y)$ over $(x,y) \in [0,1]^2$
 b.c. $u = 0$ on $\partial\Omega$



$$x_j = \cos \frac{\pi(2j-1)}{2N}$$

$$y_k = \cos \frac{\pi(2k-1)}{2M}$$

$j = 1, \dots, N$
 $k = 1, \dots, M$ } NM points



$$U = \sum_{n=0}^{N-1} \sum_{m=0}^{M-1} a_{nm} T_n(x) T_m(y)$$

For $j=2, \dots, N-1$; $k=2, \dots, M-1$ collect:

$$\sum_{n=0}^{N-1} \sum_{m=0}^{M-1} a_{nm} (T_n''(x_j) T_m(y_k) + T_n(x_j) T_m''(y_k))$$

= $f(x_j, y_k)$: $(N-2)(M-2)$ equations

of variables a_{nm} : NM

$$\text{b.c. } \sum \sum a_{nm} T_n^{(-1)} T_m(\gamma_k) = 0, k=1, \dots, M$$

$$T_n(1)$$

$$\sum \sum a_{nm} T_n(x_j) T_m^{(-1)} = 0 \quad j=2, \dots, N-1$$

$$T_m(1)$$

$$\# \text{ of b.c. } 2M + 2(N-2) + (N-2)(M-2) = NM$$

of equations = # of variables

Now we have to write as

$$\underline{\underline{A}} \underline{\hat{u}} = \hat{f}$$

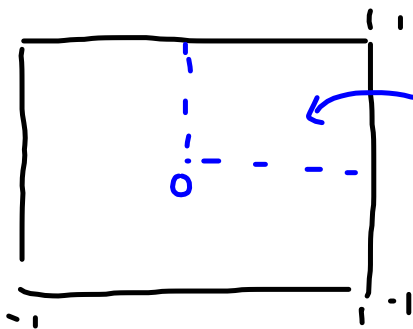
length NM
 $NM \times NM$ matrix

→ build in as much structure as possible

write $a_{nm} = \hat{u}_{n+N+1}$

$$\underline{\hat{u}} = \begin{bmatrix} a_{0,0} \\ a_{1,0} \\ \vdots \\ a_{N-1,0} \\ a_{0,1} \\ \vdots \\ a_{N-1,1} \\ \vdots \\ a_{N-1,N-1} \end{bmatrix}$$

\Rightarrow build in symmetries
 for example $f(-x, y) = f(x, y) = f(x, -y)$
 with $u=0 \text{ } \partial D \leadsto u$ has the same sym.



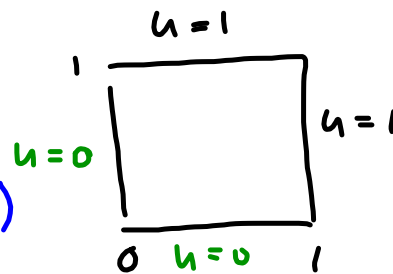
Write $u = \sum_{n=0}^{N-1} \sum_{m=0}^{M-1} a_{nm} T_n(x) T_m(y)$
 solve here has the right symmetries.

2nd example $u_{xx} + u_{yy} = f(x, y)$ with b.c.

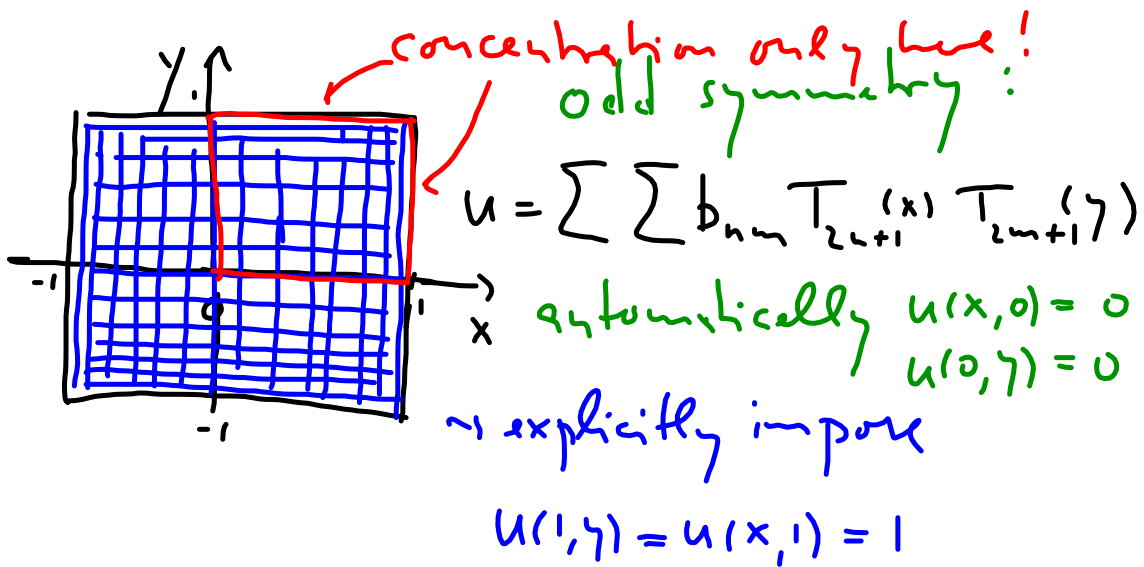
a) expansion

$$u = \sum \sum a_{nm} T_n(2x-1) T_m(2y-1)$$

and impose b.c. directly



b) expand domain and assume symmetries (odd)



§ 6.3 Chebyshev for time-dependent PDEs

→ spectral in space, finite difference in time. Explicit method has very severe time constraints owing to concentration of points! → implicit methods

Nevertheless consider leapfrog } as described in [4], p. 80

$$\frac{u^{n+1} - 2u^n + u^{n-1}}{(\Delta t)^2} = \underline{D}^2 u^n$$

Stability boundary
 $\Delta t = \frac{9.2}{N^2}$ Why?

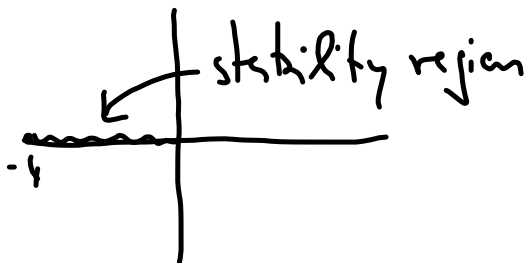
Consider the equation
 $u_{tt} = u_{xx}$
 $x \in [1, 1]$

Consider ODE $u_{tt} = \lambda u$ } general sol.
 $u^n = A z_1^n + B z_2^n$
 substitute $u^n = z^n$

characteristic eqn: $z^2 - [2 + \lambda(\Delta t)^2]z + 1 = 0$

$z_1, z_2 = 1 \quad z + \frac{1}{z} = 2 + \lambda \Delta t^2; \quad z = e^{i\alpha}$

$\alpha = \arccos(1 + \frac{1}{2}\lambda(\Delta t)^2) \sim$ must have
 $-4 < \lambda(\Delta t)^2 < 0$



$\Delta t < \sqrt{\frac{-4}{\lambda}}$

Back to PDE : largest eigenvalue
of $\underline{D}^{(2)}$ is $-0.048 N^4$

became smallest
grid spacing $\sim \frac{1}{N^2}$.

Put together

$$\Delta t < \sqrt{\frac{4}{0.048}} \frac{1}{N^2} \approx \frac{9.2}{N^2}$$

bad, better use
implicit scheme

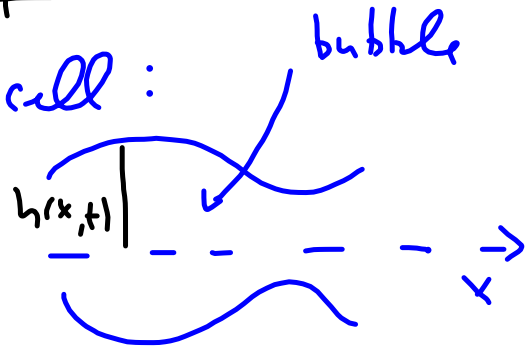
§ A nonlinear equation

Flow in a Hele-Shaw cell :

$$h_t + (h h_{xxx})_x = 0$$

Interested in pinch-off

$h \rightarrow 0$

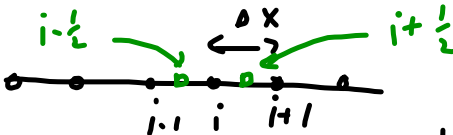


equation changes character:

$$(h h_{xxx})_x = h h_{xxxx} + h_x h_{xxx}$$

\leadsto unconditionally stable!

Finite difference:



$$\frac{h_i^{n+1} - h_i^n}{\Delta t} = \frac{f_{i+\frac{1}{2}}^{n+1} - f_{i-\frac{1}{2}}^{n+1}}{\Delta x}$$

↑
backwards Euler

$$u_i = h_i'' = \frac{h_{i+1} - 2h_i + h_{i-1}}{\Delta x^2}$$

$$f_{i+\frac{1}{2}} = \frac{(u_{i+1} - u_i)(h_{i+1} + h_i)}{2\Delta x}$$

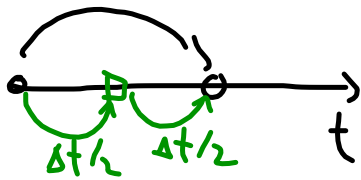
Since the equation changes character, but to solve the nonlinear set of equations. Use Newton's method.

Stability: $\frac{w_{n+1} - w_n}{\Delta t} = \lambda w_{n+1}$

$w_n = A z^n \leadsto z = \frac{1}{1 - \lambda \Delta t}, \bar{\lambda} = \lambda \Delta t$

But only 1st order accurate!

Use Δt Richardson extrapolation



1st order scheme:

$w_{n+1} = w_{n+1}^{\text{exact}} + c \Delta t^2 + O(\Delta t)^3$

two steps: $w_{n+1}^{(2)} = w_{n+1}^{\text{exact}} + 2c \left(\frac{\Delta t}{2}\right)^2 + \dots$

Combine the two:

$$W_{n+1}^{uu} = 2W_{n+1}^{(2)} - W_{n+1} = U_{n+1}^{exact} + O(\Delta t^3)$$

Stability:

2nd order!

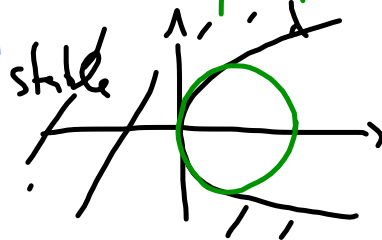
$$z_R = 2z^2\left(\frac{\bar{\lambda}}{2}\right) - z(\bar{\lambda})$$

$$\left| z_R = 2 \left(\frac{1}{1-\bar{\lambda}/2} \right)^2 - \frac{1}{1-\bar{\lambda}} \right|$$

backw. Euler

stability if $|z_R| \leq 1$

unconditionally stable!



▶ In case of stiff equations stability is everything!

▶ Always use step size control, because the typical time scale of a non-linear equation cannot be predicted!

Very simple option: use the difference

$$\Delta_i = (W_{n+1}^{(i)} - W_{n+1})_{(i)}$$

ith gridpoint

and require

- $\Delta_i < 0.01$ for all grid points
- If not reduce time step $\Delta t \rightarrow \frac{\Delta t}{2}$
 - if satisfied (for a while) increase slowly

For the Kule-Slaw problem, $\Delta t = \Delta t 2^{1/6}$ this will cause Δt to decrease by many orders of magnitude as $h \rightarrow 0$.

Also: use spatial refinement as well
 adept, adept, adept ...

