

How do we sample from the posterior?

- In general, we want samples from the joint posterior distribution
- *Independent* sampling from $p(\theta|\mathbf{y})$ may be difficult
- **BUT** sampling from a *Markov chain* with $p(\theta|\mathbf{y})$ as its stationary (equilibrium) distribution turns out to be easier
- A sequence of random variables $\theta^{(0)}, \theta^{(1)}, \theta^{(2)}, \dots$ forms a Markov chain if

$$P(\theta^{(t+1)} | \theta^{(t)}, \theta^{(t-1)}, \dots) = P(\theta^{(t+1)} | \theta^{(t)})$$

- *i.e.* conditional on the value of $\theta^{(t)}$, $\theta^{(t+1)}$ is independent of $\theta^{(t-1)}, \dots, \theta^{(0)}$
- given the $\theta^{(t)}$, the $\theta^{(t+1)}$ is independent of the $\theta^{(0)}, \dots, \theta^{(t-1)}$

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- There are general theorems that show that $\frac{1}{N} \sum_{t=1}^N g(\theta^{(t)}) \rightarrow \int g(\theta) p(\theta|\mathbf{y}) d\theta$ as $N \rightarrow \infty$ when $\theta^{(1)}, \dots, \theta^{(N)}$ are sampled from a suitable Markov chain
- Unlike with ordinary Monte Carlo, in the Markov chain case there will be $\frac{1}{N} \sum_{t=1}^N g(\theta^{(t)}) \rightarrow \int g(\theta) p(\theta|\mathbf{y}) d\theta$ as well as $\frac{1}{N} \sum_{t=1}^N g(\theta^{(t)}) \rightarrow \int g(\theta) p(\theta|\mathbf{y}) d\theta$ in the empirical mean – both $\rightarrow 0$ as $N \rightarrow \infty$

To summarise, the point of MCMC:

Bayesian posterior inference may be achieved – via Monte Carlo integration – using simulated values of all the unknown quantities in the model, generated from a Markov chain with $p(\theta|\mathbf{y})$ as its stationary distribution

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5. MCMC recipes: How do we design a Markov chain with $p(\theta|y)$ as its unique stationary distribution?

- Note that we are **not** the usual Applied Probability problem (given a Markov chain transition matrix, find the stationary distribution): here we are **given** the stationary distribution and want to **construct** a Markov chain that it corresponds to.
- It is surprisingly easy and several standard ‘recipes’ are available.
- These methods were discovered during World War II as part of the work leading to the atomic bomb: the original published method was by Metropolis *et al.* (1953), a team that worked at Los Alamos.
- The method was generalized by **Geman and Geman** (1970), and an important special case called **Hamiltonian Monte Carlo** was introduced in 1984.
- There has since been an explosion of use of these methods – they make Bayesian methods practical on a **large** (not miniature) scale.

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Terminology

- While we are discussing the general theory, we will let the vector θ denote all the **parameters** and y all the **data**. We will sometimes abbreviate
- $\pi(\theta)$ is the **target distribution** of our Markov chain – that is, the chain is designed to have $\pi(\theta)$ as its **stationary distribution** (or equilibrium or invariant) distribution
- We sometimes call a Markov chain used in this way a **Markov Chain Monte Carlo (MCMC)**
- The Markov chain will have typical states θ – usually not a countable state space (as in AP2), usually a **continuous** space.
- However, in proofs, we will use discrete (countable) notation

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