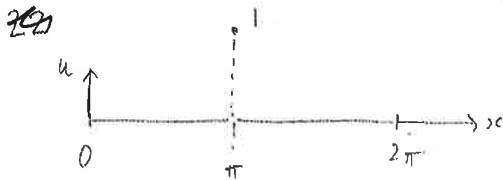


Solution Problem (3)



$$v_t = u_{xx} \quad (*)$$

$$\text{let } u(x,t) = \sum_{k=-K}^K \hat{u}_k^{(t)} e^{ikx}$$

$$v_t = \sum_{k=-K}^K \frac{d\hat{u}_k}{dt} e^{ikx} \quad \& \quad v_{xx} = \sum_{k=-K}^K -k^2 \hat{u}_k e^{ikx}$$

$$\text{So } \frac{d\hat{u}_k}{dt} = -k^2 \hat{u}_k \Rightarrow \hat{u}_k = \hat{u}_k(0) e^{-k^2 t}$$

initial transform $\hat{u}_k(0)$?

$$\text{perform } \hat{u}_k(0) = \frac{1}{N} \sum_{j=1}^N u(x_j) e^{-ikx_j} \quad \text{where } x_j = \frac{2\pi j}{N}$$

$$= \frac{1}{N} e^{-ik\pi} \quad \left(\text{where we have assumed } \exists \text{ a grid pt at } \pi \right)$$

so $u(x_j) = \begin{cases} 1 & \text{at } x_j = \pi \\ 0 & \text{otherwise} \end{cases}$

$$\Rightarrow \hat{u}_k(t) = \frac{1}{N} e^{-ik\pi - k^2 t}$$

$$\therefore u(x_j, t) = \sum_{k=-K}^K \frac{1}{N} e^{-ik\pi - k^2 t + ikx_j}$$

$$= \frac{1}{N} \sum_{k=-K}^K e^{ik(x_j - \pi) - k^2 t} \quad \text{which is } (*)$$

RTS confirm $u(x_j, t) = \frac{1}{N} \sum_{k=-K}^K e^{ik(x_j - \pi) - k^2 t}$ satisfies heat equation.

$$v_t = \frac{1}{N} \sum_{k=-K}^K -k^2 e^{ik(x_j - \pi) - k^2 t} = u_{xx} = \sum_{k=-K}^K (ik)^2 e^{ik(x_j - \pi) - k^2 t} \quad (\text{check})$$

The i.c. has transform $\hat{u}_k(0) = \frac{1}{N} e^{-ik\pi} = O(1) \forall k$ so no drop off.

(as expected since $u(x, 0)$ is not even C^0)

Instead try $u(x, 0) = \cos mx$ (which can be made entire across \mathbb{C} plane)

$$\text{then } \hat{u}_k(0) = \begin{cases} 0 & |k| \neq m \\ \frac{1}{2} & |k| = m \end{cases}$$

so drop off is dramatic!
(\hat{u}_k has compact support)

Solution Problem (4)

We have $u^{(p)}(x_e) =: u_e^{(p)} = D_{eq}^{(p)}(x_e - x_q) u_q$,

where the differentiation operator is

$$D_{eq}^{(p)}(p) = \frac{1}{N} \sum_{k=-K}^K \frac{d^p}{d\varphi^p} e^{ik\varphi} = \frac{1}{N} \frac{d^p}{d\varphi^p} \left(\frac{\sin \frac{N\varphi}{2}}{\sin \varphi/2} \right)$$

Then the spatial discretization is

$$[u u_x]_e = u_e D_{eq}^{(1)} u_q \quad \text{and}$$

$[u_{xx}]_e = D_{eq}^{(2)} u_q$, so that the Crank-Nicolson scheme becomes

$$\left. \begin{aligned} & \frac{u_e^{n+1} - u_e^n}{\Delta t} + \frac{1}{2} \left(u_e^n D_{eq}^{(1)} u_q^n + u_e^{n+1} D_{eq}^{(1)} u_q^{n+1} \right) \\ & = D_{eq}^{(2)} \left(\frac{u_q^{n+1} + u_q^n}{2} \right) \end{aligned} \right|$$

von Neumann analysis :

(4)

$$u_e^n = g^n e^{ikx_e}, \text{ and so}$$

$$u_e^P = (ik)^P g^n e^{ikx_e}, \text{ while}$$

$$u_e^n = \bar{u}, \text{ so that}$$

$$\left| \frac{g-1}{\Delta t} + \bar{u} ik \frac{g+1}{2} = -\frac{g+1}{2} k^2 \right|$$

Then g of the form $g-1 = -\frac{g}{2}(g+1)$,

with $g = \Delta t (k^2 + ik\bar{u})$.

Solving for g : $g = \frac{2-g}{2+g}$; stable

for $|2-g| \leq |2+g|$, satisfied for all $\text{Re}\{g\} \geq 0$. Thus the scheme is unconditionally stable.

(4)

Order of the scheme :

In the time domain, I can write

$$\frac{u^{n+1} - u^n}{\Delta t} = \frac{f^{n+1} + f^n}{2}, \text{ where}$$

$$f^n = -U_e^n D_{eq}^{(1)} U_q^n + D_{eq}^{(2)} U_q^n$$

Now

$$u^{n/n+1} = u^{n+1/2} + \frac{\Delta t}{2} U_t^{n+1/2} + \frac{1}{2} \left(\frac{\Delta t}{2} \right)^2 U_{tt}^{n+1/2} + \dots$$

and the same for $f^{n/n+1}$.

$$\text{Thus } \frac{u^{n+1} - u^n}{\Delta t} = U_t^{n+1/2} + O(\Delta t)^2 \text{ and}$$

$$\frac{f^{n+1} + f^n}{2} = f^{n+1/2} + \left(\frac{\Delta t}{2} \right)^2 f_{tt}^{n+1/2}$$

which means that

$$U_t^{n+1/2} = f^{n+1/2} + O(\Delta t)^2, \text{ i.e. the}$$

scheme is of 2nd order in time.

Solution Problem (5)

24. $u(x) = \cos(mx)$

obviously $u u_x = \cos(mx) [-m \sin(mx)] = -m \cos(mx) \sin(mx) = -\frac{m}{2} \sin(2mx)$

Now attempt convolution approach

$$\begin{aligned}
 (\widehat{u u_x})_k &= \sum_{\substack{q=-k \\ p+q=k}}^k i q \hat{u}_p \hat{u}_q & \text{where } \hat{u}_k &= \begin{cases} \frac{1}{2} & |k|=m \\ 0 & |k| \neq m \end{cases} \quad \left\{ \begin{array}{l} \text{FT of} \\ \cos mx \end{array} \right. \\
 &= \sum_{q=-k}^k i q \hat{u}_q \hat{u}_{k-q} \\
 &= i(-m) \hat{u}_m \hat{u}_{k+m} + i(+m) \hat{u}_m \hat{u}_{k-m} \\
 &= -im \left(\frac{1}{2}\right) \frac{1}{2} \delta_{m|k+m|} + im \left(\frac{1}{2}\right) \frac{1}{2} \delta_{m|k-m|}
 \end{aligned}$$

only non zero k are

$k=0 \quad (\widehat{u u_x})_0 = -im \frac{1}{4} + im \frac{1}{4} = 0$

$k=2m \quad (\widehat{u u_x})_{2m} = \frac{im}{4}$

$k=-2m \quad (\widehat{u u_x})_{-2m} = -\frac{im}{4}$

so $(\widehat{u u_x})_k = \begin{cases} 0 & |k| \neq 2m \\ im/4 & k=2m \\ -im/4 & k=-2m \end{cases}$

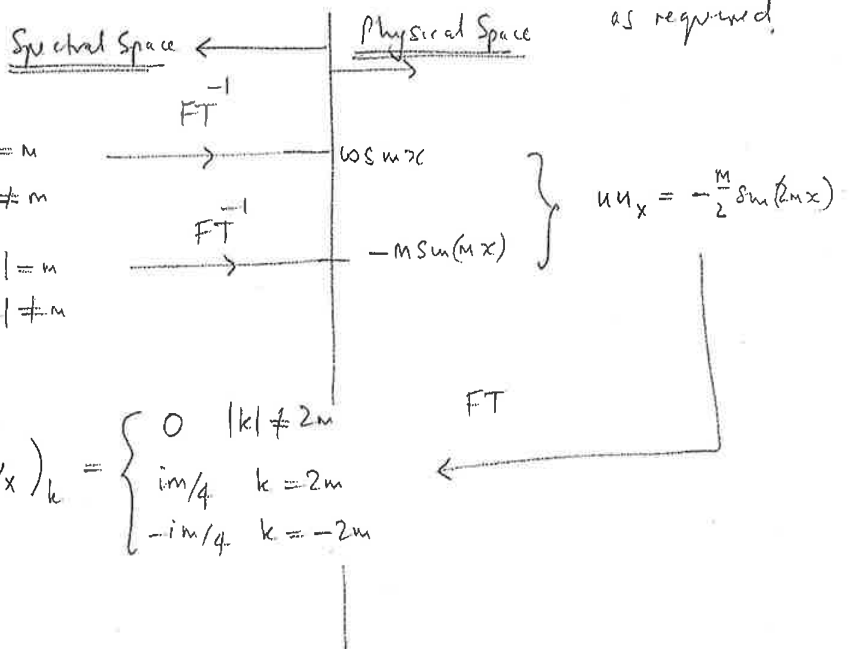
now FT^{-1} to get $\widehat{u u_x} = \frac{im}{4} e^{2imx} - \frac{im}{4} e^{-2imx} = -\frac{m}{2} \sin 2mx$ as required.

In practice

$$\hat{u}_k = \begin{cases} \frac{1}{2} & |k|=m \\ 0 & |k| \neq m \end{cases}$$

$$ik \hat{u}_k = \begin{cases} \frac{1}{2} ik & |k|=m \\ 0 & |k| \neq m \end{cases}$$

$$(\widehat{u u_x})_k = \begin{cases} 0 & |k| \neq 2m \\ im/4 & k=2m \\ -im/4 & k=-2m \end{cases}$$



Solution Problem (6)

We have $F_e^{-1} \{ \hat{u}_k \} = u(x_e) = \sum_{p=-k}^k \hat{u}_p e^{ipx_e}$

and $F_e^{-1} \{ ik \hat{u}_k \} = \sum_{q=-k}^k iq \hat{u}_q e^{iqx_e}$

and so

$$\tilde{\omega}_k = \frac{1}{N} \sum_{\ell=1}^N u u_x(x_e) e^{-ikx_e} =$$

$$\frac{1}{N} \sum_{\ell=1}^N \sum_{p,q=-k}^k \hat{u}_p iq \hat{u}_q e^{i(p+q-k)x_e}$$

Now $\frac{1}{N} \sum_{\ell=1}^N e^{ipx_e} = \sum_{m=-\infty}^{\infty} \delta_{p,mN}$

For $-k \leq k \leq k$, $|p+q-k| \leq 2N = 4k+2$,

and so $p+q-k = \begin{cases} 0 \\ \pm N \end{cases}$.

This means that

$$\left| \tilde{\omega}_k - \hat{\omega}_k = \sum_{\substack{p,q=-k \\ p+q=\pm N+k}}^k \hat{u}_p iq \hat{u}_q \right|$$

(6)

Can write this also in the form

$$\tilde{\omega}_k - \hat{\omega}_k = \sum_{p=-k+k-1}^{-k} \hat{u}_p i^{(-2k+k-1-p)} \hat{u}_{-2k+k-1-p}$$

for $k > 0$ and

$$\tilde{\omega}_k - \hat{\omega}_k = \sum_{p=k+k+1}^k \hat{u}_p i^q u_q, \quad q = 2k+1+k-p$$

for $k < 0$.

In the case $u = \cos mx = \frac{1}{2} (e^{imx} + e^{-imx})$

$$\hat{u}_p = \frac{1}{2} (\delta_{pm} + \delta_{p,-m}), \quad \hat{u}_q = \frac{1}{2} (\delta_{qm} + \delta_{q,-m})$$

and so

$$\left| \tilde{\omega}_k - \hat{\omega}_k = \frac{im}{4} \left[\delta_{k, -2(k-m)-1} + \delta_{k, 1+2(k-m)} \right] \right|$$
