

§ 5.3 Time stepping and Stability region

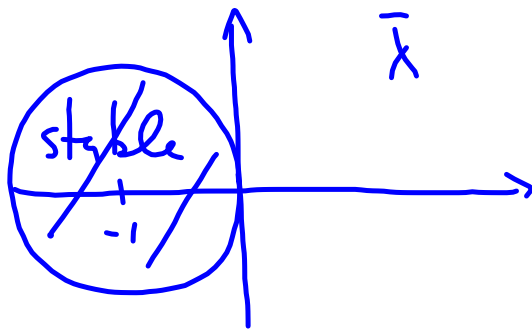
Time-dependent equation: evaluate derivatives spectrally, use finite difference in time: method of lines.

Eigenvalues are $(ik)^P$: sufficient to look at scalar equation

① Euler : $\frac{u^{n+1} - u^n}{\Delta t} = \lambda u^n$ } want $|\lambda|$ large, $\lambda < 0$.

solutions: $u^n = A z^n$, put $\bar{\lambda} = \lambda \Delta t$ so that eqn is stable

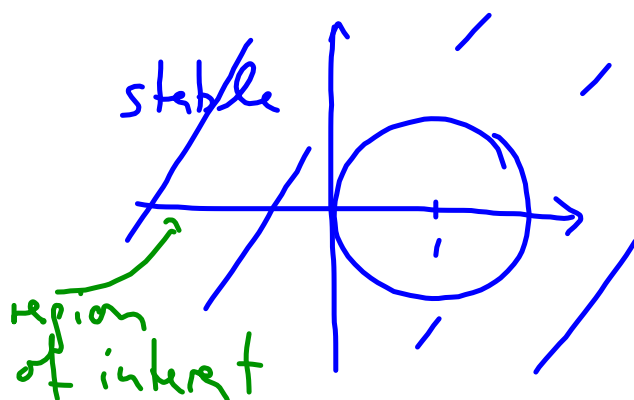
$\leadsto |z = 1 + \bar{\lambda}|$ stability: $|z| \leq 1$



if $\bar{\lambda}$ real
stable for $|\bar{\lambda}| < 2$

② Backwards Euler

$$\frac{u^{n+1} - u^n}{\Delta t} = \lambda u^{n+1} \quad \leadsto \quad z = \frac{1}{1 - \lambda \Delta t}$$



unconditionally
stable!

③ Leap frog $\frac{u^{n+1} - u^{n-1}}{2\Delta t} = \lambda u^n$

$\leadsto |z^2 - 2\bar{\lambda}z - 1 = 0|$ if z sol., then $-\frac{1}{z}$ also solution!

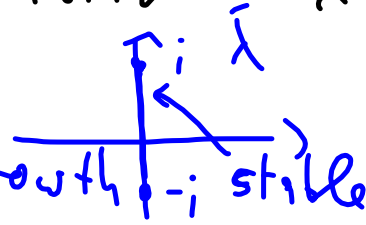
$\Leftrightarrow 1 + \frac{2\bar{\lambda}}{z} - \frac{1}{z^2} = 0$

for stability $|z_1| = |z_2| = 1$ (if $|z_1| < 1$ $\leadsto |z_2| > 1$ unstable)

hence $z = e^{i\lambda}$ $z - \frac{1}{z} = 2i \sin \lambda = 2\bar{\lambda}$

$|\bar{\lambda} = i \sin \lambda|$

exclude $\lambda \neq \pm i$, stability region, secular growth; stable



Consider $u_t + u_x = 0 \rightsquigarrow \underline{u}_t + \underline{D}'' \underline{u} = 0$

eigenvalues of D'' are $ik, -k \leq k \leq k$

Leap frog:

$$[ik, ik] \subset (-i, i)$$

$$\text{or } \Delta t < \frac{1}{k} = \frac{2}{N-1}$$

want are: $k = \pm ik$
eigenmode $e^{\pm ik}$

eigenfunc

$$\underline{u} = \begin{bmatrix} u(x_1) \\ \vdots \\ u(x_N) \end{bmatrix} = \begin{bmatrix} e^{ikx_1} \\ \vdots \\ e^{ikx_N} \end{bmatrix}$$

stability Δt grid spacing

$$e^{\pm ikh} = e^{i(\frac{N-1}{N})\pi} \approx -1$$



sawtooth mode

§ Chebyshev Spectral Methods

▷ Apply in bounded domains
(channel or a pipe)

▷ still have FFT

Basic properties

(a) defined over $[-1, 1]$, $\begin{cases} T_n = \cos n\alpha \\ x = \cos \alpha \\ |T_n(x)| \leq 1 \end{cases}$

(b) boundary values:

$T_0(x) = 1, T_1(x) = x$

$T_2(x) = 2x^2 - 1, T_3(x) = 4x^3 - 3x$

$T_n(1) = 1$

$T_n(-1) = (-1)^n$

(c) orthogonality $\int_{-1}^1 \frac{T_n(x) T_m(x)}{\sqrt{1-x^2}} dx$
 show using $x = \cos \theta$

$$= \begin{cases} 0 & m \neq n \\ \pi & m = n = 0 \\ \pi/2 & m = n \neq 0 \end{cases}$$

(d) $T_{n+1}(x) = 2x T_n(x) - T_{n-1}(x), n \geq 1$

(e) $(1-x^2) \frac{d^2 T_n}{dx^2} - x \frac{dT_n}{dx} + n^2 T_n(x) = 0$
 $n = 0, 1, 2, \dots$

(f) Derivatives (use chain rule)

$$\frac{dT_n}{dx} = \frac{n \sin(n \arccos x)}{\sqrt{1-x^2}}$$

Derivative on the boundary:

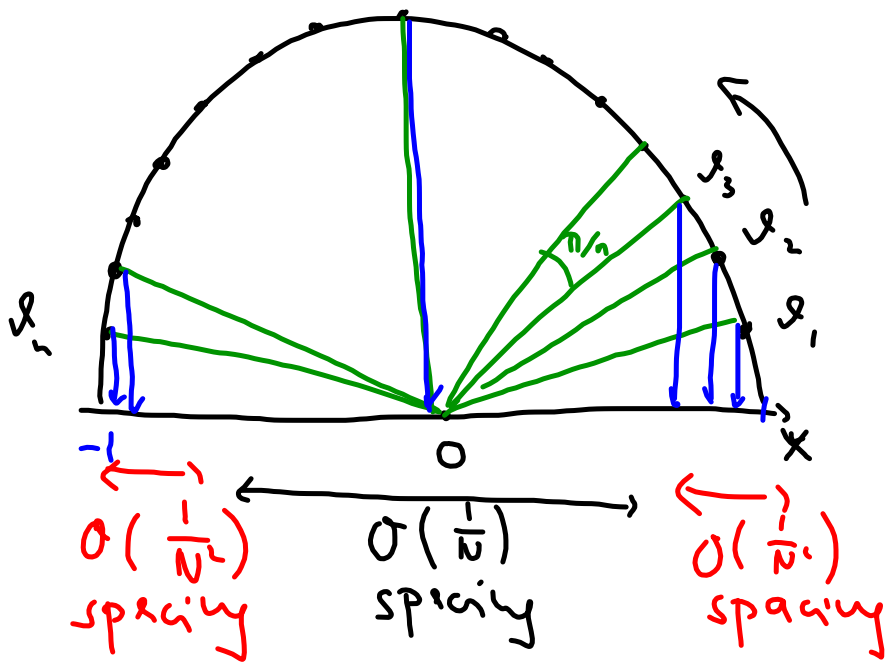
\checkmark Höp. bel's rule $\frac{dT_n}{dx}(1) = n^2$

(3) Zeros of Chebyshev polynomials

$$T_n(x) = 0 \Rightarrow n \cos^{-1} x_j = \frac{\pi}{2} + \pi(j-1), j=1, 2, \dots, n$$

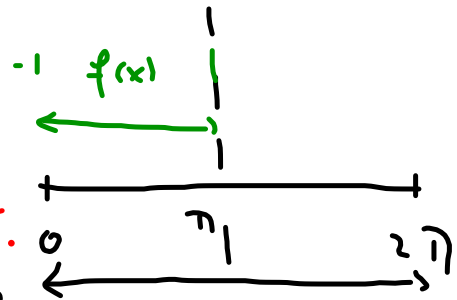
$$\Rightarrow x_j = \cos\left(\frac{\pi(2j-1)}{2n}\right)$$

\checkmark equally spaced around a semicircle
 \downarrow
 \leadsto but FFT!



Interpolating $f(x)$ over $[-1, 1]$ at
 Chebyshev zeroes \equiv interpolating
 $F(x) = f(\cos x)$ using equally spaced
 points over $[0, \pi]$

Since $F(-x) = F(x)$ and
 $F(x \pm 2\pi n) = F(x)$ ^{F is π -per.}
 \leadsto connection to Fourier
 methods \leadsto can we FFT! $F(x) = F(\pi - x)$



§ 6.1 1D Boundary Value Problems

Consider $u_{xx} = e^{4x}$ $x \in [-1, 1]$
 $u(\pm 1) = 0$

As before, 3 different approaches

- Ⓐ work in physical space
 \leadsto Define differentiation matrix $D^{(P)}$
 in real space, modified to include
 boundary conditions. see [4] p. 61
 for discussion.

Ⓑ Work in spectral space

1) Galerkin projection

note: bound. conditions are not automatically satisfied

Tau method:

$$\text{Let } u = \sum_{n=0}^{N-1} a_n T_n(x)$$

→ put b.c. in as constraint

insist that

→ $\tilde{\tau}$ method.

$$0 = \langle T_m(x), u_{xx} - e^{4x} \rangle = \langle T_m(x), \sum_{n=0}^{N-1} a_n T_n''(x) - e^{4x} \rangle$$

where $\langle A, B \rangle = \int_{-1}^1 \frac{A B}{\sqrt{1-x^2}} dx$ for $m = 0, 1, \dots, N-3$

Implement b.c.
total of N equ.

$$\left. \begin{aligned} \sum_{n=0}^{N-1} a_n T_n(1) &= 0 && \text{N-1st equ.} \\ \sum_{n=0}^{N-1} a_n T_n(-1) &= 0 && \text{N'th equ.} \end{aligned} \right\}$$

$$\begin{bmatrix} \langle T_0, T_0 \rangle & \langle T_0, T_1 \rangle & \dots & \langle T_0, T_{N-1} \rangle \\ \langle T_1, T_0 \rangle & \dots & \dots & \dots \\ \vdots & \vdots & \vdots & \vdots \\ \hline T_{0,1} & T_{1,1} & \dots & T_{N-1,1} \\ T_{0,-1} & \dots & \dots & T_{N-1,-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{N-1} \end{bmatrix} =$$

$$\begin{bmatrix} \langle T_0, e^{ix} \rangle \\ \langle T_1, e^{ix} \rangle \\ \vdots \\ \langle T_{N-1}, e^{ix} \rangle \\ 0 \\ 0 \end{bmatrix}$$

upshot: $\underline{A} \underline{a} = \underline{b}$

• can: matrix is dense
• expect exponential convergence for smooth functions

2) Collocation again represent

Now we require that $u = \sum_{n=0}^{N-1} a_n T_n(x)$

$$\sum a_n T_n(1) = 0 \quad j=1$$

$$\sum a_n T_n''(x_j) - e^{4x_j} = 0 \quad \left. \begin{array}{l} j=2, \dots, N-1 \\ x_j = \cos\left[\frac{\pi(2j-1)}{2N}\right] \end{array} \right\}$$

$$\sum a_n T_n(-1) = 0 \quad j=N$$

→ the matrix problem becomes

$$\begin{bmatrix}
 T_0^{(1)} & T_1^{(1)} & \dots & T_{N-1}^{(1)} \\
 \hline
 T_0''(x_1) & \dots & \dots & T_{N-1}''(x_1) \\
 \vdots & & & \vdots \\
 T_0''(x_{N-1}) & \dots & \dots & T_{N-1}''(x_{N-1}) \\
 \hline
 T_0^{(-1)} & T_1^{(-1)} & \dots & T_{N-1}^{(-1)}
 \end{bmatrix}
 \begin{bmatrix}
 a_0 \\
 a_1 \\
 \vdots \\
 a_{N-1}
 \end{bmatrix}
 =
 \begin{bmatrix}
 0 \\
 e^{c_1 x_1} \\
 \vdots \\
 e^{c_{N-1} x_{N-1}} \\
 0
 \end{bmatrix}$$

b.c. (pointing to the top and bottom rows of the matrix)
b.c. (pointing to the top and bottom elements of the vector)

- Very simple to program (+)
- full matrix (-)
- exponential convergence

Another approach: redefine expansion

For example: $\phi_n(x) = T_n(x) - T_{n-2}(x) \quad n \geq 2$

\leadsto so $\phi_n(\pm 1) = 0$ b.c. are satisfied identically!

or (see [3] p 113)

$\phi_{2n} := T_{2n}(x) - 1$ (zero on ± 1)

$\phi_{2n+1} := T_{2n+1}(x) - x$ (")

plus: don't have to worry about b.c.
minus: not clear convergence to exponential

