

Advanced Fluid Dynamics

1 (a) $\underline{u} = u(z, t) \hat{x}$ $\rho \frac{\partial u}{\partial t} = \mu \frac{\partial^2 u}{\partial z^2}$ $u(0, t) = U \cos \omega t$
 $u \rightarrow 0$ as $z \rightarrow \infty$

write $u = \text{Re} \{ f(z) e^{i\omega t} \}$

then $f'' - \delta^2 f = 0$ where $\delta^2 = \frac{i\rho\omega}{\mu} \Rightarrow \delta = \left(\frac{\rho\omega}{\mu}\right)^{1/2} e^{i\pi/4}$

Applying the boundary conditions, $f = U \exp(-\delta z)$

Velocity field $u = \text{Re} \left\{ U e^{-\delta z + i\omega t} \right\}$
 $= U e^{-\left(\frac{\rho\omega}{2\mu}\right)^{1/2} z} \cos\left(\omega t - \left(\frac{\rho\omega}{2\mu}\right)^{1/2} z\right)$

Shear stress at boundary $\tau_{xz}(0) = \mu \frac{\partial u}{\partial z}(0)$
 $= \text{Re} \left\{ -\mu \delta U e^{i\omega t} \right\}$

$\Rightarrow \tau_{xz}(0) = -\text{Re} \left\{ \delta \mu U \left(\frac{\rho\omega}{\mu}\right)^{1/2} e^{i(\omega t + \pi/4)} \right\}$

$= -\mu U \lambda \cos(\omega t + \pi/4)$ where $\lambda = \left(\frac{\rho\omega}{\mu}\right)^{1/2}$

(b) Rate of working at boundary $= u(0) \tau_{xz}(0)$

Average rate of working $= \frac{\omega}{2\pi} \int_0^{2\pi/\omega} U \cos \omega t \cdot \mu U \lambda \cos(\omega t + \pi/4) dt$

$\int_0^{2\pi/\omega} \cos \omega t \cos(\omega t + \pi/4) dt = \int_0^{2\pi/\omega} \cos \omega t (\cos \omega t - \sin \omega t) \frac{1}{\sqrt{2}} dt$
 $= \frac{1}{\sqrt{2}} \int_0^{2\pi/\omega} \frac{1}{2} (1 + \cos 2\omega t) - \frac{1}{2} \sin 2\omega t dt$
 $= \frac{1}{\sqrt{2}} \cdot \frac{1}{2} \cdot \frac{2\pi}{\omega}$

Hence Average rate of working $= \frac{1}{2\sqrt{2}} \cdot \mu U^2 \lambda = \frac{1}{2\sqrt{2}} \mu U^2 \left(\frac{\rho\omega}{\mu}\right)^{1/2}$

$= \text{Average rate of dissipation (balance of energy)}$

Standard example: similar to lecture 3

In lectures, evaluated by different method

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(c) Now solve $f'' - \delta^2 f = 0$ subject to $f(0) = u$ and $f(d) = u$

$$f = A \sinh \delta z + B \cosh \delta z$$

$$f(0) = u \Rightarrow B = u, \quad f(d) = u = A \sinh \delta d + B \cosh \delta d \Rightarrow A = \frac{u(1 - \cosh \delta d)}{\sinh \delta d}$$

$$\begin{aligned} \Rightarrow f &= \frac{u \sinh \delta z (1 - \cosh \delta d)}{\sinh \delta d} + u \cosh \delta z \\ &= u \left[\frac{\sinh \delta z}{\sinh \delta d} + \frac{\sinh(\delta(d-z))}{\sinh \delta d} \right] \\ &= \frac{u}{\sinh \delta d} \left(2 \sinh \frac{\delta d}{2} \cosh \left(\delta \left(\frac{d}{2} - z \right) \right) \right) \\ &= u \cdot \frac{\cosh \left[\delta \left(\frac{d}{2} - z \right) \right]}{\cosh \left[\frac{\delta d}{2} \right]} \end{aligned}$$

Here velocity $u = \operatorname{Re} \left\{ u \frac{\cosh \left[\delta \left(\frac{d}{2} - z \right) \right]}{\cosh \left[\frac{\delta d}{2} \right]} e^{i\omega t} \right\}$

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~~Shear stress on $z=0$ is $\tau_{xz} = \operatorname{Re} \left\{ \mu \lambda u \tanh \left(\frac{\delta d}{2} \right) e^{i\omega t} \right\}$~~
 ~~$= \mu \lambda u \operatorname{Re} \left\{ \tanh \left(\frac{\delta d}{2} \right) e^{i(\omega t + \pi/4)} \right\}$~~

Varies on centreline if $\operatorname{Re} \left\{ \frac{u}{\cosh \left[\frac{\delta d}{2} \right]} e^{i\omega t} \right\} = 0$

$$\Rightarrow \operatorname{Re} \left\{ \frac{1}{\cosh \left[\frac{\delta d}{2} \right]} \right\} = 0$$

but $\delta = \lambda \frac{d}{2} \frac{1}{\sqrt{2}} (1+i)$ and $\cosh [M(1+i)] = \cosh M \cos M + i \sinh M \sin M$

3 Hence require $\cos \left(\frac{\lambda d}{2\sqrt{2}} \right) = 0 \Rightarrow \lambda d = 2\sqrt{2} \left(\frac{1}{2} + n\pi \right) \quad n \in \mathbb{Z}$

(d) Shear stress $\tau_{xz} = \operatorname{Re} \left\{ \mu \frac{\partial u}{\partial z} \Big|_{z=0} \right\} = -\mu \lambda u \operatorname{Re} \left\{ \tanh \left(\frac{\delta d}{2} \right) e^{i(\omega t + \pi/4)} \right\}$

When $\lambda d \gg 1$ $\tau_{xz} = -\mu \lambda u \cos(\omega t + \pi/4)$

When $\lambda d \ll 1$ $\tau_{xz} = -\mu \lambda u \operatorname{Re} \left\{ \frac{\lambda d}{2} e^{i(\omega t + \pi/4)} \right\} = -\mu \lambda^2 \frac{d^2}{2} u \cos(\omega t + \pi/4)$

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similar to lecture 5
Method similar to example in lecture, but this is otherwise unen

2. (a) $\underline{u} = \underline{\Gamma} \underline{\hat{x}}$ $\underline{u} = \begin{pmatrix} 0 & 0 & \frac{\Gamma}{2} \\ 0 & 0 & 0 \\ \frac{\Gamma}{2} & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 0 & 0 & \frac{\Gamma}{2} \\ 0 & 0 & 0 \\ -\frac{\Gamma}{2} & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

Note: if $\underline{\Lambda} = (0, -\frac{\Gamma}{2}, 0)$ $\underline{x} \wedge \underline{\Lambda} = (\frac{\Gamma}{2}, 0, -\frac{\Gamma}{2})$

So symmetric tensor $E_{ij} = \begin{pmatrix} 0 & 0 & \frac{\Gamma}{2} \\ 0 & 0 & 0 \\ \frac{\Gamma}{2} & 0 & 0 \end{pmatrix}$ $\underline{\Lambda} = (0, -\frac{\Gamma}{2}, 0)$

[Alternative: $\nabla_i (\underline{x} \wedge \underline{\Lambda})_i = -2 \underline{\Lambda}$ and $\nabla_i (\frac{\Gamma}{2} z, 0, -\frac{\Gamma}{2} x) = (0, \Gamma, 0)$]

(b) $u_i = (\underline{x} \wedge \underline{\Lambda})_i (1 - \frac{a^2}{r^2}) + E_{ij} x_j (1 - \frac{a^5}{r^5}) - \frac{5}{2} x_p E_{pq} x_q (\frac{a^2}{r^5} - \frac{a^5}{r^7}) x_i$

$$\begin{aligned} v_j u_i &= \epsilon_{ijq} \Lambda_q (1 - \frac{a^2}{r^2}) + \frac{3a^2}{r^5} \epsilon_{ipq} x_p \Lambda_q x_j \\ &\quad + E_{ij} (1 - \frac{a^5}{r^5}) + E_{ip} x_p \frac{5a^5}{r^7} x_j \\ &\quad - \frac{5}{2} x_p E_{pq} x_q (\frac{a^2}{r^5} - \frac{a^5}{r^7}) \delta_{ij} + \frac{5}{2} x_i (\frac{a^2}{r^5} - \frac{a^5}{r^7}) (E_{jq} x_q + x_p E_{pj}) \\ &\quad - \frac{5}{2} x_p E_{pq} x_q (-\frac{5a^2}{r^7} + \frac{7a^5}{r^9}) x_i x_j \end{aligned}$$

4 $v_j u_i \Big|_{r=a} = +\frac{3}{a^2} \epsilon_{ipq} x_p \Lambda_q x_j + \frac{5}{a^2} E_{ip} x_p x_j - \frac{5}{a^4} x_p E_{pq} x_q x_i x_j$

stress tensor $\sigma_{ij} = +p \delta_{ij} + \mu (v_i u_j + v_j u_i)$ on $r=a$

$$\begin{aligned} &= +\frac{5\mu}{a^2} x_p E_{pq} x_q \delta_{ij} + \frac{3\mu}{a^2} (\epsilon_{ipq} x_p \Lambda_q x_j + \epsilon_{jip} x_p \Lambda_q x_i) \\ &\quad + \frac{5\mu}{a^2} (E_{ip} x_p x_j + E_{jip} x_p x_i) - \frac{10\mu}{a^4} x_p E_{pq} x_q x_i x_j \end{aligned}$$

shear stress on surface of particle : $\underline{\Lambda} = \frac{1}{a} \underline{x}$ [exerted on particle]

$$\begin{aligned} \sigma_{ij} \Lambda_j &= +\frac{5\mu}{a^3} x_p E_{pq} x_q x_i + \frac{3\mu}{a} \epsilon_{ipq} x_p \Lambda_q \\ &\quad + \frac{5\mu}{a^3} (E_{ip} x_p a^2 + x_j E_{jip} x_j) - \frac{10\mu}{a^5} x_p E_{pq} x_q a^2 x_i \\ &= +\frac{3\mu}{a} (\underline{x} \wedge \underline{\Lambda})_i + \frac{5\mu}{a} E_{ip} x_p \end{aligned}$$

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Unseen, though familiar method

$$(c) \text{ Drag Force } \underline{F} = \int_{r=a} \underline{\tau} ds$$

$$= \int_{r=a} \left(+\frac{3\mu}{a} \epsilon_{ijk} x_j \Lambda_k + \frac{5\mu}{a} E_{ip} x_p \right) ds$$

5 but $\int_{r=a} x_i ds = 0 \Rightarrow \text{Drag Force } \underline{F} = 0$

$$(d) \text{ Torque exerted } \underline{G} = \int_{r=a} \underline{x} \wedge \underline{\tau} ds$$

$$\Rightarrow G_i = \int_{r=a} \epsilon_{ijk} x_j \left(+\frac{3\mu}{a} \epsilon_{kpq} x_p \Lambda_k + \frac{5\mu}{a} E_{kp} x_p \right) ds$$

But $\int_{r=a} x_j x_p ds = \frac{4\pi a^4}{3} \delta_{jp}$ from hint

$$\int \epsilon_{ijk} x_j \frac{5\mu}{a} E_{kp} x_p ds = \frac{4\pi a^4}{3} \frac{5\mu}{a} E_{kp} \epsilon_{ijk} \delta_{jp} = \frac{5\mu}{a} \epsilon_{ijk} E_{kj} \overset{\text{trace}}{=}$$

but $\left. \begin{array}{l} \epsilon_{ijk} \text{ is antisymmetric} \\ E_{ij} \text{ is symmetric} \end{array} \right\} \epsilon_{ijk} E_{kj} = 0$

$$\begin{aligned} \int \epsilon_{ijk} x_j \frac{3\mu}{a} \epsilon_{kpq} x_p \Lambda_k ds &= +\frac{3\mu}{a} \frac{4\pi a^4}{3} \epsilon_{ijk} \delta_{jp} \epsilon_{kpq} \Lambda_k \\ &= +4\pi \mu a^3 \epsilon_{ijk} \epsilon_{kjq} \Lambda_k \end{aligned}$$

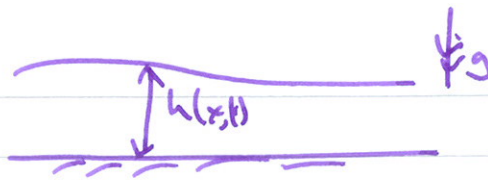
and $\epsilon_{ijk} \epsilon_{kjq} = \epsilon_{kij} \epsilon_{kjq} = 3\delta_{ij}\delta_{jq} - 3\delta_{iq} = -2\delta_{iq}$

$\Rightarrow$ ~~Correct~~ Torque applied $= -8\pi \mu a^3 \Lambda_i$
 G_i

5 $\Rightarrow \underline{G} = 4\pi \mu a^3 (0, \Gamma, 0)$

Unseen, though similar method as worksheet

3 (a) Thin layer



Governing equations: $\frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \rightarrow \frac{u}{L} \sim \frac{w}{H}$

Vertical momentum $\underbrace{\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + w \frac{\partial w}{\partial z}}_{\frac{u^2 H}{L^2}} = -\underbrace{\frac{1}{\rho} \frac{\partial p}{\partial z}}_{\frac{p}{\rho H}} + \underbrace{\nu \frac{\partial^2 w}{\partial z^2}}_{\frac{\nu H u}{L H^2}} + g \quad (2)$

Horizontal momentum $\underbrace{\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + w \frac{\partial u}{\partial z}}_{\frac{u^2}{L}} = -\underbrace{\frac{1}{\rho} \frac{\partial p}{\partial x}}_{\frac{p}{\rho L}} + \underbrace{\nu \frac{\partial^2 u}{\partial z^2}}_{\frac{\nu u}{H^2}} \quad (1)$

Assume $\frac{u^2}{L} \ll \frac{\nu u}{H^2} \Rightarrow \frac{H}{L} \cdot \frac{u H}{\nu} \ll 1$ } in (1)
and $p \sim \rho L \nu u / H^2$

Then in (2). $\frac{u^2 H}{L^2}, \frac{\nu L u}{H^3}, \frac{\nu u}{H L}, g$

Balance $\frac{\nu L u}{H^3} \sim g \Rightarrow p \sim \rho g H$ and leading order dynamics

$$\left. \begin{aligned} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} &= 0 \\ 0 &= -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \frac{\partial^2 u}{\partial z^2} \\ 0 &= -\frac{1}{\rho} \frac{\partial p}{\partial z} + g \end{aligned} \right\}$$

Bookwork

Hence pressure $p = p_{atm} + \rho g(h - z)$

(b) Pressure gradient $\frac{\partial p}{\partial x} = \rho g \frac{\partial h}{\partial x}$

$\Rightarrow \frac{\partial^2 u}{\partial z^2} = \frac{\rho g}{\rho \nu} \frac{\partial h}{\partial x}$ subject to $u(0) = 0$ (no-slip) $\frac{\partial u}{\partial z} = 0$ at $z = h$ (no-shear)

$\Rightarrow u = \frac{\rho g}{3 \nu} \frac{\partial h}{\partial x} \left(\frac{1}{2} z^2 - h z \right)$

Flux $q = \int_0^h u dz = -\frac{\rho h^3}{3 \nu} \frac{\partial h}{\partial x}$

Mass conservation $w(h) + \int_0^h \frac{\partial u}{\partial x} dz = 0$

$$\Rightarrow w(h) + \frac{\partial}{\partial x} \int_0^h u dz - u(h) \frac{dh}{dx} = 0$$

but kinematic condition at $z=h \Rightarrow \frac{dh}{dt} + u \frac{dh}{dx} = w$.

$$\Rightarrow \frac{dh}{dt} + \frac{\partial}{\partial x} \int_0^h u dz = 0$$

$$\Rightarrow \frac{dh}{dt} = \frac{\partial}{\partial x} \left(\frac{gh^2}{3v} \frac{dh}{dx} \right)$$

(c) $h = h_0 + a$ $a/h_0 \ll 1 \Rightarrow \frac{da}{dt} = \frac{gh_0^3}{3v} \frac{\partial^2 a}{\partial x^2}$ 3

(for linearisation)

Try $a = \frac{a_0}{f(x)} \exp\left(-\frac{x^2}{g(t)}\right)$

$$\frac{da}{dt} = -\frac{a_0}{f^2} \frac{df}{dt} \exp\left(-\frac{x^2}{g(t)}\right) + \frac{a_0}{f} \frac{x^2}{g^2} \frac{dg}{dt} \exp\left(-\frac{x^2}{g(t)}\right)$$

$$\frac{da}{dx} = -\frac{2xa_0}{fg} \exp\left(-\frac{x^2}{g}\right)$$

$$\frac{\partial^2 a}{\partial x^2} = -\frac{2a_0}{fg} \exp\left(-\frac{x^2}{g}\right) + \frac{4x^2 a_0}{fg^2} \exp\left(-\frac{x^2}{g}\right)$$

Hence to satisfy $\frac{da}{dt} = \frac{gh_0^3}{3v} \frac{\partial^2 a}{\partial x^2}$ requires

$$-\frac{1}{f^2} \frac{df}{dt} a_0 = -\frac{2a_0}{fg} \cdot \frac{gh_0^3}{3v}$$

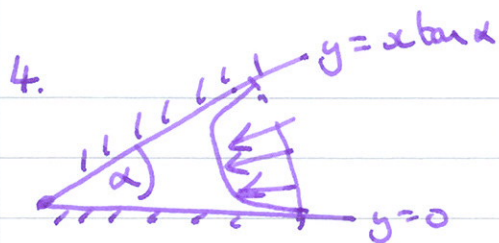
and $\frac{1}{fg^2} \frac{dg}{dt} = \frac{4}{fg^2} \cdot \frac{gh_0^3}{3v}$

Hence $g = \frac{4}{3} \frac{gh_0^3}{v} t + c$ $c = \text{constant}$

and $\frac{1}{f} \frac{df}{dt} = \frac{\frac{2}{3} \frac{gh_0^3}{v}}{\frac{4}{3} \frac{gh_0^3}{v} t + c} \Rightarrow \log f = \frac{1}{2} \log \left| \frac{4}{3} \frac{gh_0^3}{v} t + c \right| + c_1$

$$\Rightarrow a(x,t) = \frac{a_0}{A \left(\frac{4}{3} \frac{gh_0^3}{v} t + c \right)^{1/2}} \exp\left(-\frac{x^2}{\left(\frac{4}{3} \frac{gh_0^3}{v} t + c \right)}\right)$$
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Matching initial condition $\Rightarrow a(x,t) = \frac{a_0}{\left(\frac{4}{3} \frac{gh_0^3}{v} t + 1 \right)^{1/2}} \exp\left(-\frac{x^2}{\left(\frac{4}{3} \frac{gh_0^3}{v} t + 1 \right)}\right)$



Inflow to origin.

(a) Look for solution $\underline{u} = u_r(r) \hat{r}$ and $P = P(r)$

$$\Rightarrow \text{(Mass)} \quad \frac{1}{r} \frac{\partial}{\partial r} (r u_r) = 0$$

$$\text{and (Momentum)} \quad u_r \frac{du_r}{dr} = -\frac{1}{\rho} \frac{dp}{dr} \quad (\text{inviscid})$$

$$\Rightarrow u_r = \frac{K}{r} \quad (K = \text{constant})$$

$$\text{but Value flux } \alpha Q = - \int_0^\alpha r u_r d\theta = -K\alpha \Rightarrow K = -Q$$

$$\text{Pressure} \quad \frac{1}{\rho} \frac{dp}{dr} = - \frac{-Q}{r} \cdot \frac{Q}{r^2} = \frac{Q^2}{r^3}$$

$$\Rightarrow p = p_0 - \rho \frac{Q^2}{2r^2}$$

Similar to lecture

(b) This solution does not satisfy no-slip boundary conditions at $y=0$ and $y=x \tan \alpha \Rightarrow$ need to introduce boundary layers.

$$\text{Reynolds number } Re = \frac{u \cdot L}{\nu} = \frac{Q}{r} \cdot \frac{r}{\nu} = \frac{Q}{\nu}$$

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(c) Boundary layer at $y=0$: $\psi(x,y) \quad u = \frac{\partial \psi}{\partial y} \quad v = -\frac{\partial \psi}{\partial x}$

$$\text{Boundary layer equation} \quad u \frac{du}{dx} + v \frac{du}{dy} = -\frac{1}{\rho} \frac{dp}{dx} + \nu \frac{\partial^2 u}{\partial y^2}$$

$$\Rightarrow \frac{\partial \psi}{\partial y} \cdot \frac{\partial^2 \psi}{\partial x \partial y} - \frac{\partial \psi}{\partial x} \frac{\partial^2 \psi}{\partial y^2} = \frac{Q^2}{x^3} + \nu \frac{\partial^3 \psi}{\partial y^3}$$

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(d) Look for solution of form $\psi = -\sqrt{\nu Q} f\left(\frac{y}{x} \sqrt{\frac{Q}{\nu}}\right)$

$$\frac{\partial \psi}{\partial y} = -\frac{Q}{x} f' \quad \frac{\partial^2 \psi}{\partial y^2} = -Q \sqrt{\frac{Q}{\nu}} \frac{1}{x^2} f'' \quad \frac{\partial^3 \psi}{\partial y^3} = -\frac{Q^2}{\nu} \frac{1}{x^3} f'''$$

Unseen except but b-L in lecture

$$\frac{\partial \psi}{\partial x} = + \sqrt{Q} \cdot \frac{y}{x^2} \sqrt{\frac{Q}{v}} f' = \frac{Qy}{x^2} f'$$

$$\frac{\partial^2 \psi}{\partial x \partial y} = \frac{Q}{x^2} f' + \frac{Qy}{x^2} \sqrt{\frac{Q}{v}} f''$$

Here:
$$-\frac{Q}{x} f' \cdot \left(\frac{Q}{x^2} f' + \frac{Qy}{x^2} \sqrt{\frac{Q}{v}} f'' \right) + \frac{Qy}{x^2} f' \cdot Q \sqrt{\frac{Q}{v}} \frac{1}{x^2} f''$$

$$= -\frac{Q^2}{x^3} + -v \cdot \frac{Q^2}{v} \frac{1}{x^3} f'''$$

$$\Rightarrow -f'^2 = -1 - f'''$$

$$\Rightarrow f''' + f'^2 + 1 = 0 \quad (*)$$

(e) Boundary conditions:

(i) $v=0$ at $y=0 \Rightarrow \frac{\partial \psi}{\partial x} = 0$ automatically satisfied

(ii) $u=0$ at $y=0 \Rightarrow \frac{\partial \psi}{\partial y} = 0 \Rightarrow f'(0) = 0$

(iii) $u = -\frac{Q}{x}$ as $y \rightarrow \infty \Rightarrow \frac{\partial \psi}{\partial y} \rightarrow -\frac{Q}{x} \Rightarrow f' \rightarrow 1$ as $y = \frac{y}{x} \sqrt{\frac{Q}{v}} \rightarrow \infty$

Only need conditions (ii) & (iii) as (*) can be viewed as an ODE for f' .

re. if $g = f'$
$$g'' + g^2 - 1 = 0 \quad g(0) = 0, g \rightarrow 1 \text{ as } y \rightarrow \infty$$

5. Basic state : $\underline{u} = u_0(r) \hat{\underline{\theta}}$, $p = P(r)$ satisfying $-u_0 \frac{\partial}{\partial r} = \frac{1}{\epsilon} \frac{\partial p}{\partial r}$.

(a) Perturbation $\underline{u} = u_0(r) \hat{\underline{\theta}} + \underline{u}'(r, z, t)$ $p = P(r) + p'(r, z, t)$

[Linearized equation] $\frac{\partial \underline{u}'}{\partial t} - \frac{2u_0 u_0'}{r} = -\frac{1}{\epsilon} \frac{\partial p'}{\partial r}$

$$\frac{\partial u_0'}{\partial t} + \frac{u_0' \frac{\partial u_0}{\partial r}}{r} + \frac{u_0'' u_0}{r} = 0$$

$$\frac{\partial u_z'}{\partial t} = -\frac{1}{\epsilon} \frac{\partial p'}{\partial z}$$

$$\frac{1}{r} \frac{\partial}{\partial r}(r u_r') + \frac{\partial u_z'}{\partial z} = 0$$

(b) Now write $\underline{u}' = e^{i(kz + \omega t)} (\hat{u}_r, \hat{u}_\theta, \hat{u}_z)$, $p' = \hat{p} e^{i(kz + \omega t)}$

$$i\omega \hat{u}_r - \frac{2u_0 \hat{u}_\theta}{r} = -\frac{1}{\epsilon} \frac{\partial \hat{p}}{\partial r} \quad \text{--- (1)}$$

$$i\omega \hat{u}_\theta + \hat{u}_r \frac{\partial u_0}{\partial r} + \frac{\hat{u}_r u_0}{r} = 0 \quad \text{--- (2)}$$

$$i\omega \hat{u}_z = -\frac{ik}{\epsilon} \hat{p} \quad \text{--- (3)}$$

$$\frac{1}{r} \frac{\partial}{\partial r}(r \hat{u}_r) + ik \hat{u}_z = 0 \quad \text{--- (4)}$$

From --- (3) and --- (4) $-\frac{ik}{\epsilon} \hat{p} = \frac{i\omega}{-ik} \frac{1}{r} \frac{\partial}{\partial r}(r \hat{u}_r)$

From --- (2) $\hat{u}_\theta = \frac{-1}{i\omega} \frac{1}{r} \hat{u}_r \frac{\partial}{\partial r}(r u_0)$

Into --- (1): $i\omega \hat{u}_r - \frac{2u_0}{r} \cdot \frac{-1}{i\omega} \frac{1}{r} \hat{u}_r \frac{\partial}{\partial r}(r u_0) = \frac{1}{ik} \frac{\partial}{\partial r} \left(\frac{\omega}{-ik} \frac{1}{r} \frac{\partial}{\partial r}(r \hat{u}_r) \right)$

$$\Rightarrow i\omega \hat{u}_r - \frac{i}{\omega} \hat{u}_r \frac{2u_0}{r} \frac{\partial}{\partial r}(r u_0) = \frac{i\omega}{k^2} \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r}(r \hat{u}_r) \right)$$

$$\Rightarrow k^2 \hat{u}_r - \frac{k^2}{\omega^2} \hat{u}_r \frac{\partial}{\partial r}(r^2 u_0^2) = \frac{\partial}{\partial r} \left(\frac{1}{r} \left(r \frac{\partial \hat{u}_r}{\partial r} + \hat{u}_r \right) \right)$$

$$= \frac{\partial^2 \hat{u}_r}{\partial r^2} + \frac{1}{r} \frac{\partial \hat{u}_r}{\partial r} - \frac{\hat{u}_r}{r^2}$$

similar to 20 example in lecture

Under

$$\Rightarrow \left[k^2 + \frac{1}{r^2} - \frac{k^2}{\omega^2 r^3} \frac{d}{dr}(r^2 u_\theta^2) \right] \hat{u}_r = \frac{1}{r} \frac{d}{dr} \left(r \frac{d\hat{u}_r}{dr} \right).$$

$$(c) \int_{R_1}^{R_2} r \hat{u}_r^2 \left[k^2 + \frac{1}{r^2} - \frac{k^2}{\omega^2 r^3} \frac{d}{dr}(r^2 u_\theta^2) \right] dr = \int_{R_1}^{R_2} u_r \frac{d}{dr} \left(r \frac{d\hat{u}_r}{dr} \right) dr$$

$$\text{but } \int_{R_1}^{R_2} u_r \frac{d}{dr} \left(r \frac{d\hat{u}_r}{dr} \right) dr = \left[u_r r \frac{d\hat{u}_r}{dr} \right]_{R_1}^{R_2} - \int_{R_1}^{R_2} r \left(\frac{d\hat{u}_r}{dr} \right)^2 dr$$

$$\text{Hence } \int_{R_1}^{R_2} r \left[\hat{u}_r^2 \left(k^2 + \frac{1}{r^2} \right) + \left(\frac{d\hat{u}_r}{dr} \right)^2 \right] dr = \frac{k^2}{\omega^2} \int_{R_1}^{R_2} \hat{u}_r^2 \frac{1}{r^2} \frac{d}{dr}(r^2 u_\theta^2) dr$$

$$\Rightarrow \omega^2 \int_{R_1}^{R_2} \Phi dr = k^2 \int_{R_1}^{R_2} \frac{\hat{u}_r^2}{r^2} \frac{d}{dr}(r^2 u_\theta^2) dr.$$

$$\text{Note } \Phi \geq 0, \quad k^2 \geq 0, \quad \frac{\hat{u}_r^2}{r^2} \geq 0.$$

Thus ~~$\frac{d}{dr}(r^2 u_\theta^2) < 0$~~ throughout $R_1 < r < R_2$

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~~$\omega^2 < 0$~~ $\Rightarrow$ instability.

if $\omega^2 < 0$ (i.e. linearly unstable)

$$\text{then } \int_{R_1}^{R_2} \frac{\hat{u}_r^2}{r^2} \frac{d}{dr}(r^2 u_\theta^2) dr < 0$$

$$\Rightarrow \frac{d}{dr}(r^2 u_\theta^2) < 0 \text{ for some } r \text{ in } R_1 < r < R_2$$

unseen, but similar to 20 example