

ENTRY AND RETURN TIMES FOR SEMI-FLOWS

JENS MARKLOF

ABSTRACT. Haydn, Lacroix and Vaienti [Ann. Probab. 33 (2005)] proved that, for a given ergodic map, the entry time distribution converges in the small target limit, if and only if the corresponding return time distribution converges. The present note explains how entry and return times can be interpreted in terms of stationary point processes and their Palm distribution. This permits a generalization of the results by Haydn et al. to non-ergodic maps and continuous-time dynamical systems.

1. INTRODUCTION

There is currently much interest in understanding the entry and return time distributions of various classes of dynamical systems, in particular in the case of small target sets; cf. [1, 11, 17, 18, 20, 19, 25, 26, 27, 32, 43] and references therein. These statistics may be viewed as quantitative refinements of the classical Poincaré recurrence, as pointed out by Kac in his study of return times for ergodic maps and discrete stochastic processes [28]. We will here review the relationship between the entry and return time distributions for dynamical systems, and relate them to known facts for stationary point processes and their Palm distribution. This yields in particular an extension of the results by Haydn et al. [23] on the convergence of entry and return time distributions, as well as the processes generated by them [10, 48], to continuous-time dynamical systems with no assumption on ergodicity.

The plan for this paper is as follows. Rather than dealing with discrete-time systems, we consider their suspension semi-flows with general integrable roof functions (Section 2). This gives a natural interpretation of the entry and return times to a given set in terms of a random point process on the positive real line (Section 3). Invariance of the measure under the semi-flow implies stationarity of the process, which can be naturally extended to a stationary point process on the full real line (Section 4). The return times are obtained as the entry times corresponding to the Palm distribution of the original point process. The formula found by Haydn et al. [23] follows from a fundamental identity in Palm distribution theory (Section 5). This identity is a close relative of Santalo's formula for the free path length in billiards and other geometric settings [12, 44, 45], and yields a transparent proof of Kac's formula (Eq. (39) in Section 5) for the mean return time [28, 39, 47]. It also allows us to prove the equivalence of the convergence of entry and return time probabilities for sequences of target sets and dynamical systems, thus extending [23] (see

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also [1, 10, 24, 27, 48]) to non-ergodic maps and semi-flows (Section 6). The general equivalence of convergence-in-distribution of the point processes generated by the entry times and return times, respectively, follows from convergence results for Palm distributions in [29]; see Section 6 for more details.

The connection between Ambrose's representation of flows as suspensions [2, 3] and the Palm distributions of stationary point processes was first pointed out by Papangelou [41] and Hanen [22]; see also [7, 13, 21]. The relationship between entry and return time distributions and their convergence has been exploited in numerous applications. These include the limit distributions for gap statistics of number-theoretic sequences [4, 5, 14, 33, 34, 36, 37, 38], the role of Palm distributions in the statistics of quantum energy levels [40], spectra of quantum graphs [6], gap times in unimolecular reaction rates [15], and the Boltzmann-Grad limit of the periodic Lorentz gas [8, 9, 35].

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2. SUSPENSIONS

Following [2, 3, 31] we may represent any given measurable semi-flow φ^t as the suspension over a suitable map T as follows. Let (Y, \mathcal{A}, μ) be a probability space and $T : Y \rightarrow Y$ a measurable map preserving μ . Fix a function $r \in L^1(Y, \mu)$ such that $\inf r > 0$. Let $X = \{(y, s) \mid y \in Y, 0 \leq s < r(y)\}$, and set

$$(1) \quad S_0(y) = 0, \quad S_n(y) = \sum_{j=0}^{n-1} r(T^j y) \quad (n \geq 1).$$

The *suspension* (also called *special flow* or *flow under a function*) of T with *roof function* r is the semi-flow defined for $t \geq 0$ by

$$(2) \quad \varphi^t : X \rightarrow X, \quad (y, s) \mapsto (T^n y, s + t - S_n(y))$$

if $S_n(y) \leq s + t < S_{n+1}(y)$, $n = 0, 1, 2, \dots$. The corresponding φ^t -invariant probability measure ν on X is given by

$$(3) \quad \int_X f(x) \nu(dx) = \frac{1}{\bar{r}} \int_Y \left(\int_0^{r(y)} f((y, s)) ds \right) \mu(dy)$$

for every measurable $f : X \rightarrow \mathbb{R}_{\geq 0}$, where

$$(4) \quad \bar{r} := \mu r := \int_Y r(y) \mu(dy).$$

In various geometric contexts (such as billiard dynamics or geodesic flows), identities analogous to (3) are often referred to as Santalo's formula [12, 44, 45].

Given $x \in X$, $D \in \mathcal{A}$, we define the sequence of entry/return times $0 < t_1 < t_2 < \dots$ as the elements of the (possibly empty) set

$$(5) \quad H(x, D) = \{t > 0 \mid \varphi^t x \in D \times \{0\}\}.$$

We call $t_j = t_j(x)$ the j th entry time if $x \notin D \times \{0\}$, and the j th return time if $x \in D \times \{0\}$. Note that $t_{j+1} - t_j \geq \inf r$ for all j . We first discuss the entry and

return time distribution for fixed D , then (in Section 6) for a sequence of target sets D_n and, more generally, sequences of suspension semi-flows.

3. POINT PROCESSES

Let $\mathcal{M}(\mathbb{R}_{>0})$ (resp. $\mathcal{M}(\mathbb{R})$) be the space of locally finite Borel measures on $\mathbb{R}_{>0}$ (resp. \mathbb{R}), equipped with the vague topology. We denote by $\mathcal{N}(\mathbb{R}_{>0})$ (resp. $\mathcal{N}(\mathbb{R})$) the closed subset of integer-valued measures, i.e., the set of ζ such that $\zeta B \in \mathbb{Z} \cup \{\infty\}$ for any Borel set B . A *point process* on $\mathbb{R}_{>0}$ (resp. \mathbb{R}) is a random measure in $\mathcal{N}(\mathbb{R}_{>0})$ (resp. $\mathcal{N}(\mathbb{R})$). Given an integer-valued measure ζ , we can write

$$(6) \quad \zeta = \sum_j \delta_{\tau_j(\zeta)}$$

where the τ_j are real-valued functions of ζ . We use the convention that $\tau_j \leq \tau_{j+1}$, and $\tau_0 \leq 0 < \tau_1$ if there are non-positive τ_j . A point process is called *simple* if $\sup_t \zeta\{t\} \leq 1$ a.s.

The push-forward $P_*\nu$ of the invariant measure ν under the measurable map

$$(7) \quad P : X \rightarrow \mathcal{M}(\mathbb{R}_{>0}), \quad x \mapsto \zeta = \sum_{t \in H(x,D)} \delta_t = \sum_j \delta_{t_j(x)},$$

defines a simple point process ζ . This process depends on the choice of $D \in \mathcal{A}$. The j th entry time of the suspension is precisely given by $t_j(x) = \tau_j(\zeta)$, where x is distributed according to ν . We will see in Proposition 3 that the point process $P(y,0)$ given by the return times $t_j(y,0)$, with $y \in D$ distributed according to the probability measure $\mu(D)^{-1}\mu$, has the same distribution as a point process η given by the Palm distribution of ζ .

4. STATIONARITY

For $u \in \mathbb{R}_{\geq 0}$, define the shift operator θ^u on $\mathcal{M}(\mathbb{R}_{>0})$ by $\theta^u \zeta B = \zeta(B+u)$ for every Borel set $B \subset \mathbb{R}_{>0}$. If $\zeta \in \mathcal{N}(\mathbb{R}_{>0})$, we have

$$(8) \quad \zeta = \sum_{j=1}^{\infty} \delta_{\tau_j(\zeta)}, \quad \theta^u \zeta = \sum_{j=j_0}^{\infty} \delta_{\tau_j(\zeta)-u}$$

where $j_0 = \min\{j \mid \tau_j - u > 0\}$. We say a random measure $\zeta \in \mathcal{M}(\mathbb{R}_{>0})$ is *stationary* if $\theta^u \zeta \stackrel{d}{=} \zeta$ for all $u \in \mathbb{R}_{\geq 0}$. Similarly, for $u \in \mathbb{R}$, define the shift operator θ^u on $\mathcal{M}(\mathbb{R})$ by $\theta^u \zeta B = \zeta(B+u)$ for every Borel set $B \subset \mathbb{R}$. We say a random measure ζ in $\mathcal{M}(\mathbb{R})$ is *stationary* if $\theta^u \zeta \stackrel{d}{=} \zeta$ for all $u \in \mathbb{R}$. If ζ_0 in $\mathcal{M}(\mathbb{R}_{>0})$ is a stationary random measure, then (with ζ_0 now viewed as an element in $\mathcal{M}(\mathbb{R})$) the limit $\theta^u \zeta_0 \xrightarrow{d} \zeta$ ($u \rightarrow \infty$) exists in $\mathcal{M}(\mathbb{R})$ and defines a stationary random measure, whose restriction to $\mathcal{M}(\mathbb{R}_{>0})$ has the same distribution as ζ_0 . We call ζ the *stationary extension* of ζ_0 to \mathbb{R} .

The intensity measure of a stationary random measure ζ is $I_\zeta \text{Leb}$, where the intensity is given by

$$(9) \quad I_\zeta = \frac{\mathbb{E}\zeta(0, R]}{R},$$

which, by stationarity, is independent of the choice of $R > 0$.

Proposition 1. *The simple point process $\xi = P(x)$, with $x \in X$ distributed according to ν , is stationary on $\mathbb{R}_{>0}$ with intensity $I_\xi = \bar{r}^{-1}\mu(D)$.*

Proof. Since ν is φ^u -invariant, we have for any $u \geq 0$

$$(10) \quad \xi = \sum_{t \in H(x, D)} \delta_t \stackrel{d}{=} \sum_{t \in H(\varphi^u x, D)} \delta_t = \theta^u \xi,$$

where the last relation follows from

$$(11) \quad H(\varphi^u x, D) = \{t > 0 \mid \varphi^{t+u} x \in D \times \{0\}\}$$

$$(12) \quad = \{t > u \mid \varphi^t x \in D \times \{0\}\} - u$$

$$(13) \quad = (H(x, D) - u) \cap \mathbb{R}_{>0}.$$

This shows that ξ is stationary on $\mathbb{R}_{>0}$. Its intensity is

$$(14) \quad I_\xi = \mathbb{E} \frac{\#\{j \mid 0 < \tau_j(\xi) \leq R\}}{R} = \int_X \frac{\#\{j \mid 0 < t_j(x) \leq R\}}{R} \nu(dx).$$

Now, for any $\epsilon \in (0, \inf r)$,

$$(15) \quad \#\{j \mid 0 < t_j(x) \leq R\} = \frac{1}{\epsilon} \int_0^R \mathbb{1}(\varphi^t(x) \in D \times [0, \epsilon]) dt + E_R(x)$$

where $|E_R(x)| \leq 1$. Since φ^t preserves ν , we have

$$(16) \quad \int_X \mathbb{1}(\varphi^t(x) \in D \times [0, \epsilon]) \nu(dx) = \nu(\varphi^{-t}(D \times [0, \epsilon]))$$

$$(17) \quad = \nu(D \times [0, \epsilon]) = \epsilon \bar{r}^{-1} \mu(D).$$

We conclude $I_\xi = \bar{r}^{-1} \mu(D) + O(R^{-1})$ for any $R > 0$. Taking $R \rightarrow \infty$ proves that $I_\xi = \bar{r}^{-1} \mu(D)$. \square

Note that a random measure and its stationary extension have the same intensity, so in particular if ξ is the stationary extension of $P(x)$ to \mathbb{R} , then $I_\xi = \bar{r}^{-1} \mu(D)$. Let

$$(18) \quad Z_D^1 = \{y \in Y \mid T^j y \in D \text{ for some } j \in \mathbb{N}\} = \bigcup_{j=1}^{\infty} T^{-j} D$$

be the set of points in Y whose forward orbit intersects D .

Proposition 2. *Let ξ be the stationary extension of $P(x)$ to \mathbb{R} , with $x \in X$ distributed according to ν . Then*

$$(19) \quad \mathbb{P}(\xi \neq 0) = \mu(Z_D^1).$$

Proof. We have $\xi \neq 0$ if and only if $x \in \{(y, s) \mid y \in Z_D^1, 0 \leq s < r(y)\}$, and the claim follows. \square

Let

$$(20) \quad Z_D^\infty = \{y \in Y \mid T^j y \in D \text{ for infinitely many } j \in \mathbb{N}\} = \bigcap_{k=1}^{\infty} \bigcup_{j=k}^{\infty} T^{-j} D$$

be the set of points in Y whose forward orbit intersects D infinitely often. Now $\mathbb{P}(\xi[0, \infty) = \infty) = \mu(Z_D^\infty)$ if and only if $x \in \{(y, s) \mid y \in Z_D^\infty, 0 \leq s < r(y)\}$. The zero-infinity law for stationary random measures on \mathbb{R} [30, Lemma 11.1] gives

$$(21) \quad \mathbb{P}(\xi \neq 0) = \mathbb{P}(\xi[0, \infty) = \infty) = \mu(Z_D^\infty).$$

By Proposition 2, this shows that $\mu(Z_D^1) = \mu(Z_D^\infty)$, which is a formulation of the Poincaré recurrence theorem. Note that Z_D^∞ is T -invariant. Thus, if T is ergodic, then $\mu(Z_D^\infty) \in \{0, 1\}$ and $\mu(Z_D^\infty) = 1$ if and only if $\mu(D) > 0$.

An example of a non-ergodic map, to which the above proposition applies, is

$$(22) \quad T : \mathbb{R}^2 / \mathbb{Z}^2 \rightarrow \mathbb{R}^2 / \mathbb{Z}^2, \quad (x_1, x_2) \mapsto (x_1 + x_2, x_2),$$

where μ is the Haar probability measure of $\mathbb{R}^2 / \mathbb{Z}^2$. T is evidently not ergodic; for instance $D = \mathbb{R}/\mathbb{Z} \times D_2$ is T -invariant for any measurable $D_2 \subset \mathbb{R}/\mathbb{Z}$ and $\mu(D) = \text{Leb } D_2$ can take any value in $[0, 1]$. On the other hand $\mu(Z_D^1) = 1$, if for instance $D = D_1 \times \mathbb{R}/\mathbb{Z}$, for any measurable $D_1 \subset \mathbb{R}/\mathbb{Z}$ with $\text{Leb } D_1 > 0$. The entry and return times of this map (and its higher-dimensional analogues) play a central role in the periodic Lorentz gas [8, 9, 35].

5. PALM DISTRIBUTIONS

The Palm distribution Q_ξ of a stationary random measure ξ on \mathbb{R} with finite and positive intensity is defined by the relation [30, Chapter 11]

$$(23) \quad Q_\xi f = \frac{1}{I_\xi \text{Leb } B} \mathbb{E} \int_B f(\theta^u \xi) \xi(du),$$

for any measurable $f : \mathcal{M}(\mathbb{R}) \rightarrow \mathbb{R}_{\geq 0}$, where $B \subset \mathbb{R}$ is a given Borel set with $\text{Leb } B > 0$. It follows from the stationarity of ξ that this definition is in fact independent of the choice of B . Let η be a random measure distributed according to the Palm distribution Q_ξ , i.e., $\mathbb{E}f(\eta) = Q_\xi f$. If ξ is a point process, we can write $\xi = \sum_j \delta_{\tau_j(\xi)}$, and so

$$(24) \quad \mathbb{E}f(\eta) = \frac{1}{I_\xi \text{Leb } B} \mathbb{E} \sum_j \mathbb{1}(\tau_j(\xi) \in B) f\left(\sum_i \delta_{\tau_i(\xi) - \tau_j(\xi)}\right).$$

This shows that η is a point process and furthermore that, if ξ is a simple point process, then η is a simple point process, too, and $\eta\{0\} = 1$ a.s. The stationarity of ξ implies that η is *cycle-stationary*, i.e. η has the same distribution as the point process $\theta^{\tau_j(\eta)} \eta = \sum_i \delta_{\tau_i(\eta) - \tau_j(\eta)}$ for any j .

A basic example is when ξ is a Poisson process with constant intensity I_ξ . In this case $\eta \stackrel{d}{=} \delta_0 + \xi$. This relation is in fact unique to the Poisson process (Slivnyak's theorem): If ξ is a stationary process on \mathbb{R} and $\delta_0 + \xi$ is distributed according to Q_ξ , then ξ is a homogeneous Poisson process.

If ξ is the stationary extension of $P(x)$ to \mathbb{R} with P as in (7), then (24) shows that any point process η with distribution Q_ξ is supported on the return times. We in fact have the following relation with the return time process $P(y, 0)$, where y is uniformly distributed on D .

Proposition 3. *Let ξ be the stationary extension of $P(x)$ to \mathbb{R} , with $x \in X$ distributed according to ν , and η a point process distributed according to the Palm distribution Q_ξ . Then, for every measurable $f : \mathcal{N}(\mathbb{R}) \rightarrow \mathbb{R}_{\geq 0}$ supported on $\mathcal{N}(\mathbb{R}_{>0})$,*

$$(25) \quad \mathbb{E}f(\eta) = \frac{1}{\mu(D)} \int_D f(P(y, 0)) \mu(dy).$$

Proof. For any $\epsilon \in (0, \inf r]$, we have $\xi(-\epsilon, 0] \leq 1$ and so (24) simplifies to

$$(26) \quad \mathbb{E}f(\eta) = \frac{1}{I_\xi \epsilon} \mathbb{E} \mathbb{1}(-\epsilon < \tau_0(\xi) \leq 0) f\left(\sum_i \delta_{\tau_i(\xi) - \tau_0(\xi)}\right).$$

In geometric terms, $-\epsilon < \tau_0(\xi) \leq 0$ restricts the expectation to orbits that have just hit the section D within the time interval $[0, \epsilon)$. Since, by assumption, f is supported on $\mathcal{N}(\mathbb{R}_{>0})$, (26) becomes

$$(27) \quad \mathbb{E}f(\eta) = \frac{1}{\bar{r} I_\xi \epsilon} \int_D \left(\int_0^{r(y)} \mathbb{1}(0 \leq -t_0(y, s) < \epsilon) f\left(\sum_i \delta_{t_i(y, s) - t_0(y, s)}\right) ds \right) \mu(dy).$$

For $s < \epsilon \leq \inf r$, we have $t_j(y, s) + s = t_j(y, 0)$ (in particular $t_0(y, s) = -s$), and so

$$(28) \quad \sum_i \delta_{t_i(y, s) - t_0(y, s)} = \sum_i \delta_{t_i(y, 0)} = P(y, 0).$$

Hence

$$(29) \quad \mathbb{E}f(\eta) = \frac{1}{\bar{r} I_\xi \epsilon} \int_D \left(\int_0^{r(y)} \mathbb{1}(0 \leq s < \epsilon) f(P(y, 0)) ds \right) \mu(dy)$$

$$(30) \quad = \frac{1}{\bar{r} I_\xi} \int_D f(P(y, 0)) \mu(dy),$$

and (25) follows from $\bar{r} I_\xi = \mu(D)$; recall Proposition 1. \square

The following inversion formula is a fundamental result of Palm distribution theory [30, Proposition 11.3 (iii)].

Proposition 4. *Assume ξ is a simple, stationary point process on \mathbb{R} with positive finite intensity. Let η be a point process given by the Palm distribution Q_ξ . Then $\mathbb{P}(\xi \in \cdot \mid \xi \neq 0)$ is uniquely determined by η , and, for any measurable $f : \mathcal{N}(\mathbb{R}) \rightarrow \mathbb{R}_{\geq 0}$,*

$$(31) \quad \mathbb{E}[f(\xi) \mathbb{1}(\xi \neq 0)] = I_\xi \mathbb{E} \int_0^{\tau_1(\eta)} f(\theta^u \eta) du.$$

We reproduce the elegant proof of Proposition 4 from [30, p. 205].

Proof. In view of (23),

$$(32) \quad I_\xi \text{Leb}(B) \mathbb{E}f(\eta) = \mathbb{E} \int_B f(\theta^u \xi) \xi(du)$$

for any Borel set B and measurable $f : \mathcal{N}(\mathbb{R}) \rightarrow \mathbb{R}_{\geq 0}$. By a monotone class argument (take finite linear combinations of functions of the form $g(\xi, u) = f(\xi) \chi_B(u)$ where χ_B is the indicator function of B), (32) extends to

$$(33) \quad I_\xi \mathbb{E} \int_{\mathbb{R}} g(\eta, u) du = \mathbb{E} \int_{\mathbb{R}} g(\theta^u \xi, u) \xi(du)$$

for every measurable $g : \mathcal{N}(\mathbb{R}) \times \mathbb{R} \rightarrow \mathbb{R}_{\geq 0}$. Using the function $g(\zeta, u) = h(\theta^{-u}\zeta, u)$ with measurable $h : \mathcal{N}(\mathbb{R}) \rightarrow \mathbb{R}_{\geq 0}$, and substituting u by $-u$ in the first integral, yields

$$(34) \quad I_{\xi} \mathbb{E} \int_{\mathbb{R}} h(\theta^u \eta, -u) du = \mathbb{E} \int_{\mathbb{R}} h(\xi, u) \xi(du).$$

Apply this formula with

$$(35) \quad h(\zeta, u) = f(\zeta) \mathbb{1}(\tau_0(\zeta) = u),$$

and note that $\tau_0(\theta^u \eta) = -u$ if and only if $u \in [0, \tau_1(\eta))$. This proves (31). To show uniqueness of the conditional probability, note that in view of (31) for any measurable set A , and f its indicator function,

$$(36) \quad \text{Prob}(\xi \in A \mid \xi \neq 0) = \frac{\mathbb{E}[f(\xi) \mathbb{1}(\xi \neq 0)]}{\mathbb{E} \mathbb{1}(\xi \neq 0)} = \frac{\mathbb{E} \int_0^{\tau_1(\eta)} f(\theta^u \eta) du}{\mathbb{E} \tau_1(\eta)}.$$

Here

$$(37) \quad \mathbb{E} \mathbb{1}(\xi \neq 0) = I_{\xi} \mathbb{E} \tau_1(\eta)$$

follows from (31) for $f \equiv 1$. □

Note that (37) can be written as

$$(38) \quad \mathbb{E} \tau_1(\eta) = \frac{\mathbb{P}(\xi \neq 0)}{I_{\xi}} = \bar{r} \frac{\mu(Z_D^1)}{\mu(D)}.$$

This yields in view of (18) and (25) with $f(\eta) = \tau_1(\eta)$, the following identity for the mean return time for the semiflow φ^t :

$$(39) \quad \int_D t_1(y, 0) \mu(dy) = \bar{r} \mu \left(\bigcup_{j=1}^{\infty} T^{-j} D \right).$$

Eq. (39) generalizes Kac's formula [28] to semi-flows, without any assumption on ergodicity. It is well known in billiard dynamics [12] and other transport problems [15, 42]; see also also [46]. As already pointed out by Wright [47] (cf. also [39, 42]), the ergodicity assumed by Kac is not required, if we restrict Y to the set of points Z_D^1 whose forward trajectories intersect D . An elementary example of a non-ergodic ξ and its Palm distribution is discussed in Appendix A.

Applying (31) with the choice $f(\zeta) = \mathbb{1}(\tau_1(\zeta) > R)$ and (37) yields

$$(40) \quad \mathbb{P}(\tau_1(\xi) > R \mid \xi \neq 0) = \frac{1}{\mathbb{E} \tau_1(\eta)} \mathbb{E} \int_0^{\tau_1(\eta)} \mathbb{1}(\tau_1(\eta) - u > R) du$$

$$(41) \quad = \frac{1}{\mathbb{E} \tau_1(\eta)} \mathbb{E} \int_0^{\infty} \mathbb{1}(\tau_1(\eta) > R + u) du,$$

and so

$$(42) \quad \mathbb{P}(\tau_1(\xi) > R \mid \xi \neq 0) = \frac{1}{\mathbb{E} \tau_1(\eta)} \int_R^{\infty} \mathbb{P}(\tau_1(\eta) > u) du.$$

Eq. (40) says that on $\xi \neq 0$ the random variable $\tau_1(\xi)$ has the same distribution as $\tau_1(\eta) - u$, where u is uniformly distributed in the available gap $[0, \tau_1(\eta))$ with

intensity $1/\mathbb{E}\tau_1(\eta)$. Eq. (42) generalizes the formula found by Haydn et al. [23] for ergodic maps, and is well known in the literature in various other contexts, e.g. in the theory of renewal processes [16, Chapter XI.4]. Identities of this type are known as *Palm-Khinchin equations*. Further instances are obtained from (31) by choosing the test function $f(\zeta) = \mathbb{1}(\tau_j(\zeta) > R)$, which yields

$$(43) \quad \mathbb{P}(\tau_j(\zeta) > R \mid \zeta \neq 0) = \frac{1}{\mathbb{E}\tau_1(\eta)} \mathbb{E} \int_0^{\tau_1(\eta)} \mathbb{1}(\tau_j(\eta) - u > R) du$$

$$(44) \quad = \frac{1}{\mathbb{E}\tau_1(\eta)} \mathbb{E} \int_0^{\tau_j(\eta)} \mathbb{1}(\tau_j(\eta) - u > R) du$$

$$(45) \quad - \frac{1}{\mathbb{E}\tau_1(\eta)} \mathbb{E} \int_{\tau_1(\eta)}^{\tau_j(\eta)} \mathbb{1}(\tau_j(\eta) - u > R) du.$$

The first integral (44) is analogous to (41). For the second integral (45),

$$(46) \quad \mathbb{E} \int_{\tau_1(\eta)}^{\tau_j(\eta)} \mathbb{1}(\tau_j(\eta) - u > R) du = \mathbb{E} \int_0^{\tau_j(\eta) - \tau_1(\eta)} \mathbb{1}(\tau_j(\eta) - \tau_1(\eta) - u > R) du$$

$$(47) \quad = \mathbb{E} \int_0^{\tau_{j-1}(\eta)} \mathbb{1}(\tau_{j-1}(\eta) - u > R) du,$$

by cycle-stationarity of the Palm distribution. In conclusion,

$$(48) \quad \mathbb{P}(\tau_j(\zeta) > R \mid \zeta \neq 0) = \frac{1}{\mathbb{E}\tau_1(\eta)} \int_R^\infty [\mathbb{P}(\tau_j(\eta) > u) - \mathbb{P}(\tau_{j-1}(\eta) > u)] du.$$

This in particular generalizes the identities for ergodic maps in [10] to (not necessarily ergodic) semi-flows. An analogous relation holds for the number of hits in a given time interval [24].

6. CONVERGENCE

We now consider the entry and return time statistics for a sequence of probability spaces $(Y_n, \mathcal{A}_n, \mu_n)$, a sequence of measurable maps $T_n : Y_n \rightarrow Y_n$ preserving μ_n , target sets $D_n \in \mathcal{A}_n$ and roof functions $r_n \in L^1(Y_n, \mu_n)$ with $\inf r_n > 0$ for every n . We rescale the entry times by the intensity, i.e., define the sequence of entry times $0 < t_{1,n} < t_{2,n} < \dots$ as the elements of the set $H_n(x, D_n) = \bar{r}_n^{-1} \mu_n(D_n) H(x, D_n)$, and put

$$(49) \quad P_n : X \rightarrow \mathcal{N}(\mathbb{R}_{>0}), \quad x \mapsto \sum_{t \in H_n(x, D_n)} \delta_t.$$

One example to keep in mind is when $(Y_n, \mathcal{A}_n, \mu_n) = (Y, \mathcal{A}, \mu)$ and $T_n = T$ are fixed, and one considers a sequence of targets $D_n \in \mathcal{A}$ with $\mu(D_n) \rightarrow 0$. A further possibility is to fix D and consider a sequence of invariant measures $\mu_n \in \mathcal{A}$. The latter setting is for instance relevant for the gap statistics of Farey fractions via the horocycle flow: Take ν_n to be the invariant measure supported on a closed horocycle of length $\ell_n \rightarrow \infty$, and μ_n the measure supported on periodic points of the return map T for a certain section (the Boca-Cobeli-Zaharescu map) [5]. The equidistribution of long closed horocycles implies the weak convergence $\nu_n \xrightarrow{w} \nu$

and $\mu_n \xrightarrow{w} \mu$, which in turn implies $\xi_n \xrightarrow{d} \xi$ in this setting; see [4] for more examples of this type and [34] for the higher-dimensional analogue.

For x random with respect to ν_n and ν_n defined by (3) with respect to μ_n , denote by ξ_n be the stationary extension of $P_n(x)$. In the present scaling $I_{\xi_n} = 1$ and $\mathbb{E}\tau_1(\eta_n) = \mathbb{P}(\xi_n \neq 0)$, where η_n is distributed according to Q_{ξ_n} . The following well known fact deals with slightly more general point processes with not necessarily constant, but still uniformly bounded, intensity.

Proposition 5. *Let (ξ_n) be a sequence of stationary point processes with $\sup_n I_{\xi_n} < \infty$. Then (ξ_n) is relatively compact in distribution.*

Proof. By [30, Lemma 16.15], we need to show that the sequence of random variables $(\xi_n B)$ is tight in $\mathbb{R}_{\geq 0}$ for any relatively compact Borel set $B \subset \mathbb{R}$. By Markov's inequality, for any $K > 0$,

$$(50) \quad \mathbb{P}(\xi_n B \geq K) \leq \frac{1}{K} \mathbb{E} \xi_n B = \frac{1}{K} I_{\xi_n} \text{Leb } B.$$

Therefore

$$(51) \quad \limsup_{K \rightarrow \infty} \left(\sup_n \mathbb{P}(\xi_n B \geq K) \right) = 0$$

and hence $(\xi_n B)$ is tight. \square

Relative compactness means that any subsequence of (ξ_n) contains a converging subsequence. Let ξ be a limit point of a converging subsequence, i.e., $\xi_n \xrightarrow{d} \xi$ along some subsequence. The limit will again be a stationary, but not necessarily simple, point process.

The following proposition shows that the convergence of entry times is equivalent to the convergence of return times. It is a direct consequence of Eq. (42), and generalizes the results of [23] (see also [1, 27]). Again we consider more general processes, not necessarily those with unit intensity.

Proposition 6. *Let (ξ_n) be a sequence of stationary point processes on \mathbb{R} with $0 < I_{\xi_n} < \infty$, and η_n a point process given by the Palm distribution of ξ_n such that $\sup_n \mathbb{E}\tau_1(\eta_n) < \infty$. Let ρ be a Borel probability measure on $\mathbb{R}_{\geq 0}$ and $F(R) = \rho(\mathbb{R}_{>R})$. Then the following are equivalent.*

- (i) $\mathbb{E}\tau_1(\eta_n) \mathbb{P}(\tau_1(\xi_n) \leq R \mid \xi_n \neq 0) \rightarrow \int_0^R F(u) du$ for every $R \geq 0$;
- (ii) $\mathbb{E}g(\tau_1(\eta_n)) \rightarrow \int_0^\infty g(u) \rho(du)$ for every bounded continuous $g : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$.

A simple example illustrating this statement is given in Appendix B.

Proof. By (42),

$$(52) \quad \mathbb{E}\tau_1(\eta_n) \mathbb{P}(\tau_1(\xi_n) \leq R \mid \xi_n \neq 0) = \int_0^R \mathbb{P}(\tau_1(\eta_n) > u) du$$

$$(53) \quad = \mathbb{E} \int_0^R \mathbb{1}(\tau_1(\eta_n) > u) du$$

$$(54) \quad = \mathbb{E}g(\tau_1(\eta_n)),$$

with $g(u) = \min(u, R)$, which is bounded continuous on $\mathbb{R}_{\geq 0}$ with $g(0) = 0$. So (ii) implies

$$(55) \quad \mathbb{E}\tau_1(\eta_n) \mathbb{P}(\tau_1(\xi_n) \leq R \mid \xi \neq 0) \rightarrow \int_0^\infty g(u)\rho(du)$$

$$(56) \quad = \int_0^R u\rho(du) + RF(R)$$

$$(57) \quad = \int_0^R F(u)du,$$

where the last equality follows from integration by parts. This proves (i).

Now assume (i) holds. Since, by Markov's inequality and (38), for any $K > 0$

$$(58) \quad \mathbb{P}(\tau_1(\eta_n) \geq K) \leq \frac{1}{K}\mathbb{E}\tau_1(\eta_n),$$

where $\mathbb{E}\tau_1(\eta_n)$ has by assumption a uniform upper bound, the sequence $(\tau_1(\eta_n))$ is tight and hence relatively compact. This means that every subsequence contains a convergent subsequence, whose weak limit is a Borel probability measure ρ_0 , i.e., for any bounded continuous $g : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$,

$$(59) \quad \mathbb{E}g(\tau_1(\eta_n)) \rightarrow \int_0^\infty g(u)\rho_0(du).$$

But the already established implication (ii) \Rightarrow (i) then yields for $g(u) = \min(u, R)$ and all $R \geq 0$

$$(60) \quad \mathbb{E}\tau_1(\eta_n) \mathbb{P}(\tau_1(\xi_n) \leq R) \rightarrow \int_0^\infty g(u)\rho_0(du) = \int_0^R F_0(u)du$$

with $F_0(R) = \rho_0(\mathbb{R}_{>R})$. This implies by assumption (i)

$$(61) \quad \int_0^R F_0(u)du = \int_0^R F(u)du.$$

This yields $F_0 = F$ (since F_0, F are right-continuous), and hence $\rho_0 = \rho$ (since ρ_0, ρ are Borel probability measures on $\mathbb{R}_{\geq 0}$). Thus the weak limit $\rho_0 = \rho$ is unique, which in turn implies that every subsequence converges. This proves (ii). \square

The following theorem complements Proposition 6 by providing a criterion for the equivalence of convergence for general stationary processes and their Palm distributions. This is a special case of Theorem 6.1 in [29] for general point processes (see the remark after Theorem 6.3).

Proposition 7. *Let (ξ_n) be a sequence of stationary point processes on \mathbb{R} with $0 < I_{\xi_n} < \infty$, and η_n a point process given by the Palm distribution of ξ_n . Then any two of the following statements imply the third:*

- (i) $I_{\xi_n} \rightarrow I_{\xi}$;
- (ii) $\xi_n \xrightarrow{d} \xi$;
- (iii) $\eta_n \xrightarrow{d} \eta$, where η has distribution Q_{ξ} .

Applied to the processes generated by the entry and return times via (49), Proposition 7 yields a generalization of Theorem 3.1 in [48] to (not necessarily ergodic) continuous-time dynamical systems.

We conclude this section with an interpretation of the limit relations in Proposition 6 in terms of the limit point processes ζ , η in Proposition 7. Let ζ^* , η^* be the simple point processes obtained by removing from ζ , η all multiplicities. ζ^* is again stationary and the intensities satisfy $I_{\zeta} = m_{\zeta} I_{\zeta^*}$, where $m_{\zeta} \geq 1$ is called the mean multiplicity of ζ . Furthermore, η^* is given by the Palm distribution Q_{ζ^*} . Note that, by definition, $\tau_0(\zeta) = \tau_0(\zeta^*)$ and $\tau_1(\zeta) = \tau_1(\zeta^*)$ for any $\zeta \in \mathcal{N}(\mathbb{R})$. Thus (42) applied to ζ^* yields

$$(62) \quad \mathbb{P}(\tau_1(\zeta) > R \mid \zeta \neq 0) = \frac{1}{m_{\zeta} \mathbb{E} \tau_1(\eta)} \int_R^{\infty} \mathbb{P}(\tau_1(\eta) > u) du.$$

Comparing this formula with the limit distributions in Proposition 6, we have

$$(63) \quad \mathbb{E} \tau_1(\eta) \mathbb{P}(\tau_1(\zeta) \leq R \mid \zeta \neq 0) = \int_0^R F(u) du$$

and

$$(64) \quad \mathbb{P}(\tau_1(\eta) > R) = \tilde{\rho}(\mathbb{R}_{>R}) = m_{\zeta} \rho(\mathbb{R}_{>R}) = m_{\zeta} F(R),$$

with the Borel probability measure $\tilde{\rho}$ defined by

$$(65) \quad \rho = \frac{m_{\zeta} - 1}{m_{\zeta}} \delta_0 + \frac{1}{m_{\zeta}} \tilde{\rho}.$$

The point here is that ρ in Proposition 6 registers return times of the sequence of point processes that accumulate at zero, whereas $\tilde{\rho}$, as the return time distribution of the limit point process, ignores the corresponding zero return times.

APPENDIX A. CASE STUDY OF AN ELEMENTARY NON-ERGODIC SUSPENSION

Fix $q_1 \in [0, 1]$, $q_0 = 1 - q_1$, $\ell_0, \ell_1 \in \mathbb{R}_{>0}$. Let $Y = \{0, 1\}$ be the set of two elements, with the probability measure μ defined by $\mu\{i\} = q_i$, and T be the identity map on Y . The suspension φ^t on X is defined with roof function $r(i) = \ell_i$. Thus X is the union of two disjoint circles of length ℓ_0 and ℓ_1 , and φ^t is the translation by t on each circle. Each circle yields one ergodic component. The φ^t -invariant measure ν on X as in (3) has normalization $\bar{r} = q_0 \ell_0 + q_1 \ell_1$.

If the target set is for example $D = \{1\}$, then the entry times are $t_j = \ell_1 j - u_1$ with probability

$$(66) \quad p_1 = \nu(\{1\} \times [0, \ell_1)) = \frac{q_1 \ell_1}{q_0 \ell_0 + q_1 \ell_1},$$

and u_1 distributed according to the uniform probability measure on $[0, \ell_1)$, and undefined with probability $p_0 = 1 - p_1$. The point process ζ of the entry times, extended to a stationary process on \mathbb{R} , is thus

$$(67) \quad \zeta = \alpha \sum_{m \in \mathbb{Z}} \delta_{\ell_1 m + s_1},$$

where $\alpha = 1$ with probability p_1 , $\alpha = 0$ with probability $p_0 = 1 - p_1$, and $s_1 \in [0, \ell_1]$ is a uniformly distributed random variable on $[0, \ell_1]$. The point process ξ has intensity

$$(68) \quad I_\xi = \mathbb{E}\xi[0, 1] = \frac{p_1}{\ell_1} = \frac{q_1}{q_0\ell_0 + q_1\ell_1} = \bar{r}^{-1}\mu(\{1\}),$$

as predicted by Proposition 1.

The Palm distribution (23) of ξ is given by

$$(69) \quad Q_\xi f = \frac{1}{I_\xi \text{Leb } B} \frac{p_1}{\ell_1} \int_0^{\ell_1} \int_B \sum_{m \in \mathbb{Z}} f\left(\sum_{n \in \mathbb{Z}} \delta_{\ell_1 n + s - u}\right) \delta_{m\ell_1 + s}(du) ds$$

$$(70) \quad = \frac{1}{\text{Leb } B} \int_{\mathbb{R}} \int_B f\left(\sum_{n \in \mathbb{Z}} \delta_{\ell_1 n + s - u}\right) \delta_s(du) ds$$

$$(71) \quad = f\left(\sum_{n \in \mathbb{Z}} \delta_{\ell_1 n}\right).$$

Thus Q_ξ is a point mass, and a random measure η with distribution Q_ξ satisfies

$$(72) \quad \eta = \sum_{n \in \mathbb{Z}} \delta_{\ell_1 n} \quad \text{a.s.}$$

The first hitting time of η is $\tau_1(\eta) = \ell_1$ a.s., and so $\mathbb{E}\tau_1(\eta) = \ell_1 = p_1 I_\xi^{-1}$, which confirms (38).

If the target set is $D = Y$, then the entry times are $t_j = \ell_1 j - u_1$ with probability p_1 as in (66), and $t_j = \ell_0 j - u_0$ with probability $p_0 = 1 - p_1$. The random variables u_0, u_1 are independent and uniformly distributed on $[0, \ell_0)$ and $[0, \ell_1)$, respectively. The point process ξ of the entry times, extended to a stationary process on \mathbb{R} , is now

$$(73) \quad \xi = \alpha \sum_{m \in \mathbb{Z}} \delta_{\ell_1 m + s_1} + (1 - \alpha) \sum_{m \in \mathbb{Z}} \delta_{\ell_0 m + s_0}$$

where $\alpha = 1$ with probability p_1 , $\alpha = 0$ with probability $p_0 = 1 - p_1$, and $s_0 \in [0, \ell_0]$, $s_1 \in [0, \ell_1]$ are uniformly distributed, independent random variables.

We have $\mathbb{P}(\xi \neq 0) = 1$, and ξ is a stationary, simple point process with intensity

$$(74) \quad I_\xi = \mathbb{E}\xi[0, 1] = \frac{p_0}{\ell_0} + \frac{p_1}{\ell_1} = \frac{1}{q_0\ell_0 + q_1\ell_1} = \bar{r}^{-1} > 0.$$

By the same calculation as in (69), the Palm distribution (23) of ξ is now

$$(75) \quad Q_\xi f = \frac{1}{I_\xi} \sum_{i=0,1} \frac{p_i}{\ell_i} f\left(\sum_{n \in \mathbb{Z}} \delta_{\ell_i n}\right).$$

A random measure η with distribution Q_ξ can be therefore realized by the simple point process

$$(76) \quad \eta = \sum_{n \in \mathbb{Z}} \delta_{\ell_n}$$

with

$$(77) \quad \mathbb{E}f(\eta) = \frac{1}{I_{\xi}} \mathbb{E} \left[\frac{1}{\ell} f \left(\sum_{n \in \mathbb{Z}} \delta_{\ell n} \right) \right],$$

where the random variable ℓ takes the value ℓ_i with probability p_i . The first hitting time of η is $\tau_1(\eta) \stackrel{d}{=} \ell$, and so $\mathbb{E}\tau_1(\eta) = I_{\xi}^{-1}$, which is precisely (38).

APPENDIX B. AN ILLUSTRATIVE EXAMPLE FOR PROPOSITIONS 6 AND 7

Consider the sequence of stationary, simple point processes

$$(78) \quad \xi_n = \sum_{m \in \mathbb{Z}} \sum_{k=-n}^n \delta_{(2n+1)(m+s)+a_n k},$$

where (a_n) is any sequence with $0 < a_n < 1$ and $\lim a_n = 0$, and the random variable s is uniformly distributed in \mathbb{R}/\mathbb{Z} . Note that $I_{\xi_n} = 1$. The Palm distribution (23) of ξ_n is given by

$$(79) \quad Q_{\xi_n} f = \frac{1}{2n+1} \sum_{l=-n}^n f \left(\sum_{m \in \mathbb{Z}} \sum_{k=-n}^n \delta_{(2n+1)m+a_n(k-l)} \right),$$

and hence we may choose

$$(80) \quad \eta_n = \sum_{m \in \mathbb{Z}} \sum_{k=-n}^n \delta_{(2n+1)m+a_n(k-l)},$$

where l is a uniformly distributed random integer in $[-n, n]$. Hence

$$(81) \quad \begin{cases} \mathbb{P}(\tau_1(\eta_n) = a_n) & = \frac{2n}{2n+1} \\ \mathbb{P}(\tau_1(\eta_n) = 2n+1-2na_n) & = \frac{1}{2n+1} \\ \mathbb{P}(\tau_1(\eta_n) \notin \{a_n, 2n+1-2na_n\}) & = 0. \end{cases}$$

This shows that

$$(82) \quad \mathbb{P}(\tau_1(\xi_n) \leq R) \rightarrow 0, \quad \mathbb{E}\tau_1(\eta_n) = 1, \quad \mathbb{P}(\tau_1(\eta_n) > R) \rightarrow 0,$$

for each fixed $R > 0$, and thus $F = 0$ and $\rho = \delta_0$, which is consistent with Proposition 6.

This example does not, however, satisfy the hypotheses of Proposition 7. We have $\xi_n \xrightarrow{\text{a.s.}} 0$, and hence $I_{\xi} = 0$. On the other hand $I_{\xi_n} = 1$, so hypothesis (i) in Proposition 7 fails, whilst (ii) holds. Let us show that (iii) fails. Since $\eta_n[-1, 1] \geq \min(\lfloor a_n^{-1} \rfloor, n)$ for every realization of η_n , the sequence (η_n) accumulates infinite mass in $[-1, 1]$, and hence does not converge in distribution to a random measure in $\mathcal{M}(\mathbb{R})$.

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JENS MARKLOF, SCHOOL OF MATHEMATICS, UNIVERSITY OF BRISTOL, BRISTOL BS8 1TW, U.K.
 j.marklof@bristol.ac.uk