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Sample of results which can be proved using these tools:

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• Rotation number $\rho(f) := \lim_{n \to \infty} \frac{F^n(x) - x}{n}$, (where *F* is lift of *f* and *x* any point in *S*¹)

$[\mathit{Rk}: \ ho(f) \in \mathbb{Q}$ if and only if f has periodic points.]

Theorem (Poincaré)

If f has no periodic points, there exists an (irrational) rotation R_{α} (where $\alpha = \rho(f)$) and a semi-conjugacy h between f and R_{α} (h monotone and surjective).



Theorem (Denjoy)

If in addition $f \in \mathscr{C}^2$ (or \mathscr{C}^1 and f' has bounded variation), then h is a conjugacy.

Theorem (Herman, see also Sinai-Khanin)

If in addition $f \in \mathbb{C}^{2+\nu}$ for some $\nu > 0$ and $\alpha = [a_0, a_1, \ldots]$ satisfies $a_n \leq Cn^{\gamma}$ for some $C, \gamma > 0$ (true for a.e. α) then the conjugacy h is \mathscr{C}^1 .

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A Central Limit Theorem for cocycles over rotations

(based on joint work with Michael Bromberg)



CLT (Central Limit Theorem): central feature in probability theory / hyperbolic dynamical systems; what about entropy zero dynamics?

 $(x,y)\mapsto (R_{\alpha}(x),y+f(x))$ $T^n(0,0)=(R^n_{\alpha}(0),\sum_{k=0}^{n-1}f(R^i_{\alpha}(0)))$

$$(x, y) \mapsto (R_{\alpha}(x), y + f(x))$$

 $T^{n}(0, 0) = (R^{n}_{\alpha}(0), \sum_{k=0}^{n-1} f(R^{i}_{\alpha}(0)))$

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$$R_{lpha}(x) = x + lpha \mod 1$$

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CLT (Central Limit Theorem): central feature in probability theory / hyperbolic dynamical systems; what about entropy zero dynamics?



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Walk on \mathbb{R} driven by R_{α} and f: $T : [0,1] \times \mathbb{R} \rightarrow [0,1] \times \mathbb{R}$ $(x,y) \mapsto (R_{\alpha}(x), y + f(x))$ $T^{n}(0,0) = (R^{n}_{\alpha}(0), \sum_{k=0}^{n-1} f(R^{i}_{\alpha}(0)))$

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Temporal limit theorems:

▶ Beck CLT: $\alpha = \sqrt{2}$ (quadratic irr.), $\beta = \frac{1}{2}$;

$$\frac{X_N - a_N}{b_N} \to \mathscr{N},$$



where \mathcal{N} Gaussian, $a_N = c_1 \log N$, $b_N = c_2 \sqrt{\log N}$

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Theorem (Bromberg-U')

For any lpha bounded type (bnd CF entries), any eta badly approximable wrt lpha and any $0 < x_0 < 1$,

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- Renormalization: we use a classical renormalization algorithm (instead than geometric renormalization), given by an *extension* over the *Gauss map*. This algorithm produces simultaneosuly:
 - the continued fraction entries of $\alpha = [a_1, a_2, \dots, a_n, \dots];$
 - the Ostrowski expansion of β relative to α and its entries $(b_n)_n$;
 - Refs: Arnoux-Fisher, Ito, Bonanno-Isola, ...

Symbolic coding: use the Rohlin towers given by the renormalization algorithm to code the dynamics (Vershik-adic coding); coding leads to a non-homogeneous Markov chain;

CLT for (*non-homogeneous*) Markov chains: proved by Dobrushin (for technical reasons, we use the CLT for φ-mixing arrays of Markov chains by Utev)

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From a rotation on $[-1, \alpha]$ with marked point $-1 < \beta < \alpha$, the algorithm produces a sequence of rotations on $[-1, \alpha_n]$, with marked points β_n :

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Algorithm step n:



- ▶ β_n belongs to b_n th copy, or set $b_n = 0$; β'_n induced marked point;
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For a sequence of nested *inducing intervals* $I^{(n)}$, the induced map on $I^{(n)}$ is a rotation by α_n . We have:

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- For the rotation, there are only two towers (of heigts q_n and q_{n+1}): a large one (L) and a small (S) one.
- Cut them into 3 towers by the position of β_n .
- Call them {L, M, S} for large, middle, small.
- From stage n to n + 1, do cutting and stacking.



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The Ostrowsky renormalization algorithm gives a presentation of R_{α} as a sequence of 3 Rohlin towers over the induced maps.



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For the symbolic coding, use two consecutive renormalization steps.

▶ Label subtowers of step n inside step n + 1Labels (J, j), $J \in \{L, M, S\}$, $0 \le j \le a_n$.



- Coding map Ψ: code a point x ∈ I by Ψ(x) = {(J_n, j_n)}_n if, for any n, x belongs to the subtower labelled by (J_n, j_n) at stage n.
- Fact: Symbolic sequences in $\Psi(I)$ form a Markov chain. Write:
 - transition matrices with entries in function of a_n and b_n;
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S,0)	(M,0)	



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	(M,2)	(L,2)
	(M,1)	(L,1)
5,0)	(M,0)	(L,0)

6



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Inducing and renormalization for rotations

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Sample of results which can be proved using these tools:

- Three gaps theorem (Steinhaus theorem) for rotations; (using towers)
- Denjoy-Koksma inequality for Birkhoff sums over rotations; (using towers)
- Rotation numbers for homeos and diffeos of S¹ (using the renormalization procedure) [Ref: van Strien-de Melo book]
- Poincaré theorem for homeos of S¹ (using the renormalization procedure) [*Ref: van Strien-de Melo book*]
- Herman result on regularity of conjugacy for diffeos of S¹ (using the renormalization procedure) [*Ref: Sinai-Khanin*]
- A limit theorem for Birkhoff sums of non integrable functions (using the partitions)
 [Ref: Sinai-Ulcigrai, '08]
- A generalization of Beck central limit theorem for rotations (using cutting and stacking)
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MFO Oberwolfach Dynamische Systeme

Corinna Ulcigrai

A Central Limit Theorem for cocycles over rotations

(based on joint work with Michael Bromberg)

Oberwolfach, July 10, 2017

