

Dependent Double Branching Annihilating Random Walk

Joint with
Attila László Nagy

Márton Balázs

University of Bristol

Oberseminar Stochastics
Bonn, 9th July, 2015.

Attractive and non-attractive models

Totally asymmetric simple exclusion process

A \oplus \ominus 0 model

Totally asymmetric zero range process

On large scales

Shocks

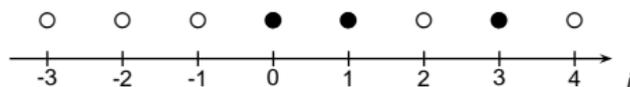
Rarefaction waves

A mean field version

Positive recurrence

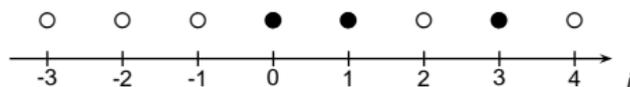
Two words on the proof

The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

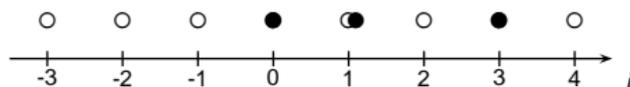
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

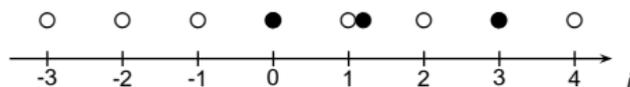
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

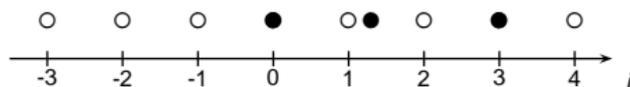
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

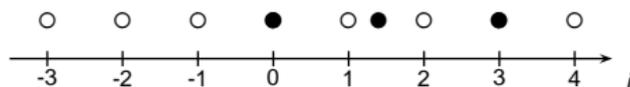
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

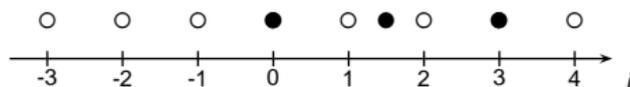
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

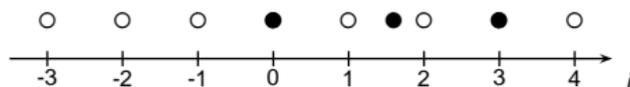
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

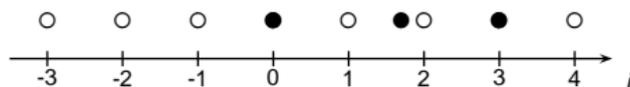
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

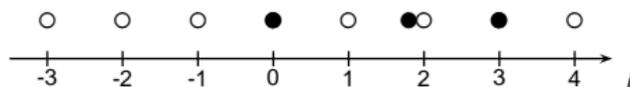
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

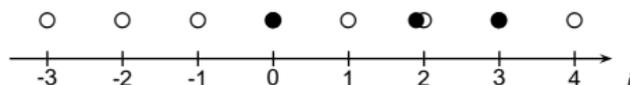
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

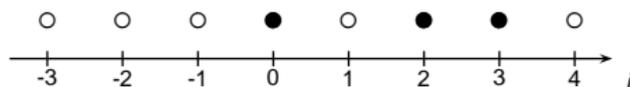
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

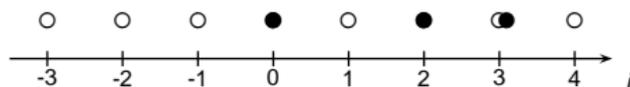
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

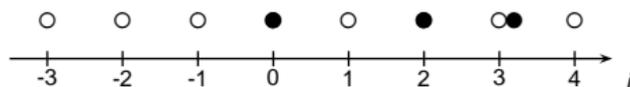
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

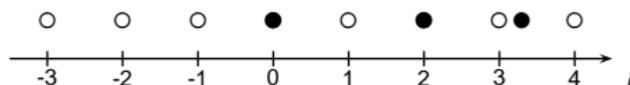
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

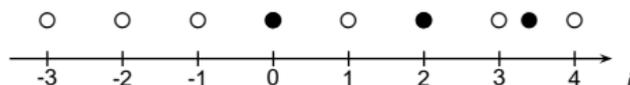
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

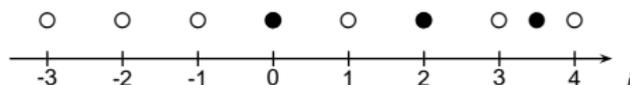
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

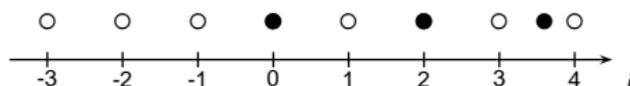
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

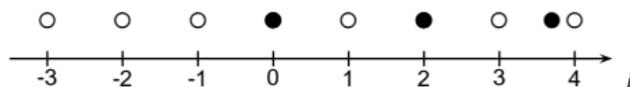
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

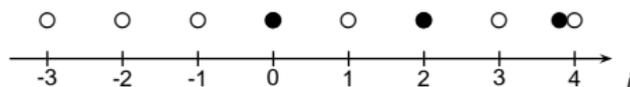
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

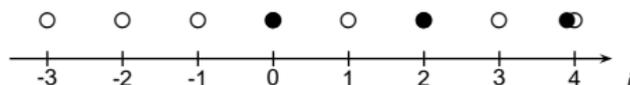
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

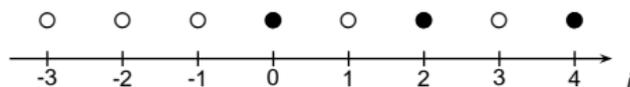
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

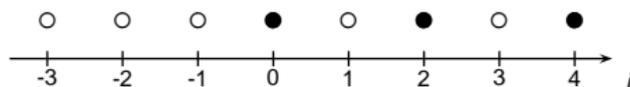
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

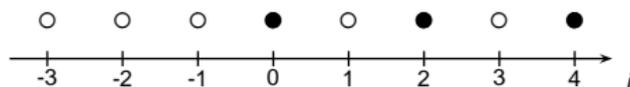
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

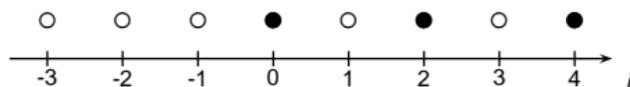
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

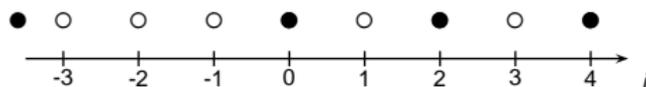
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

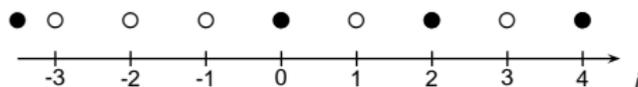
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

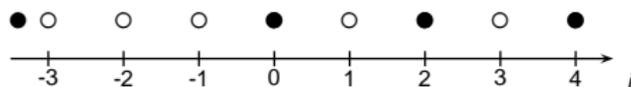
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

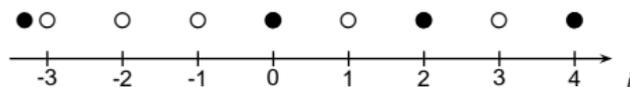
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

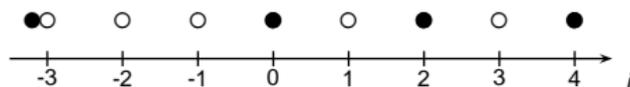
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

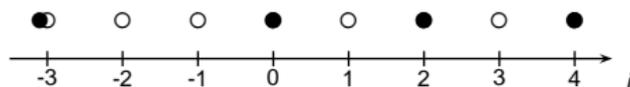
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

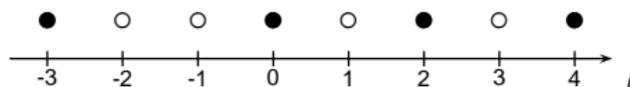
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

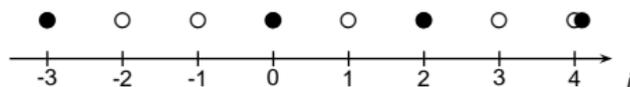
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

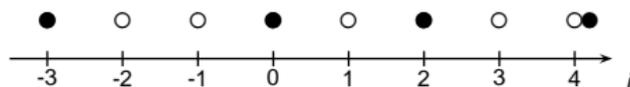
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

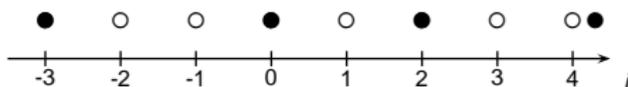
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

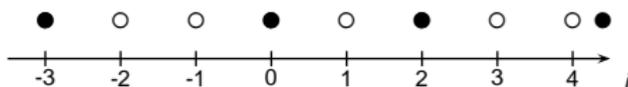
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

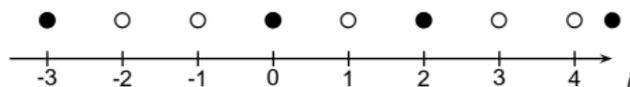
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

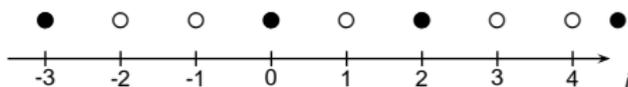
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\rho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

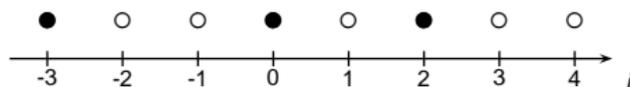
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

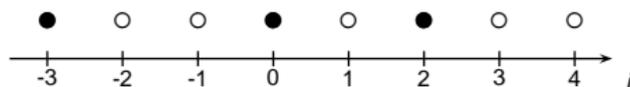
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

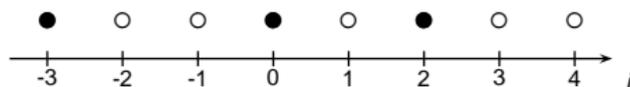
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

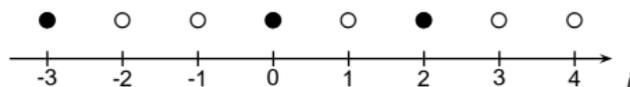
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

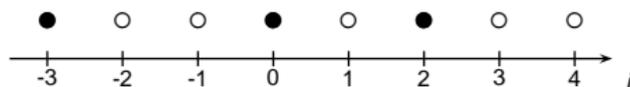
The totally asymmetric simple exclusion process



$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

The totally asymmetric simple exclusion process



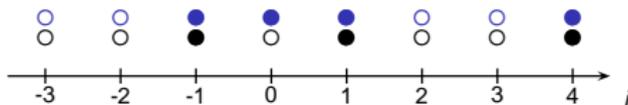
$\omega_i(0) \sim \text{Bernoulli}(\varrho)$ product distribution.

Particles step to the right with **rate 1**,
unless the destination site is occupied.

The $\text{Bernoulli}(\varrho)$ product distribution is stationary (**and non-reversible**) for all $0 \leq \varrho \leq 1$: $\omega_i(t) \sim \text{Bernoulli}(\varrho)$.

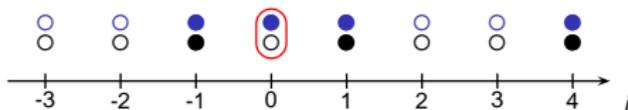
These are the important (= ergodic) stationary distributions.

The second class particle



Stochastic coupling: evolution as close as possible

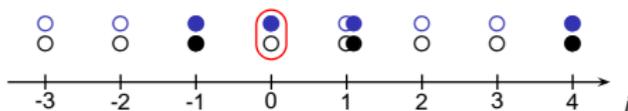
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

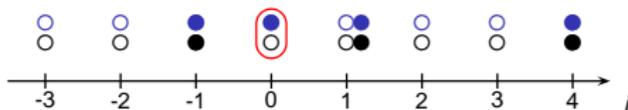
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

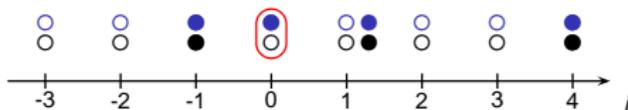
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

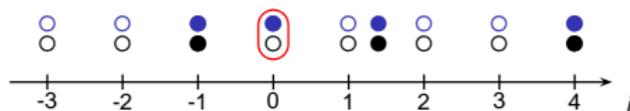
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

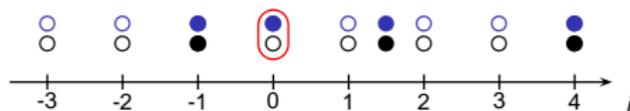
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

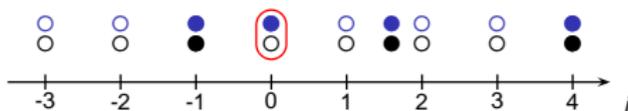
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

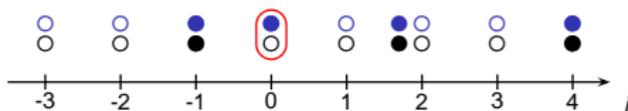
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

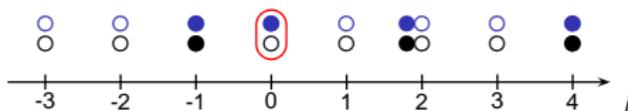
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

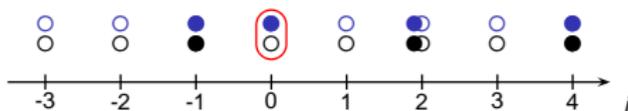
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

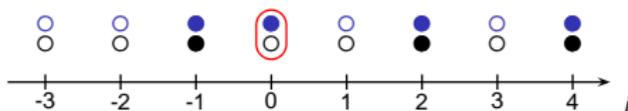
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

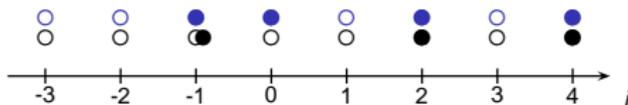
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

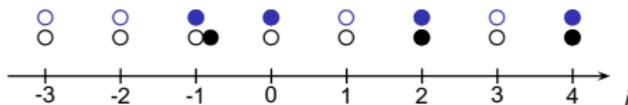
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

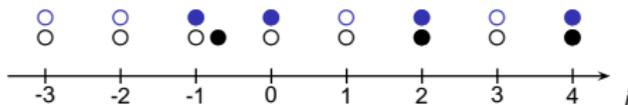
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

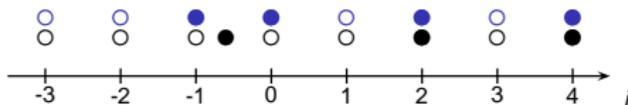
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

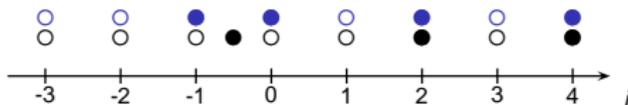
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

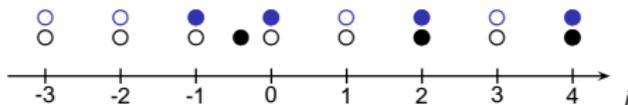
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

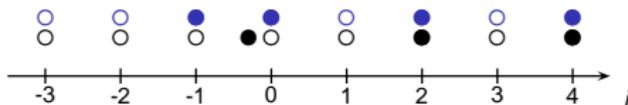
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

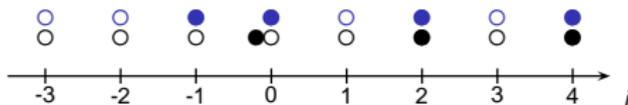
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

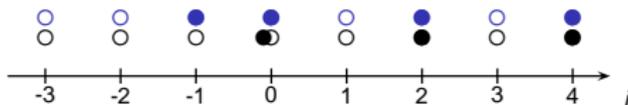
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

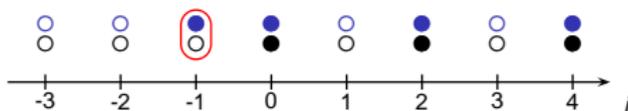
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

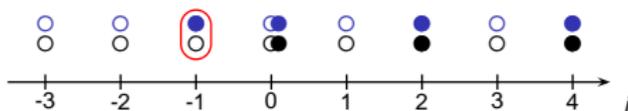
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

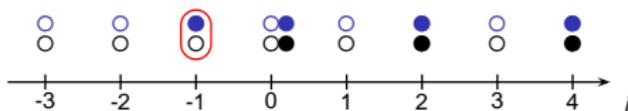
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

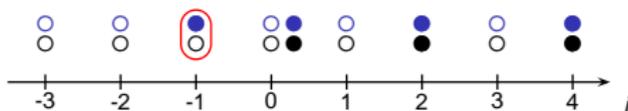
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

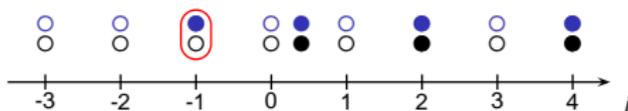
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

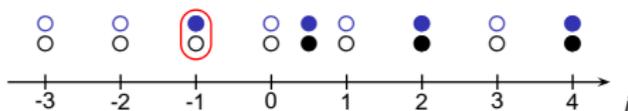
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

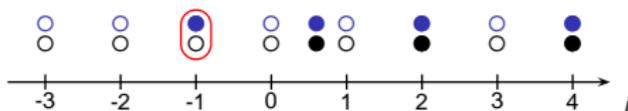
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

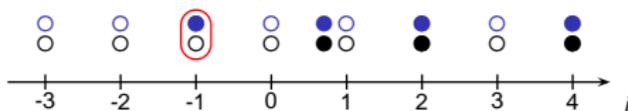
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

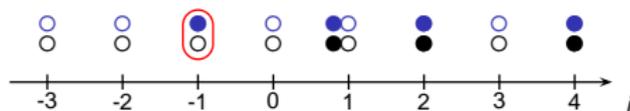
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

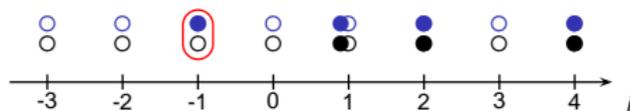
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

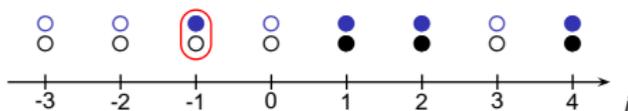
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

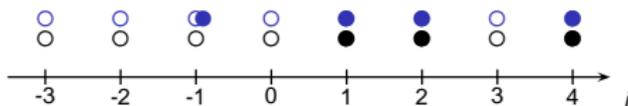
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

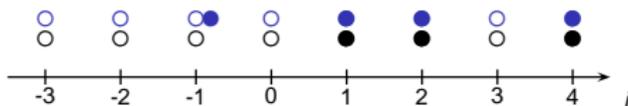
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

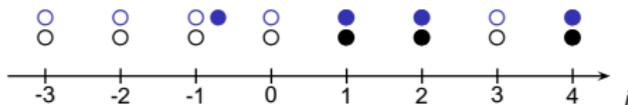
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

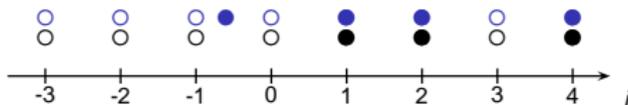
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

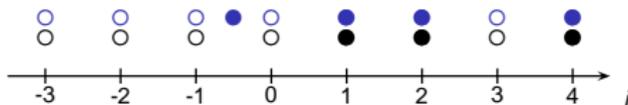
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

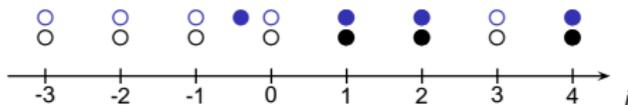
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

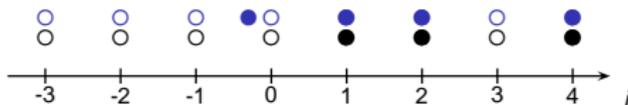
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

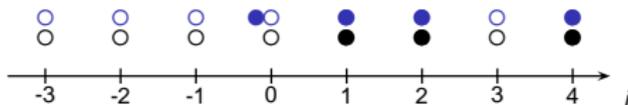
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

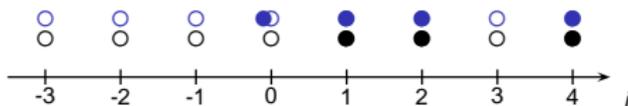
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

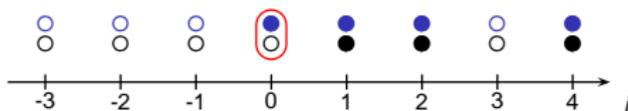
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle.

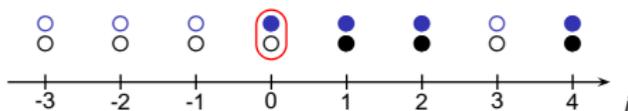
The second class particle



Stochastic coupling: evolution as close as possible

Second class particle. Its position at time t : $Q(t)$.

The second class particle

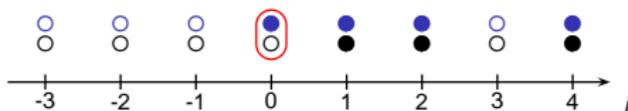


Stochastic coupling: evolution as close as possible

Second class particle. Its position at time t : $Q(t)$.

$$\begin{aligned}
 \mathbf{Cov}(\omega_i(t), \omega_0(0)) &= \mathbf{E}[\omega_i(t)\omega_0(0) \mid \omega_0(0) = 0] \cdot (1 - \rho) \\
 &\quad + \mathbf{E}[\omega_i(t)\omega_0(0) \mid \omega_0(0) = 1] \cdot \rho - \rho^2 \\
 &= \mathbf{E}[\omega_i(t)] \cdot \rho - \rho^2.
 \end{aligned}$$

The second class particle



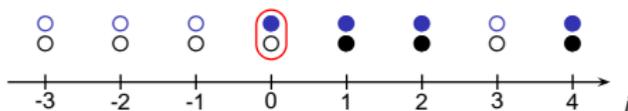
Stochastic coupling: evolution as close as possible

Second class particle. Its position at time t : $Q(t)$.

$$\begin{aligned} \mathbf{Cov}(\omega_i(t), \omega_0(0)) &= \mathbf{E}[\omega_i(t)\omega_0(0) \mid \omega_0(0) = 0] \cdot (1 - \varrho) \\ &\quad + \mathbf{E}[\omega_i(t)\omega_0(0) \mid \omega_0(0) = 1] \cdot \varrho - \varrho^2 \\ &= \mathbf{E}[\omega_i(t)] \cdot \varrho - \varrho^2. \end{aligned}$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_i(t) - \omega_i(t)] = \mathbf{E}[\omega_i(t)] - \mathbf{E}[\omega_i(t)].$$

The second class particle



Stochastic coupling: evolution as close as possible

Second class particle. Its position at time t : $Q(t)$.

$$\begin{aligned} \mathbf{Cov}(\omega_i(t), \omega_0(0)) &= \mathbf{E}[\omega_i(t)\omega_0(0) \mid \omega_0(0) = 0] \cdot (1 - \varrho) \\ &\quad + \mathbf{E}[\omega_i(t)\omega_0(0) \mid \omega_0(0) = 1] \cdot \varrho - \varrho^2 \\ &= \mathbf{E}[\omega_i(t)] \cdot \varrho - \varrho^2. \end{aligned}$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_i(t) - \omega_i(t)] = \mathbf{E}[\omega_i(t)] - \mathbf{E}[\omega_i(t)].$$

$$\begin{aligned} \varrho &= \mathbf{E}[\omega_i(t)] = \mathbf{E}[\omega_i(t) \mid \omega_0(0) = 0] \cdot (1 - \varrho) \\ &\quad + \mathbf{E}[\omega_i(t) \mid \omega_0(0) = 1] \cdot \varrho \\ &= \mathbf{E}[\omega_i(t)] \cdot (1 - \varrho) + \mathbf{E}[\omega_i(t)] \cdot \varrho \end{aligned}$$

The second class particle

$$\mathbf{Cov}(\omega_j(t), \omega_0(0)) = \mathbf{E}[\omega_j(t)] \cdot \varrho - \varrho^2. \quad (1)$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]. \quad (2)$$

$$\varrho = \mathbf{E}[\omega_j(t)] \cdot (1 - \varrho) + \mathbf{E}[\omega_i(t)] \cdot \varrho. \quad (3)$$

The second class particle

$$\mathbf{Cov}(\omega_j(t), \omega_0(0)) = \mathbf{E}[\omega_j(t)] \cdot \varrho - \varrho^2. \quad (1)$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]. \quad (2)$$

$$\varrho = \mathbf{E}[\omega_j(t)] \cdot (1 - \varrho) + \mathbf{E}[\omega_i(t)] \cdot \varrho. \quad (3)$$

So,

$$\mathbf{Cov}(\omega_j(t), \omega_0(0)) \stackrel{(1)}{=} \varrho \cdot (\mathbf{E}[\omega_j(t)] - \varrho)$$

The second class particle

$$\mathbf{Cov}(\omega_j(t), \omega_0(0)) = \mathbf{E}[\omega_j(t)] \cdot \varrho - \varrho^2. \quad (1)$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]. \quad (2)$$

$$\varrho = \mathbf{E}[\omega_j(t)] \cdot (1 - \varrho) + \mathbf{E}[\omega_i(t)] \cdot \varrho. \quad (3)$$

So,

$$\begin{aligned} \mathbf{Cov}(\omega_j(t), \omega_0(0)) &\stackrel{(1)}{=} \varrho \cdot (\mathbf{E}[\omega_j(t)] - \varrho) \\ &\stackrel{(3)}{=} \varrho(1 - \varrho) \cdot (\mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]) \end{aligned}$$

The second class particle

$$\mathbf{Cov}(\omega_j(t), \omega_0(0)) = \mathbf{E}[\omega_j(t)] \cdot \varrho - \varrho^2. \quad (1)$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]. \quad (2)$$

$$\varrho = \mathbf{E}[\omega_j(t)] \cdot (1 - \varrho) + \mathbf{E}[\omega_i(t)] \cdot \varrho. \quad (3)$$

So,

$$\begin{aligned} \mathbf{Cov}(\omega_j(t), \omega_0(0)) &\stackrel{(1)}{=} \varrho \cdot (\mathbf{E}[\omega_j(t)] - \varrho) \\ &\stackrel{(3)}{=} \varrho(1 - \varrho) \cdot (\mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]) \\ &\stackrel{(2)}{=} \varrho(1 - \varrho) \cdot \mathbf{P}\{Q(t) = i\}. \end{aligned}$$

The second class particle

$$\mathbf{Cov}(\omega_j(t), \omega_0(0)) = \mathbf{E}[\omega_j(t)] \cdot \varrho - \varrho^2. \quad (1)$$

$$\mathbf{P}\{Q(t) = i\} = \mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]. \quad (2)$$

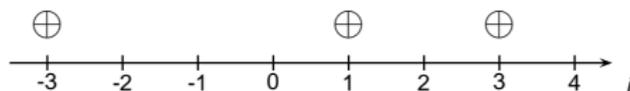
$$\varrho = \mathbf{E}[\omega_j(t)] \cdot (1 - \varrho) + \mathbf{E}[\omega_i(t)] \cdot \varrho. \quad (3)$$

So,

$$\begin{aligned} \mathbf{Cov}(\omega_j(t), \omega_0(0)) &\stackrel{(1)}{=} \varrho \cdot (\mathbf{E}[\omega_j(t)] - \varrho) \\ &\stackrel{(3)}{=} \varrho(1 - \varrho) \cdot (\mathbf{E}[\omega_j(t)] - \mathbf{E}[\omega_i(t)]) \\ &\stackrel{(2)}{=} \varrho(1 - \varrho) \cdot \mathbf{P}\{Q(t) = i\}. \end{aligned}$$

The second class particle traces information propagation.

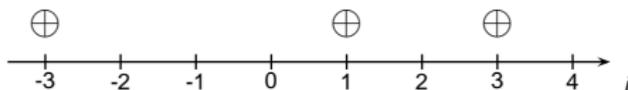
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

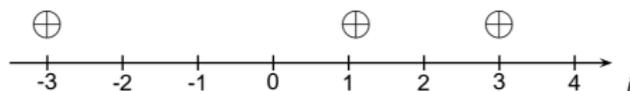
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

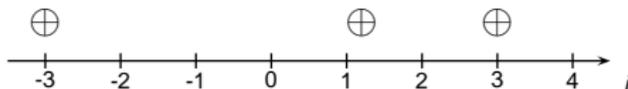
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

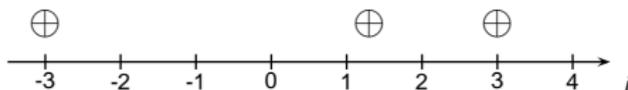
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

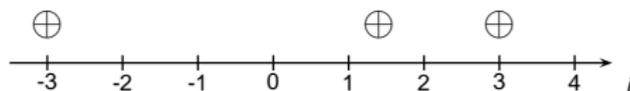
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

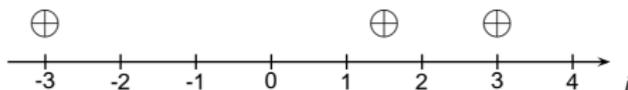
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

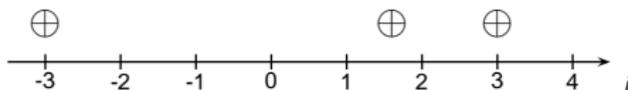
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

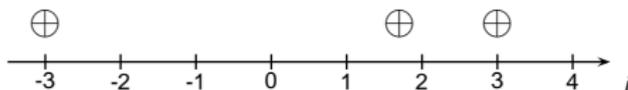
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

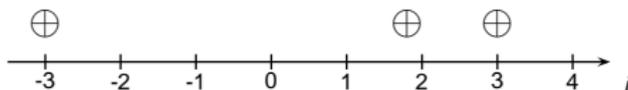
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

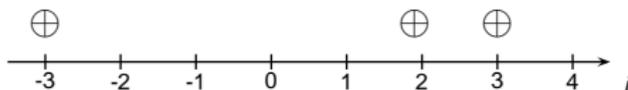
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

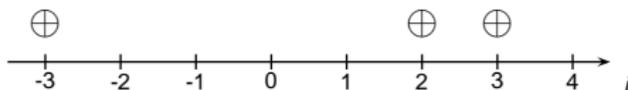
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

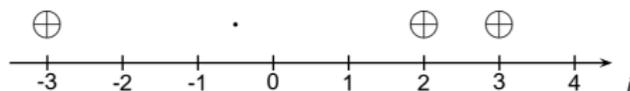
\oplus to the right: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

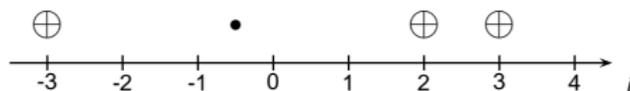
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

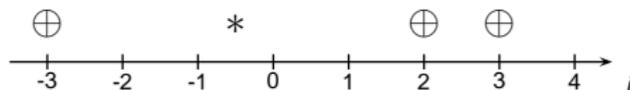
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

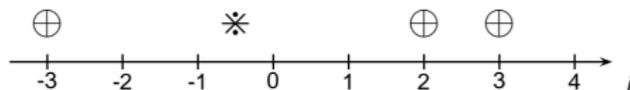
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

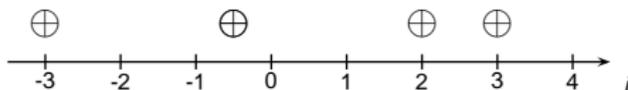
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

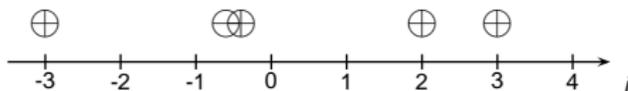
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

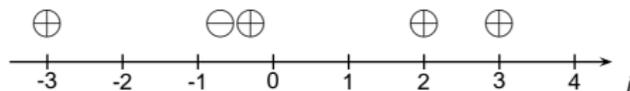
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

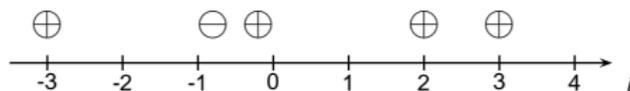
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

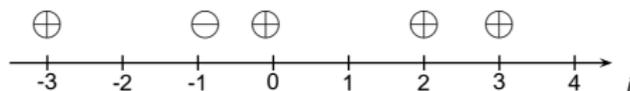
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

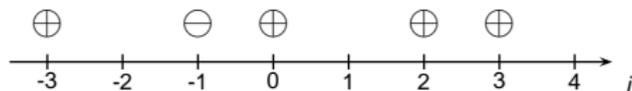
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

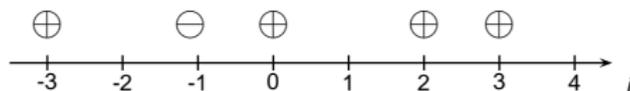
pair creation from vacuum: rate c



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

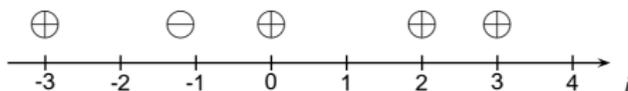
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

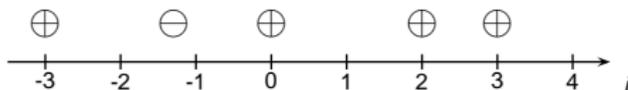
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

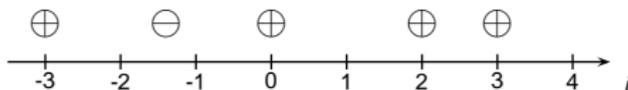
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

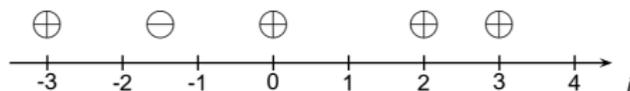
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

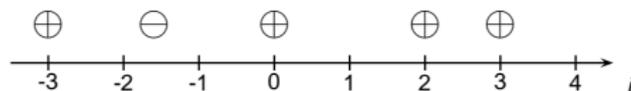
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

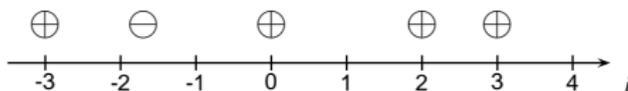
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

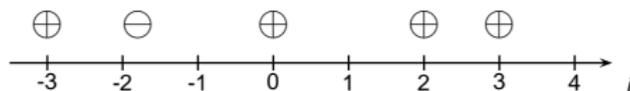
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

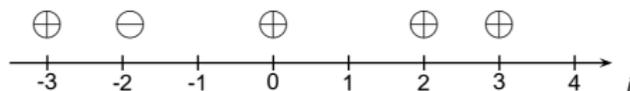
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

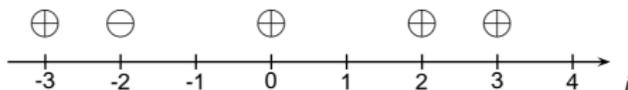
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

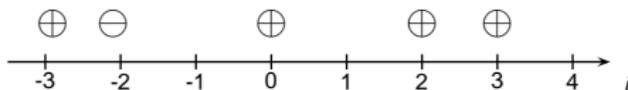
\ominus to the left: rate 1



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

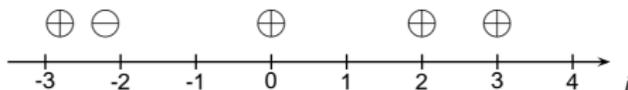
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

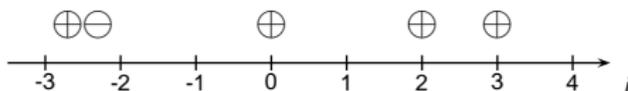
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

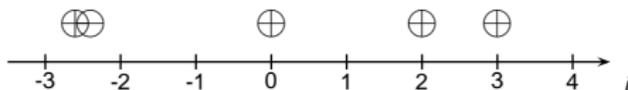
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

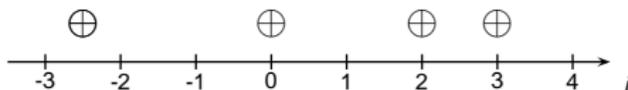
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

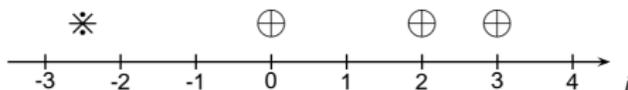
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

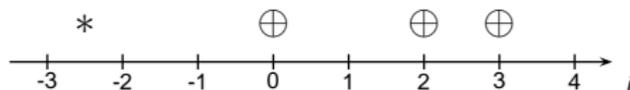
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

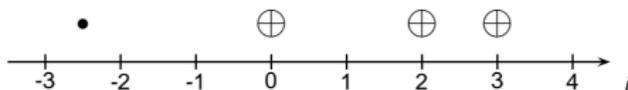
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

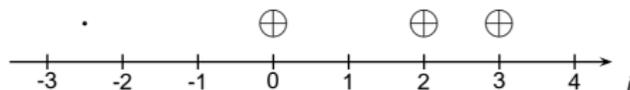
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

A $\oplus \ominus 0$ model

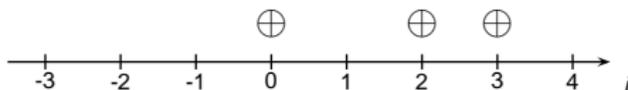
annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

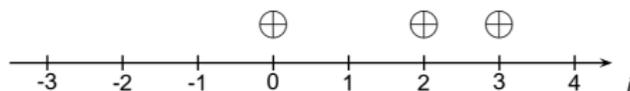
A $\oplus \ominus 0$ model

annihilation: rate 2



$\omega_i = -1, 0, 1$: a family of product initial distribution.

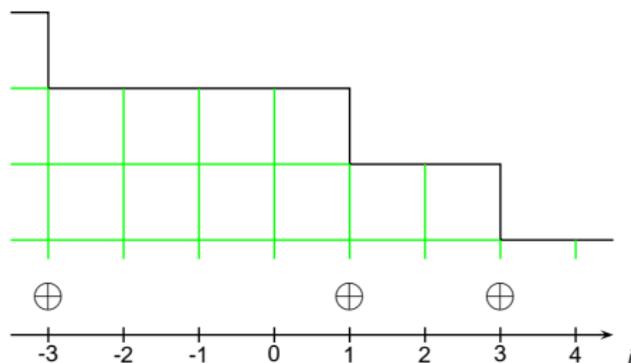
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

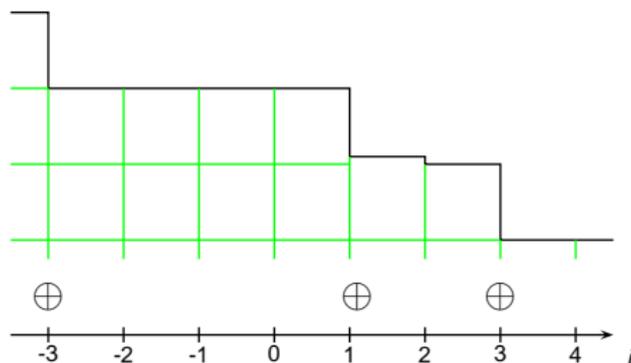
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

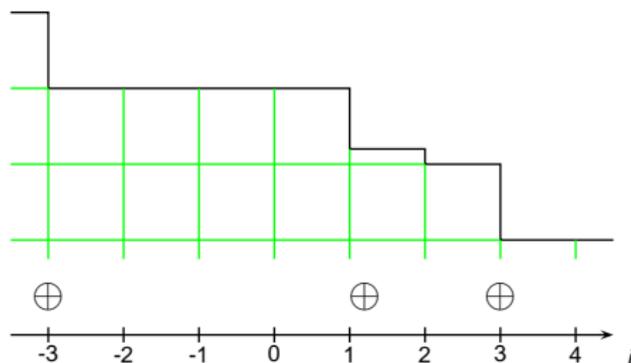
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

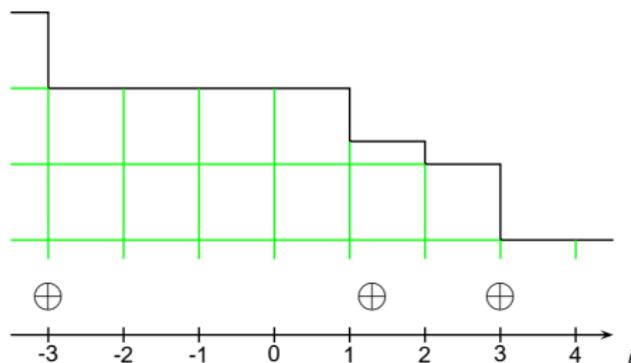
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

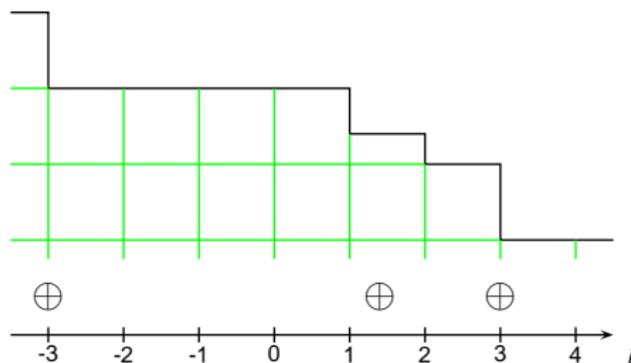
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

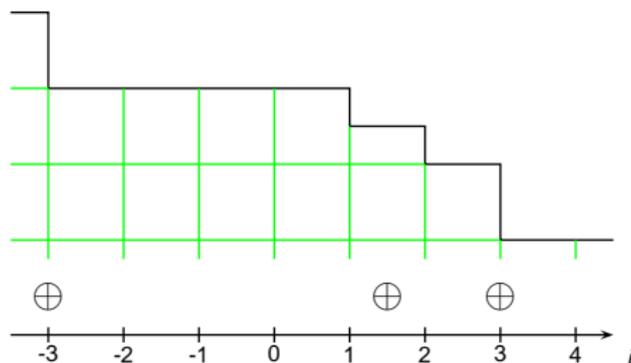
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

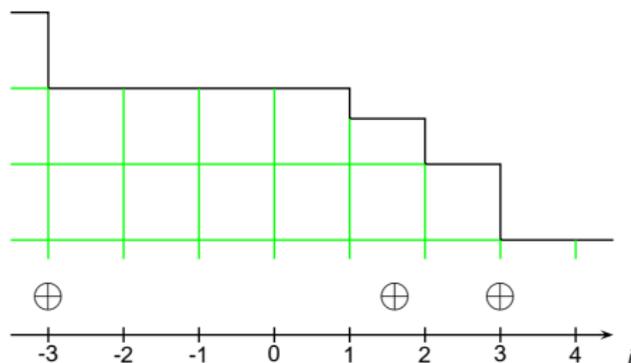
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

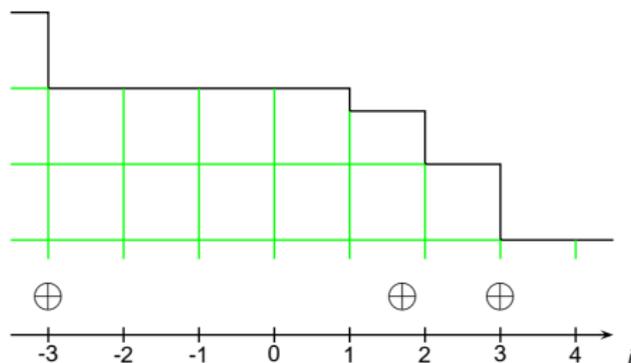
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

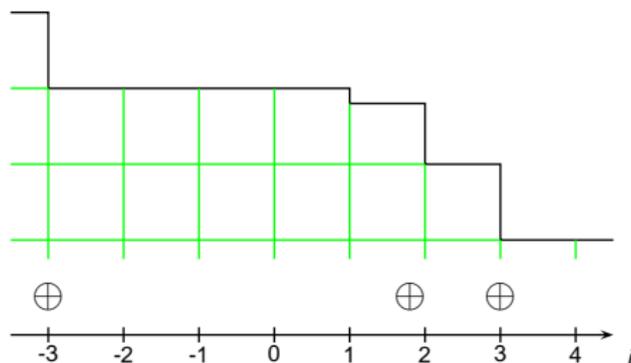
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

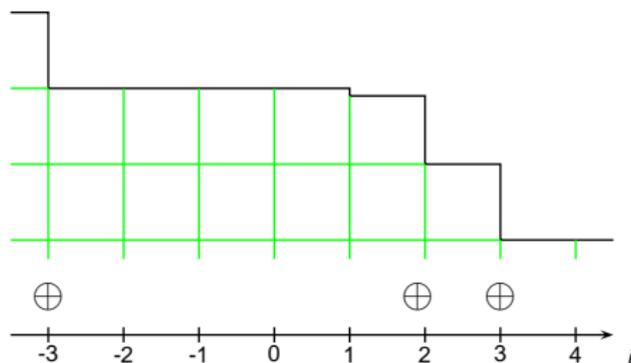
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

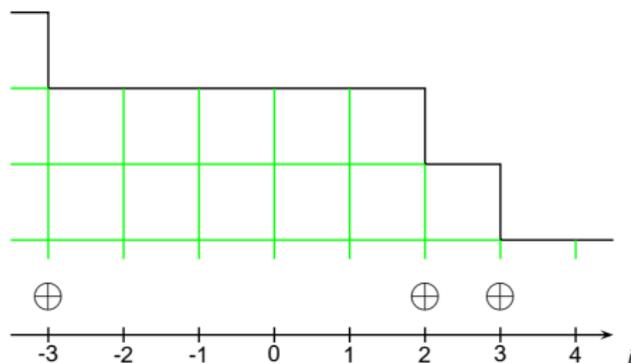
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

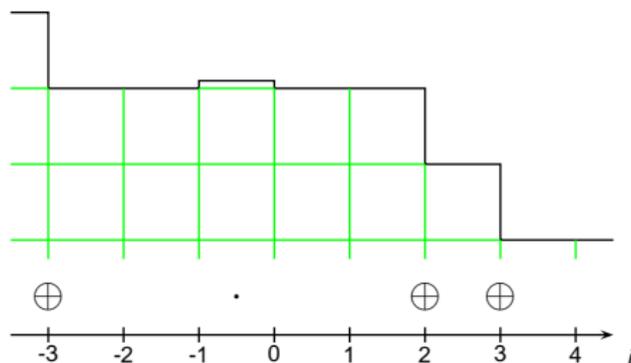


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

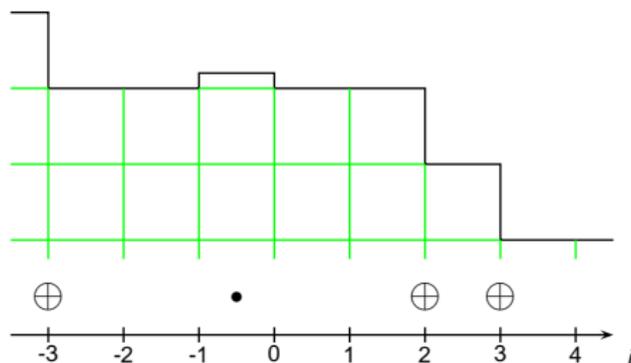
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

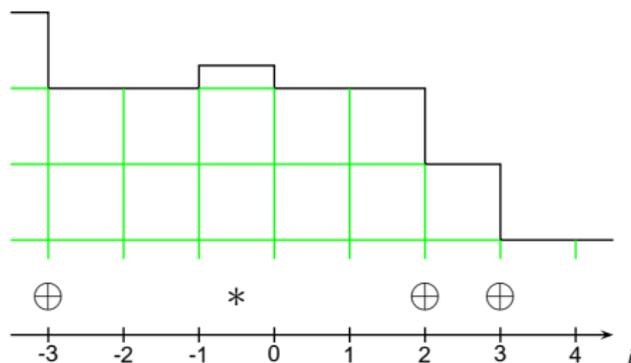
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

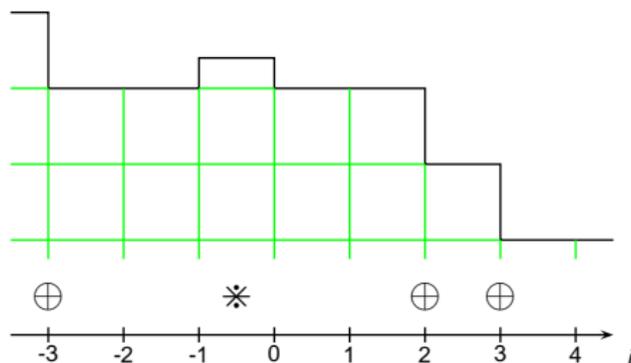
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

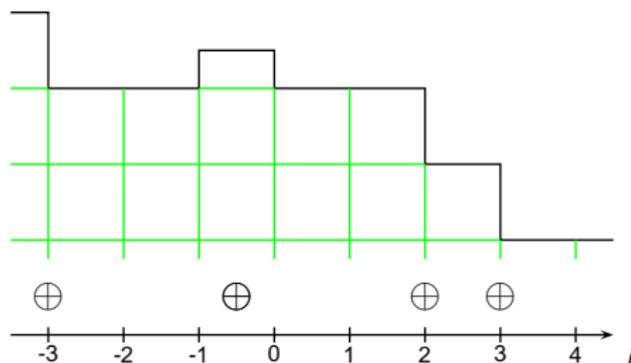
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

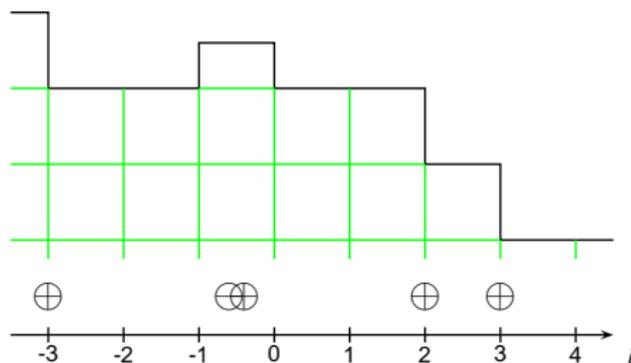
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

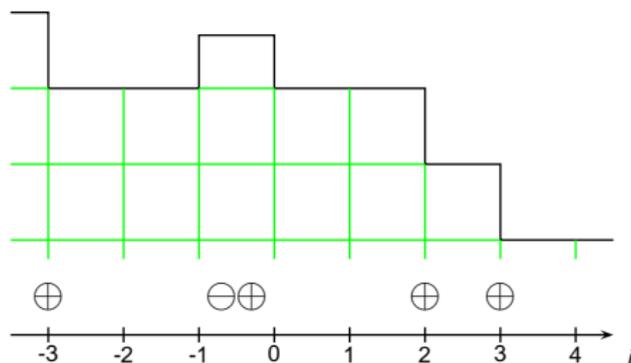
These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

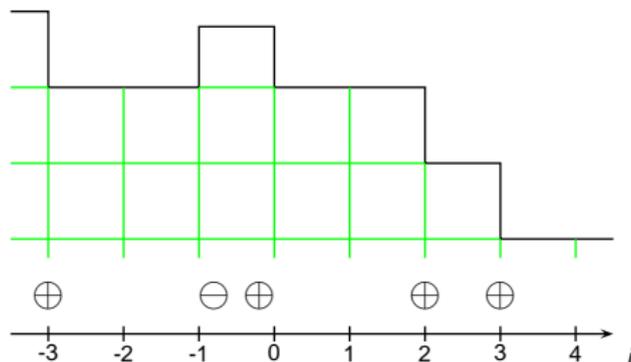
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

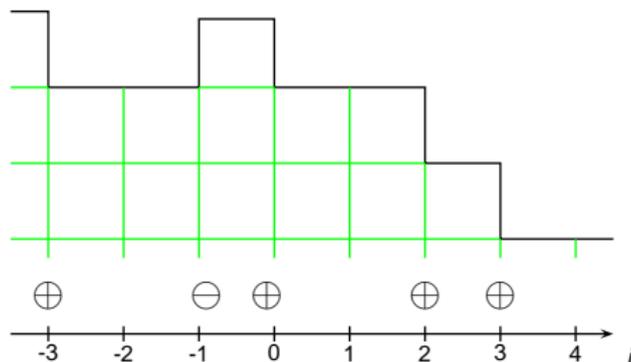


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

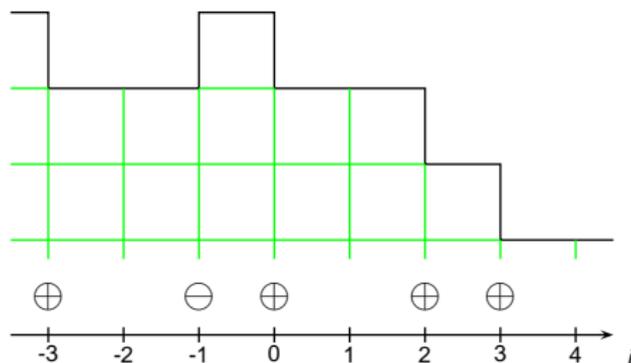
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

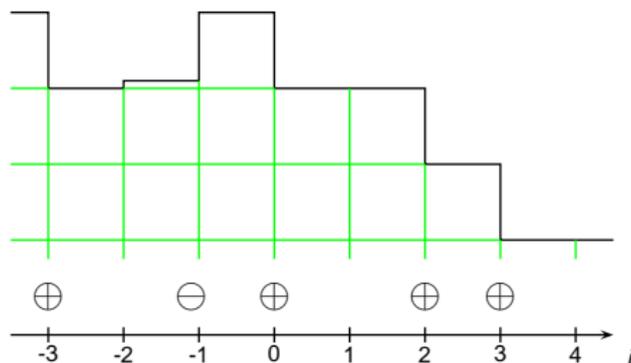
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

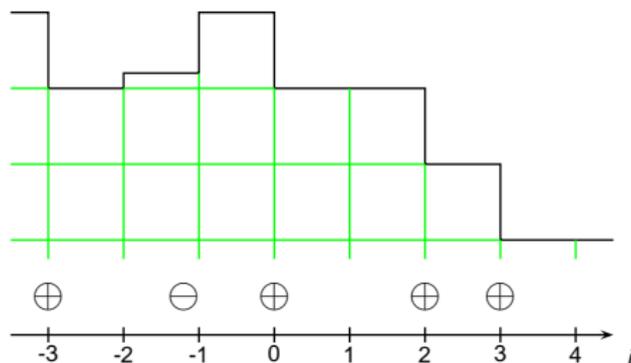


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

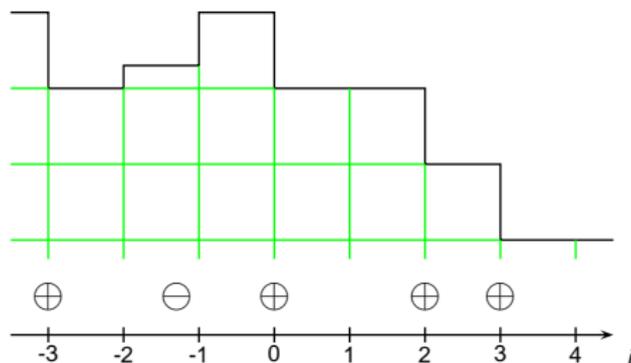


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

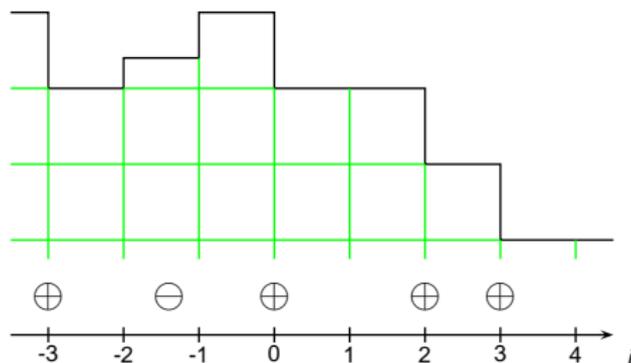
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

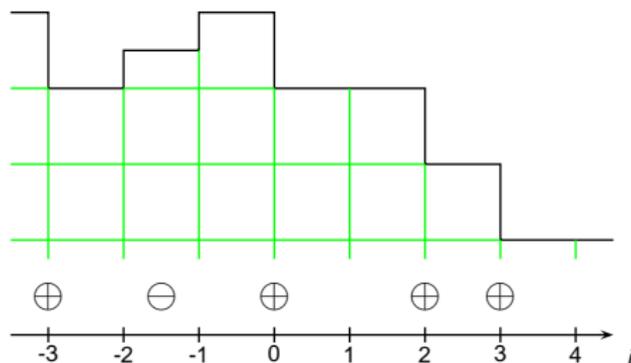
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

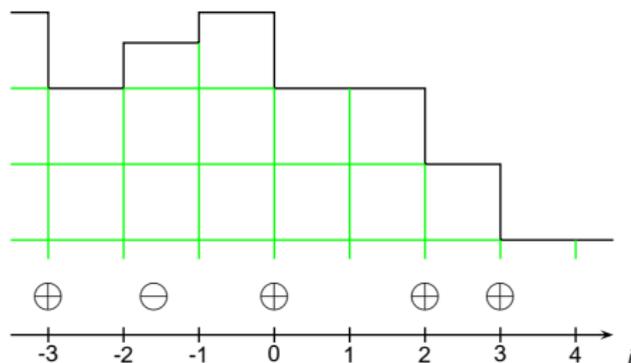
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

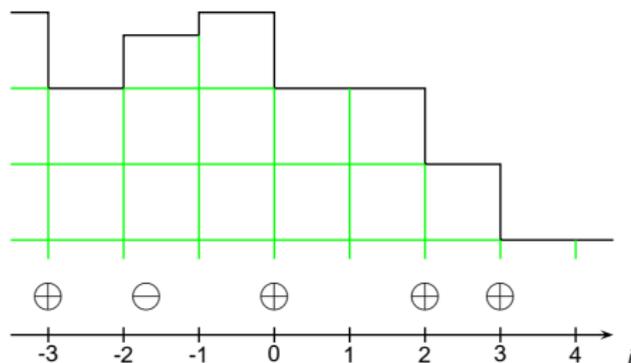
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

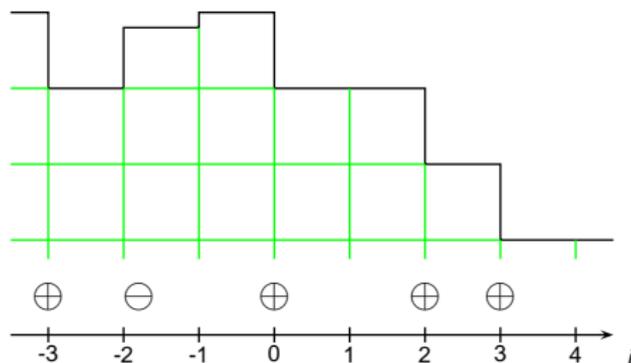


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

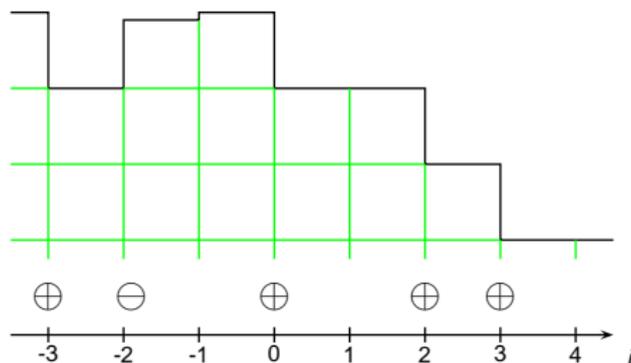


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

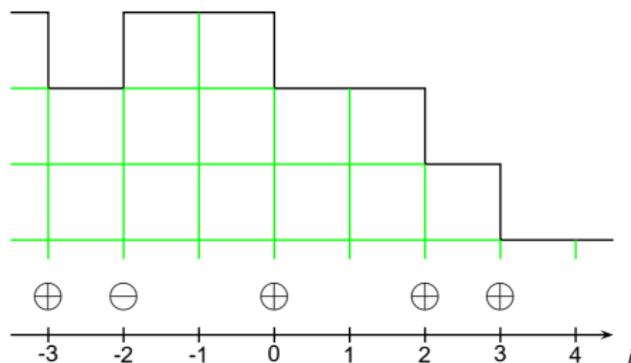
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

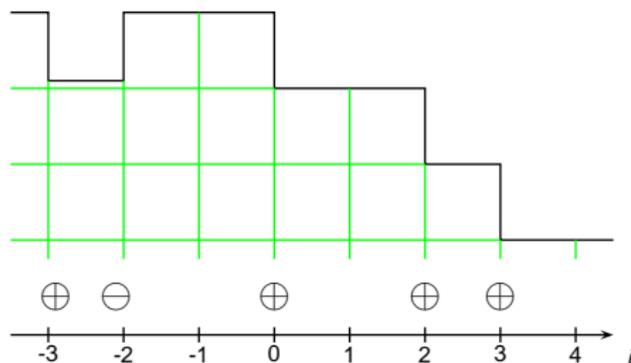
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

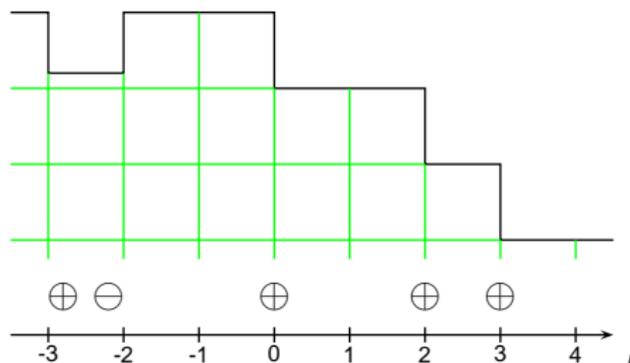


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

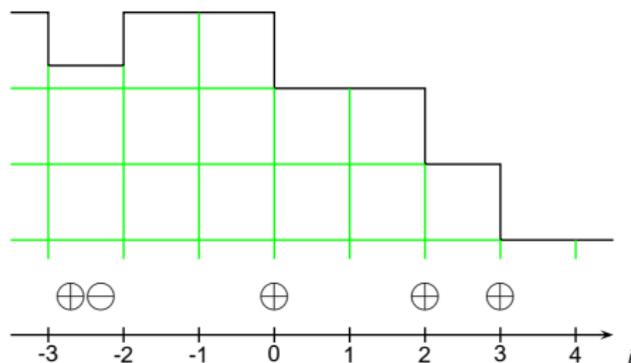


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

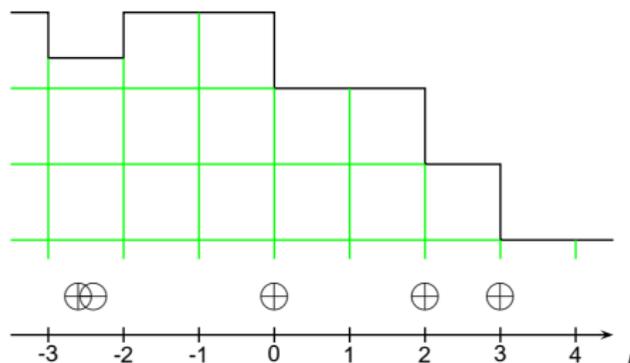


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

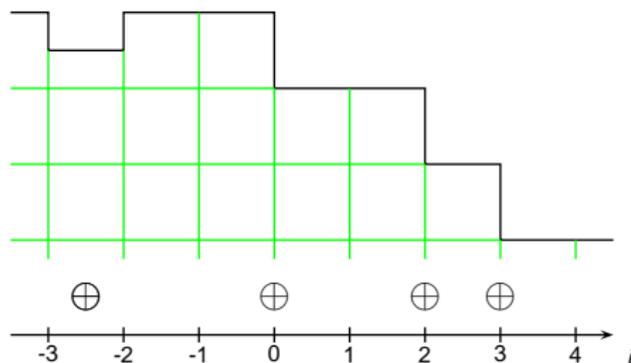


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

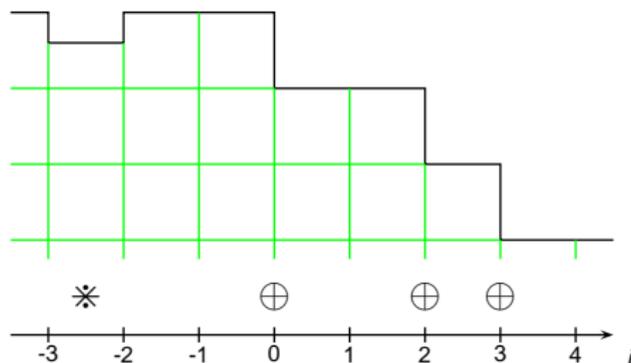
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

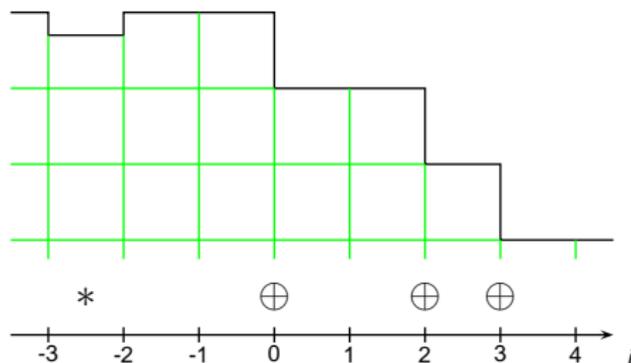
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model

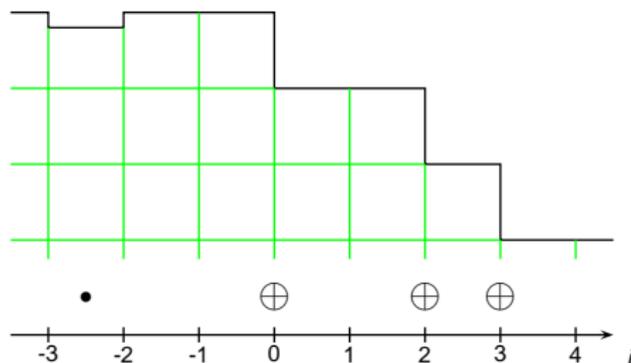


$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

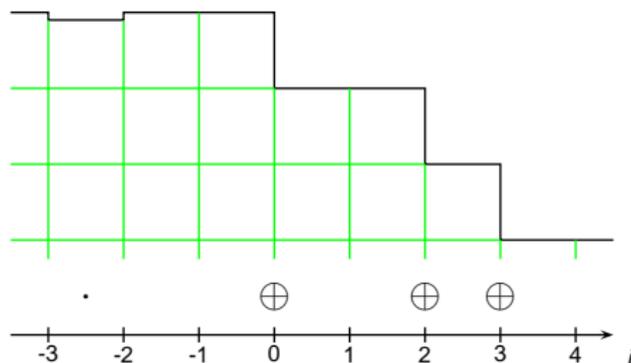
A $\oplus \ominus 0$ model



$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

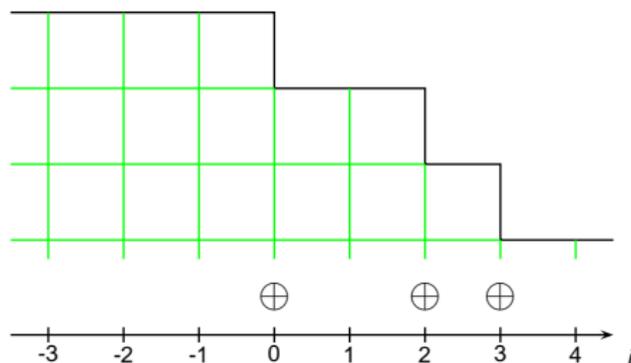
A $\oplus \ominus 0$ model

$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

A $\oplus \ominus 0$ model



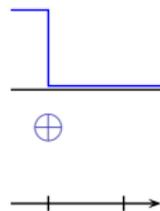
$\omega_i = -1, 0, 1$: a family of product initial distribution.

Those product distributions are stationary (and non-reversible).

These are the important (= ergodic) stationary distributions.

The second class particle

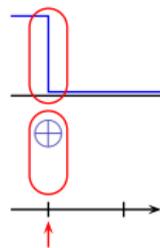
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

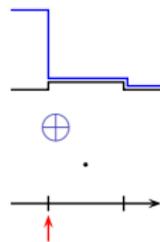
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

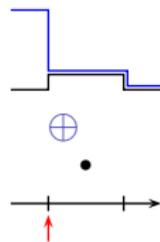
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

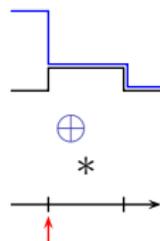
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

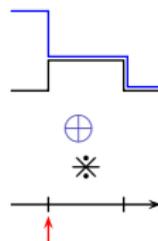
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

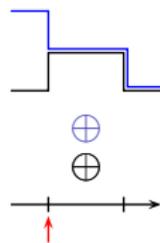
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

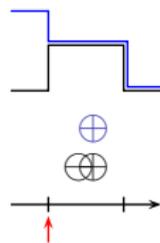
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

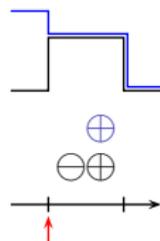
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

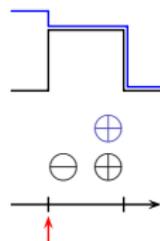
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

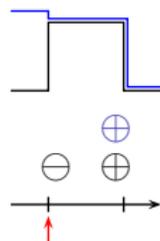
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

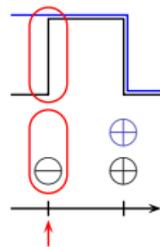
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

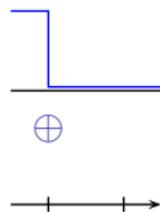
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate c

The second class particle

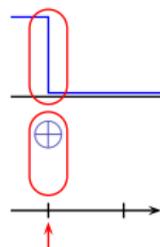
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

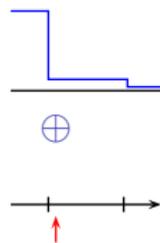
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

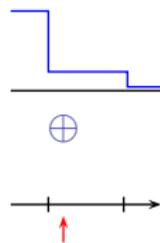
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

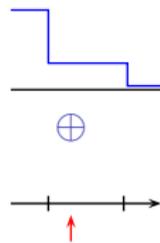
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

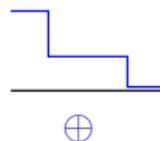
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

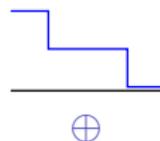
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

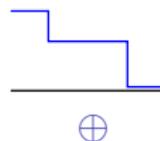
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

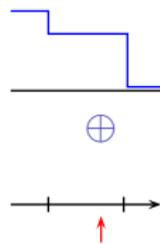
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

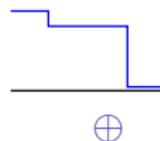
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

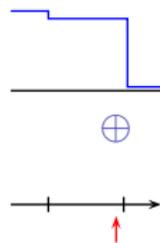
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

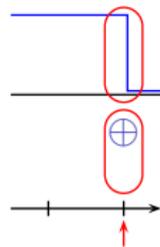
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

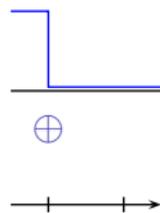
... works much like in TASEP for $c \leq 1$. The interesting case:



With rate $1 - c$

The second class particle

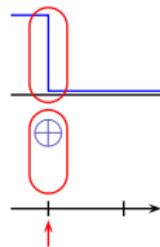
But, for $c > 1$:



With rate 1

The second class particle

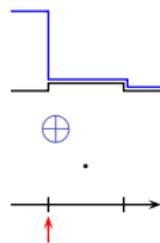
But, for $c > 1$:



With rate 1

The second class particle

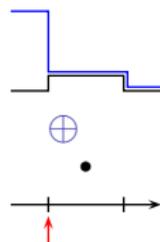
But, for $c > 1$:



With rate 1

The second class particle

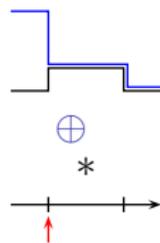
But, for $c > 1$:



With rate 1

The second class particle

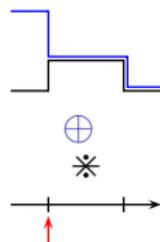
But, for $c > 1$:



With rate 1

The second class particle

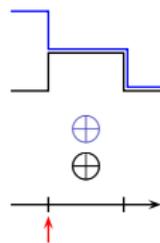
But, for $c > 1$:



With rate 1

The second class particle

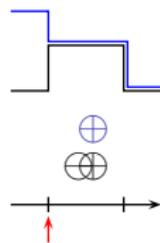
But, for $c > 1$:



With rate 1

The second class particle

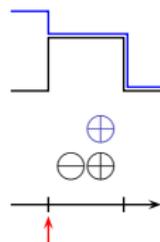
But, for $c > 1$:



With rate 1

The second class particle

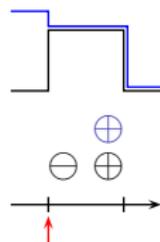
But, for $c > 1$:



With rate 1

The second class particle

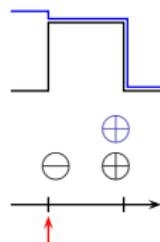
But, for $c > 1$:



With rate 1

The second class particle

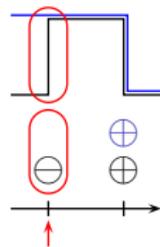
But, for $c > 1$:



With rate 1

The second class particle

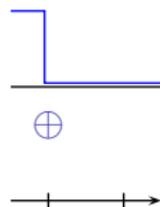
But, for $c > 1$:



With rate 1

The second class particle

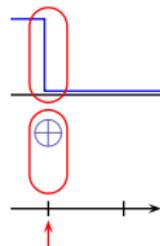
But, for $c > 1$:



With rate $c - 1$

The second class particle

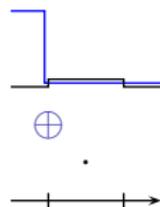
But, for $c > 1$:



With rate $c - 1$

The second class particle

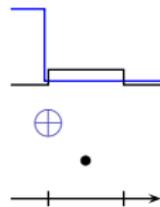
But, for $c > 1$:



With rate $c - 1$

The second class particle

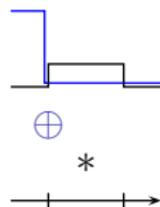
But, for $c > 1$:



With rate $c - 1$

The second class particle

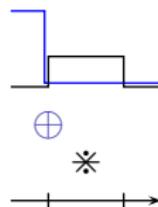
But, for $c > 1$:



With rate $c - 1$

The second class particle

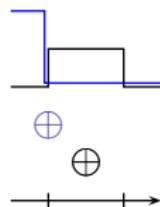
But, for $c > 1$:



With rate $c - 1$

The second class particle

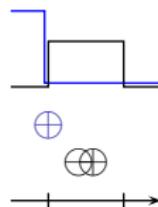
But, for $c > 1$:



With rate $c - 1$

The second class particle

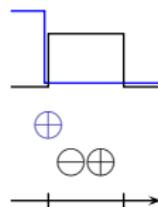
But, for $c > 1$:



With rate $c - 1$

The second class particle

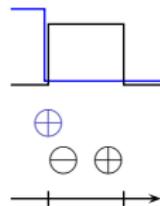
But, for $c > 1$:



With rate $c - 1$

The second class particle

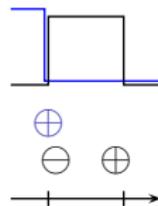
But, for $c > 1$:



With rate $c - 1$

The second class particle

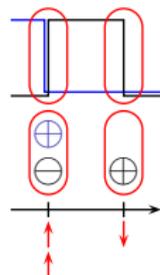
But, for $c > 1$:



With rate $c - 1$

The second class particle

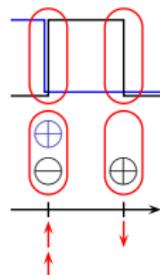
But, for $c > 1$:



With rate $c - 1$

The second class particle

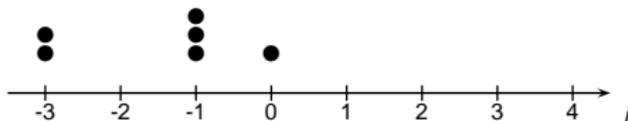
But, for $c > 1$:



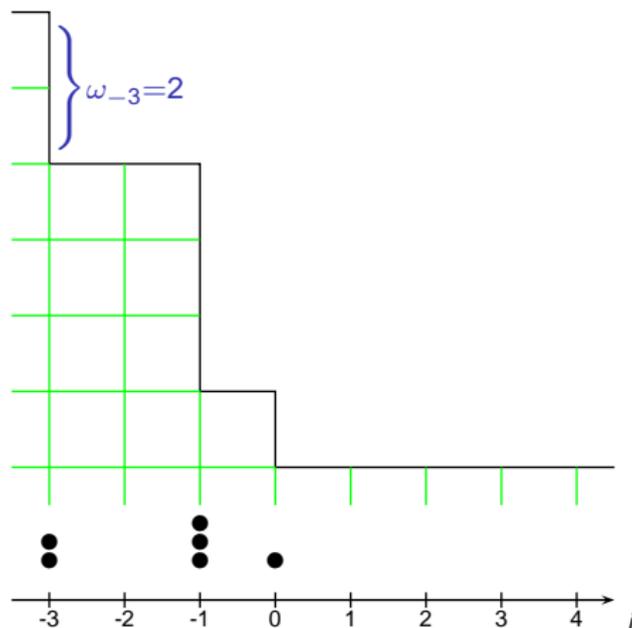
With rate $c - 1$

Non-attraction

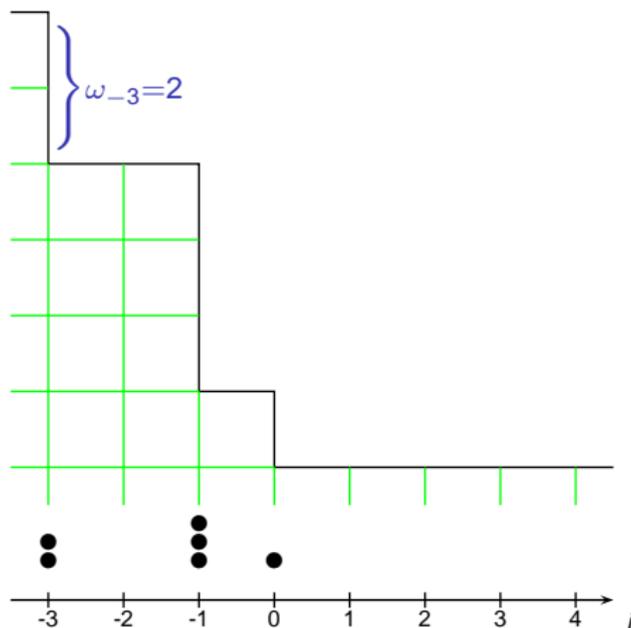
Totally asymmetric zero range process



Totally asymmetric zero range process

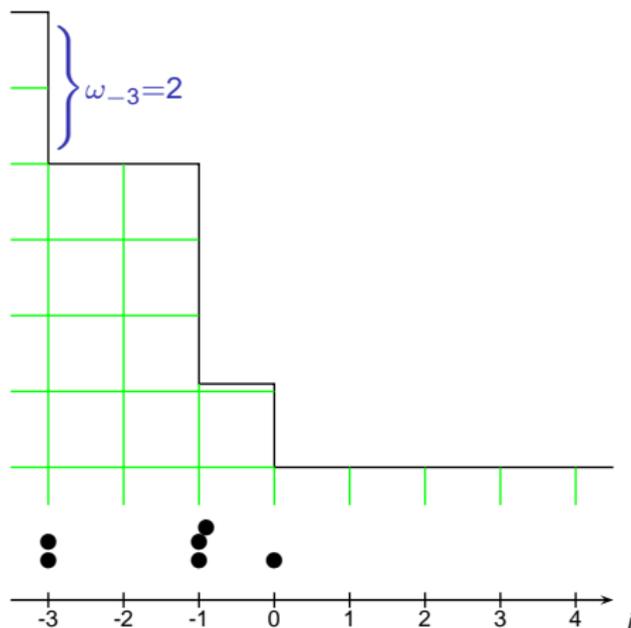


Totally asymmetric zero range process



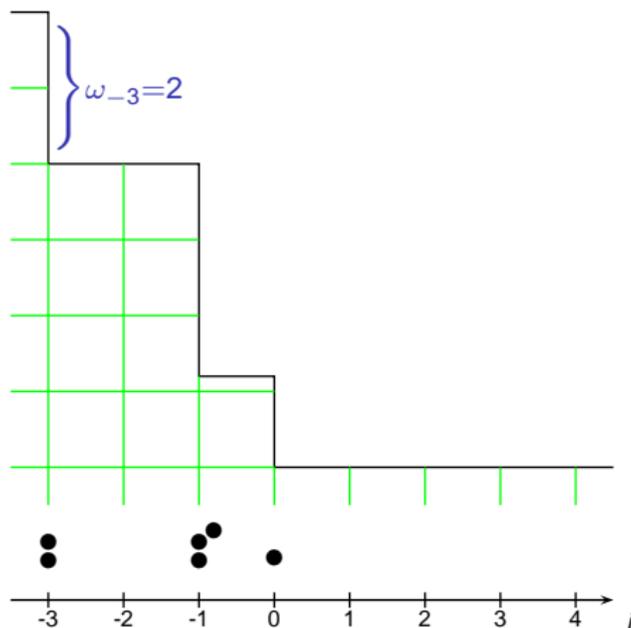
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



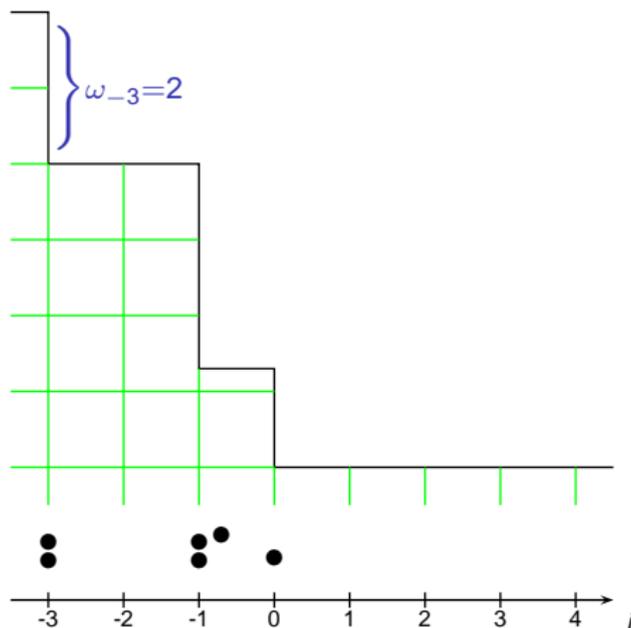
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



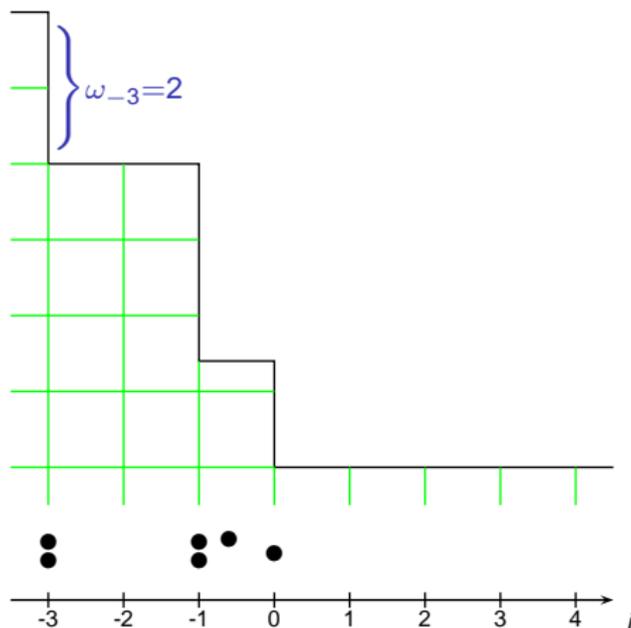
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



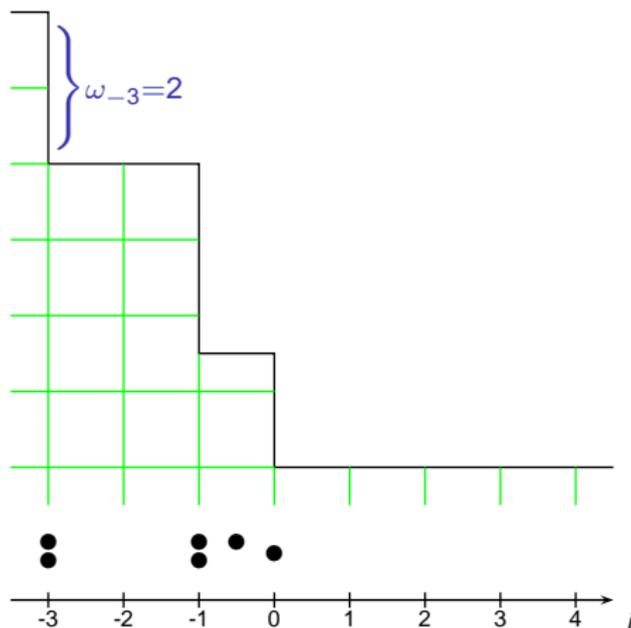
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



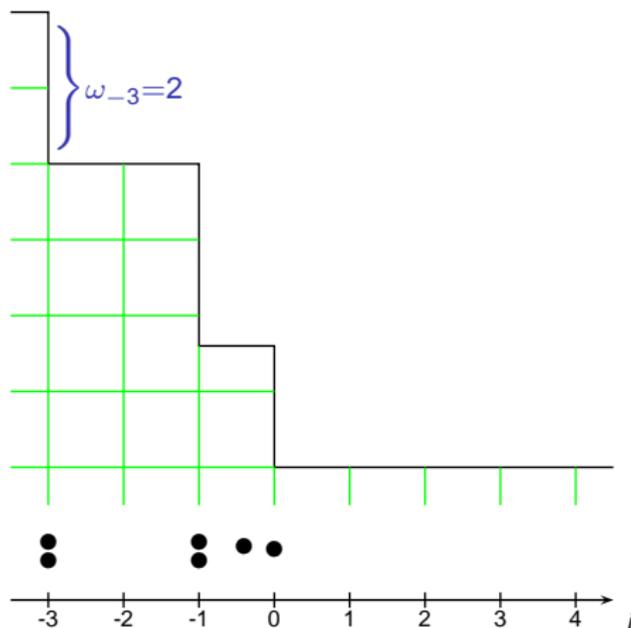
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



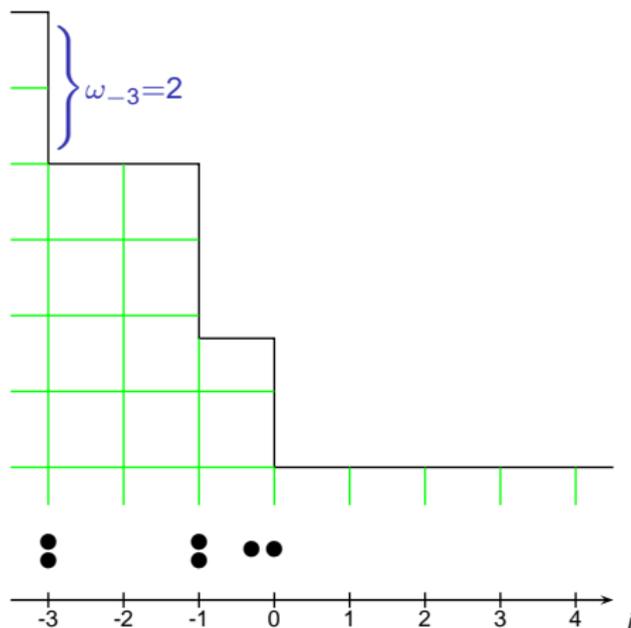
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



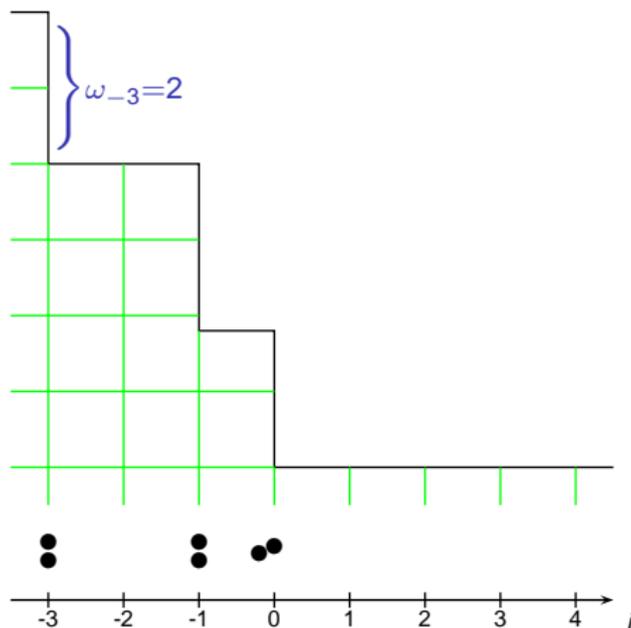
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



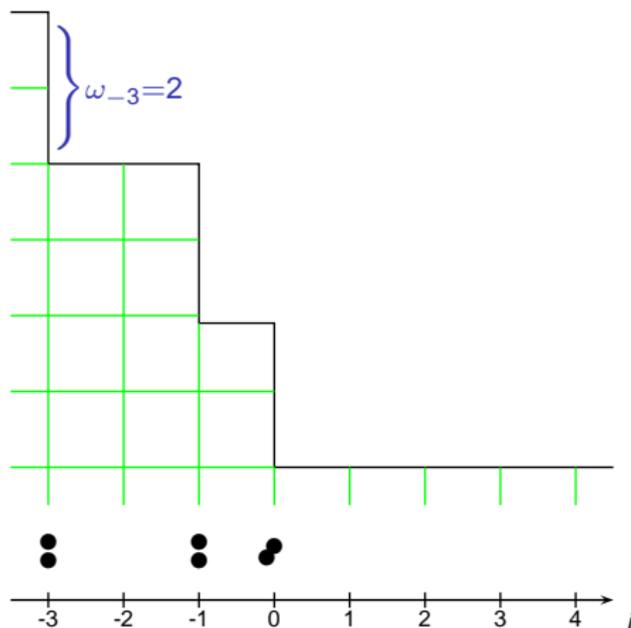
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



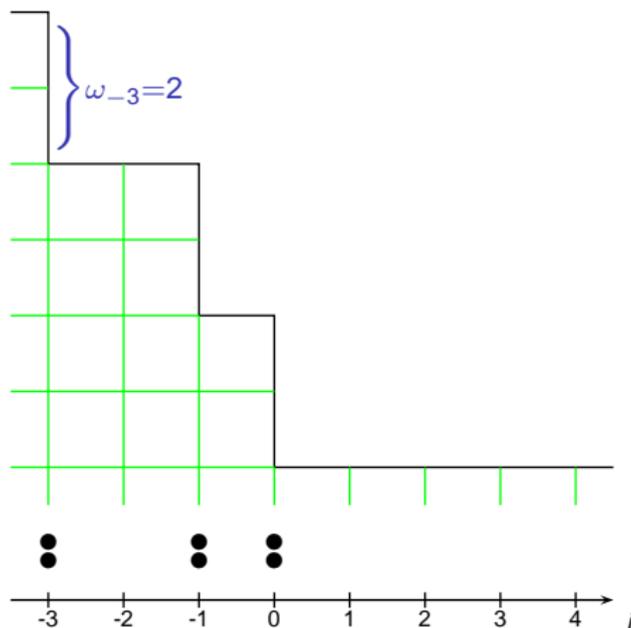
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



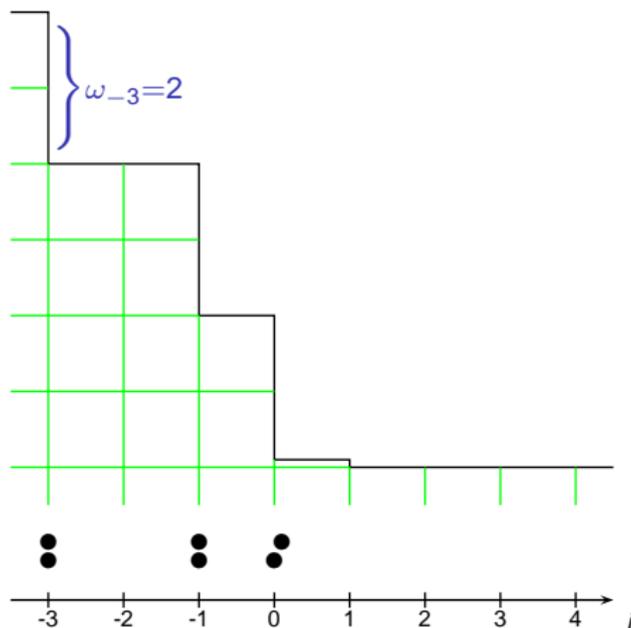
Particles jump to the right with rate $r(\omega_j)$.

Totally asymmetric zero range process



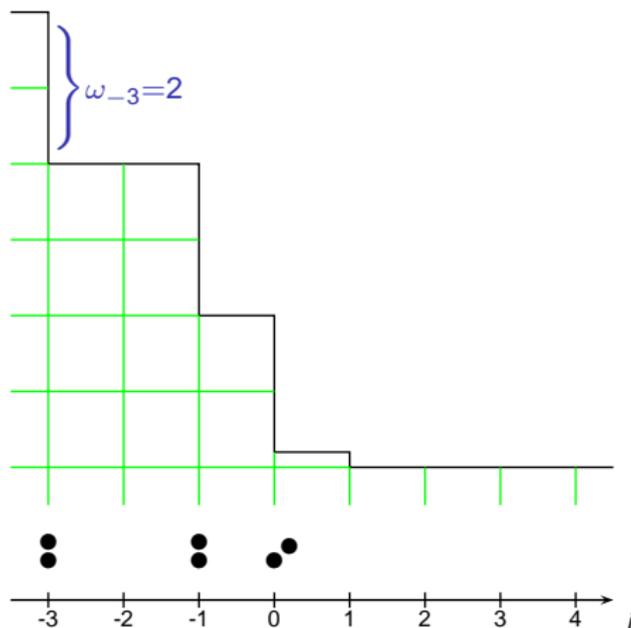
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



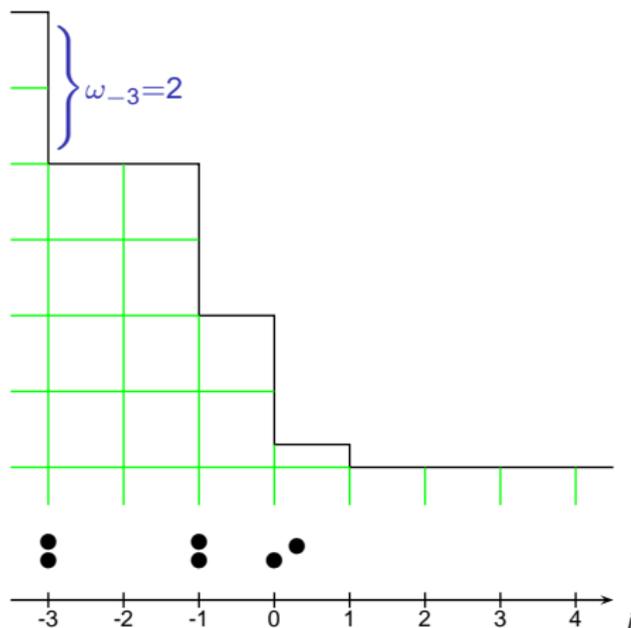
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



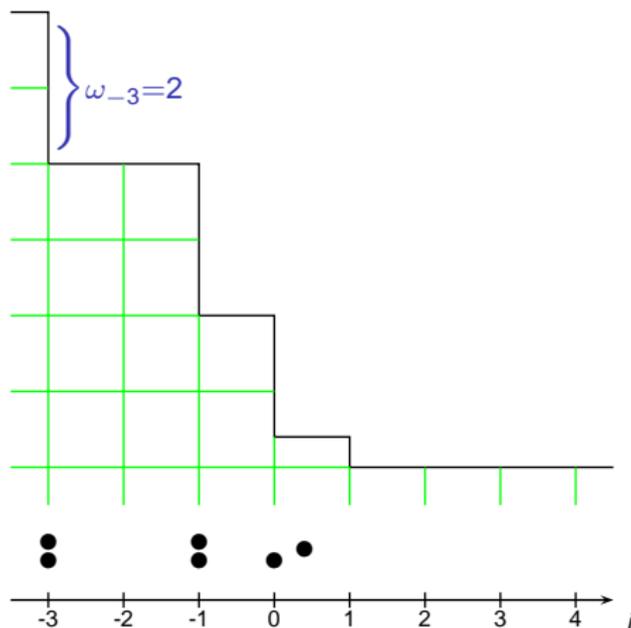
Particles jump to the right with rate $r(\omega_j)$.

Totally asymmetric zero range process



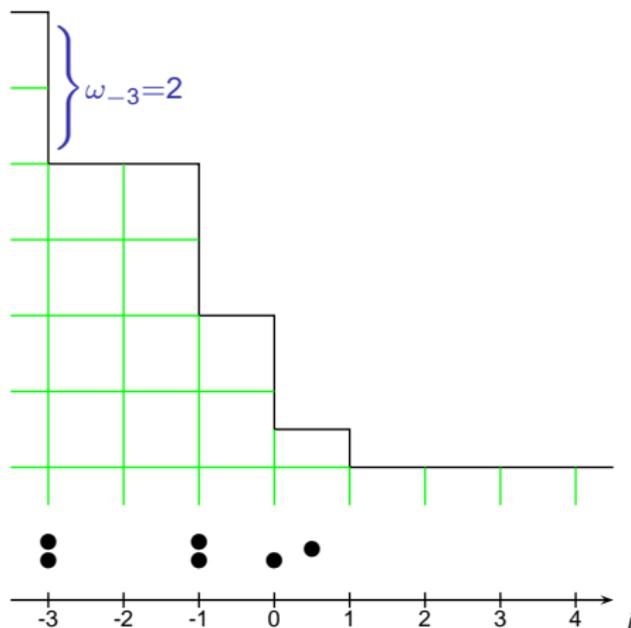
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



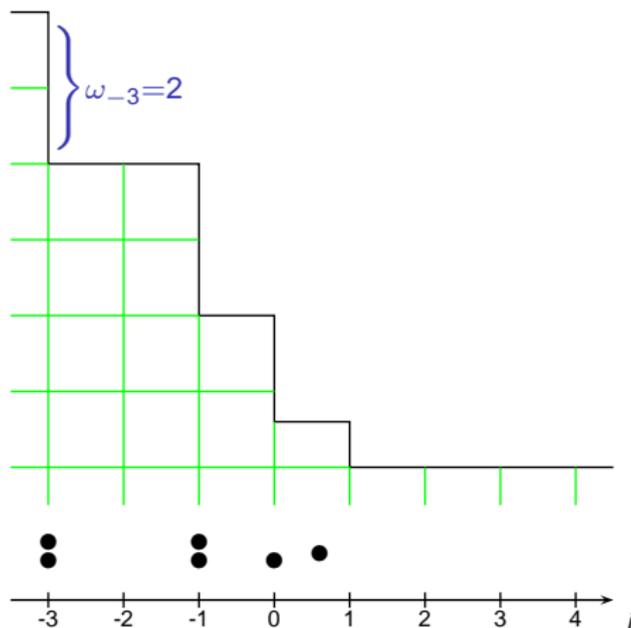
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



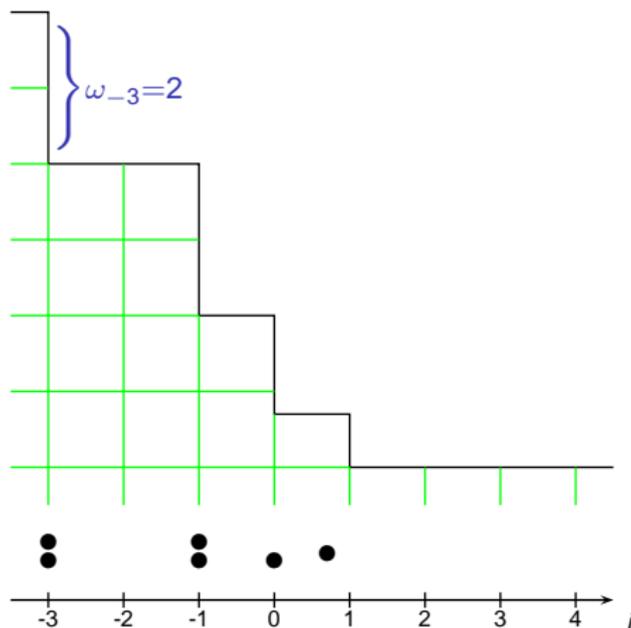
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



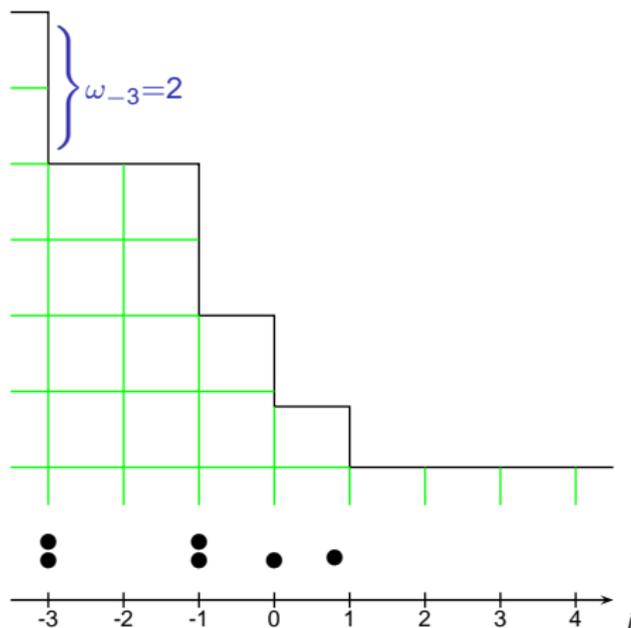
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



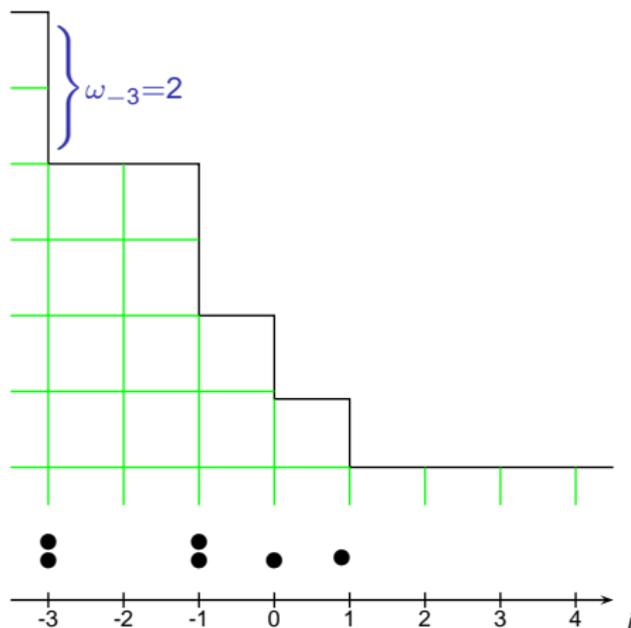
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



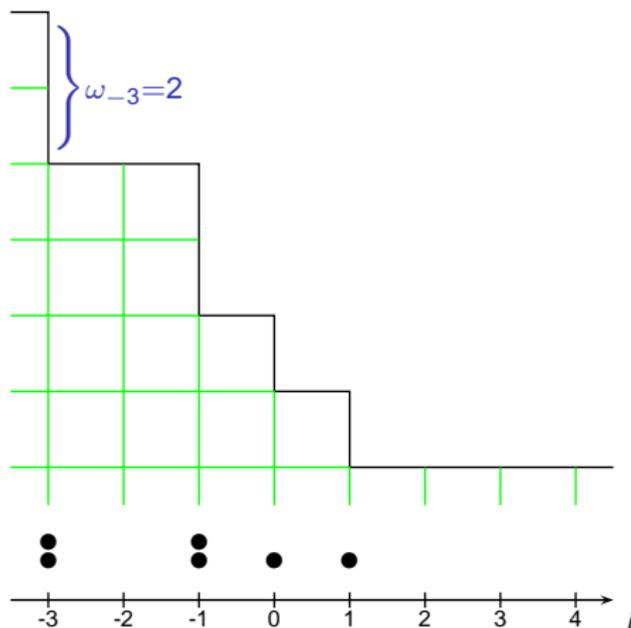
Particles jump to the right with rate $r(\omega_i)$.

Totally asymmetric zero range process



Particles jump to the right with rate $r(\omega_i)$.

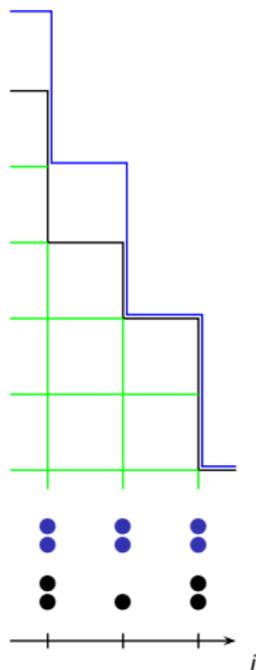
Totally asymmetric zero range process



Particles jump to the right with rate $r(\omega_j)$.

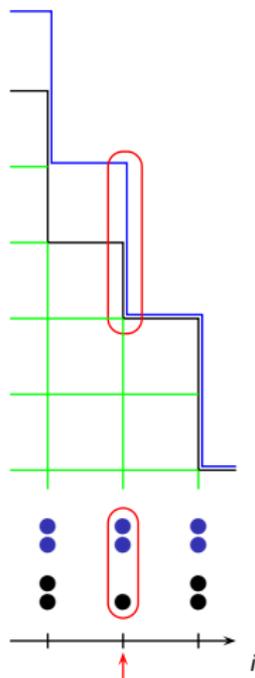
The second class particle: attractive case

States ω and ω' only differ at one site.



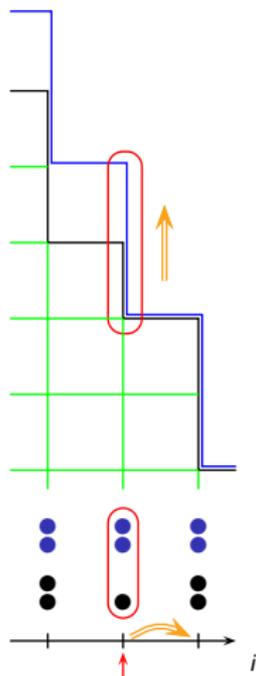
The second class particle: attractive case

States ω and ω' only differ at one site.



The second class particle: attractive case

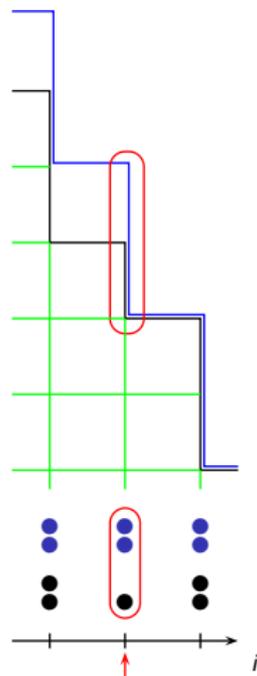
States ω and ω' only differ at one site.



Growth on the right:
 $\text{rate} \leq \text{rate}$

The second class particle: attractive case

States ω and ω' only differ at one site.



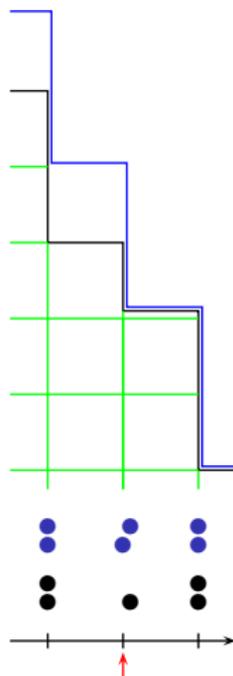
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



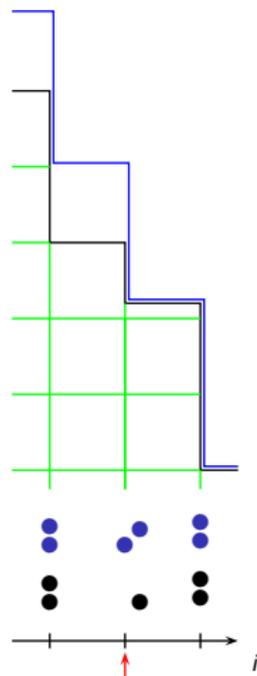
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



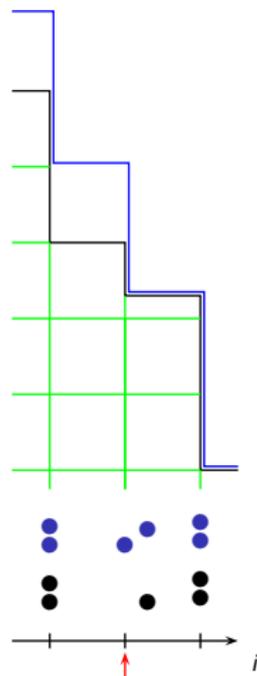
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



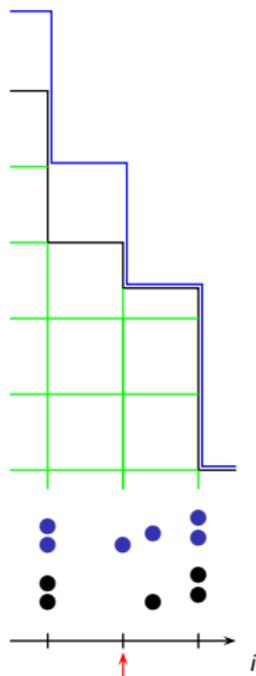
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



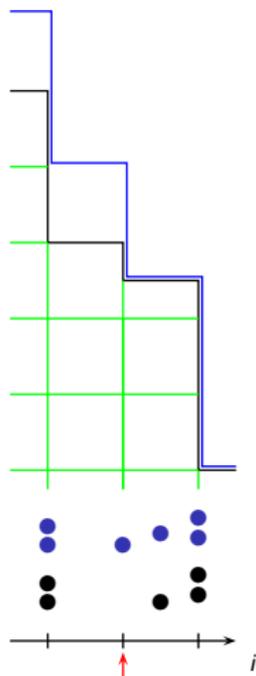
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



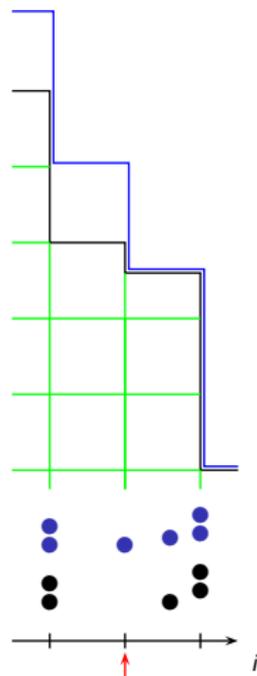
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



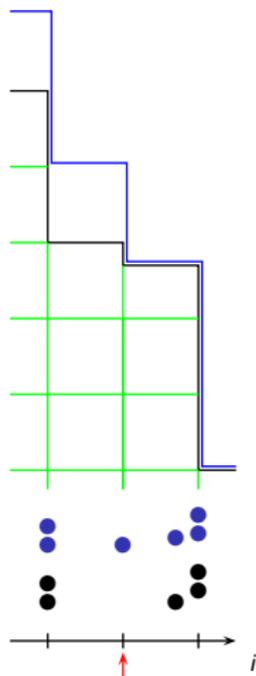
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



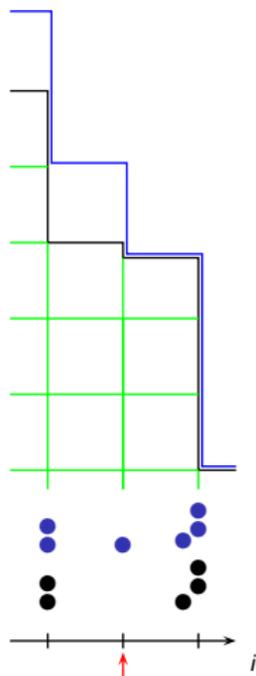
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



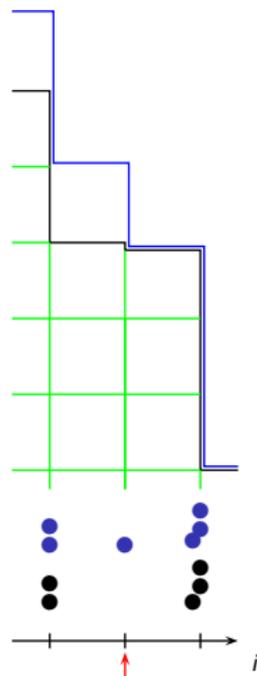
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



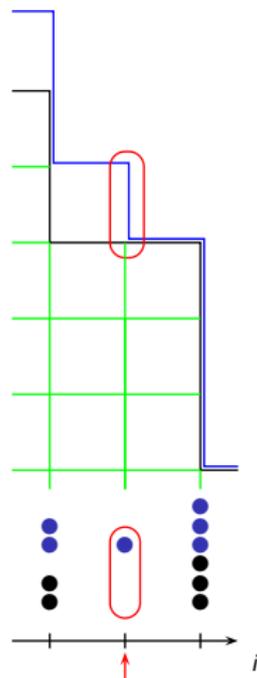
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



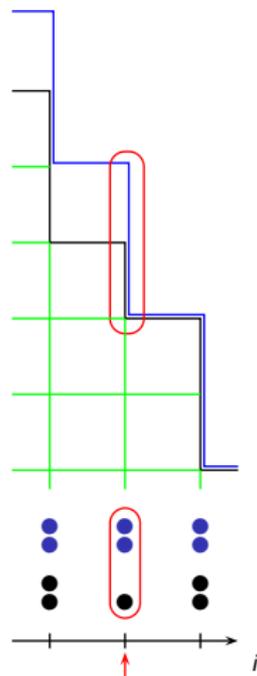
Growth on the right:

rate \leq rate

with rate:

The second class particle: attractive case

States ω and ω' only differ at one site.



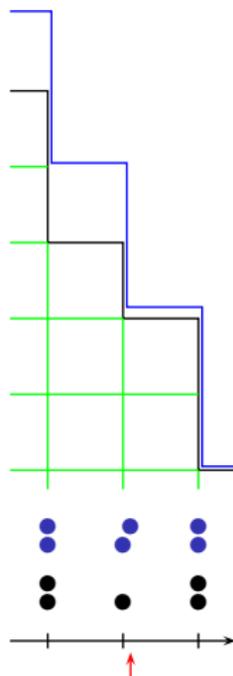
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

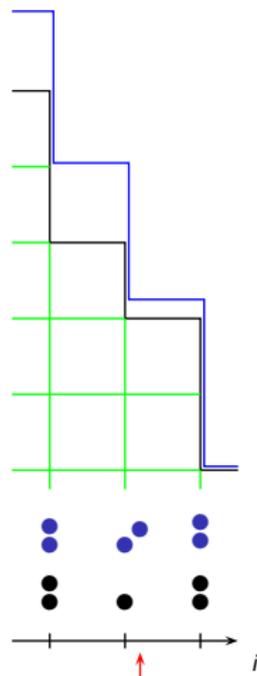
States ω and $\tilde{\omega}$ only differ at one site.



Growth on the right:
 $\text{rate} \leq \text{rate}$
 with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



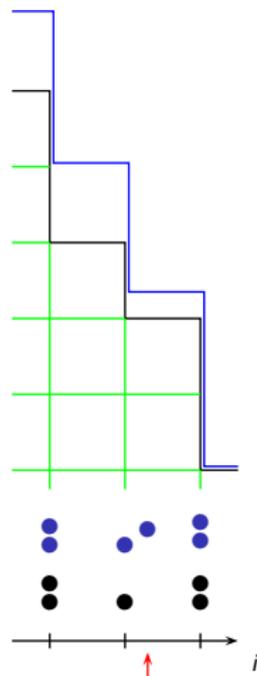
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



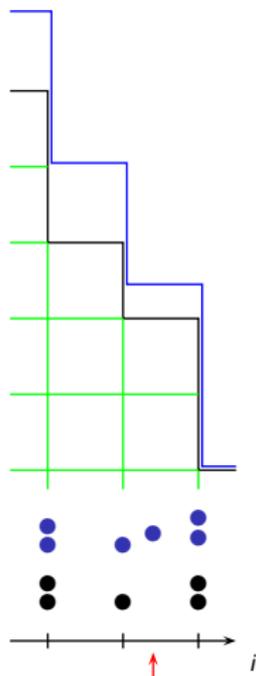
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



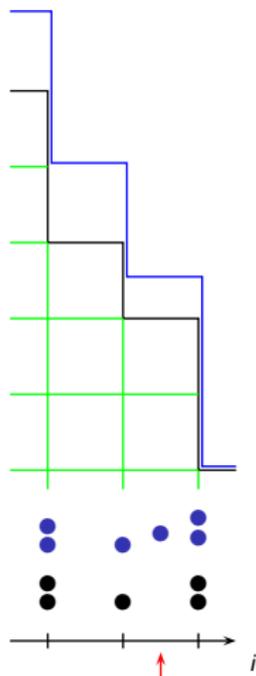
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

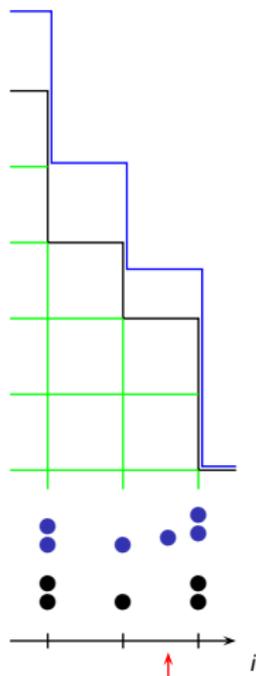
States ω and $\tilde{\omega}$ only differ at one site.



Growth on the right:
 $\text{rate} \leq \text{rate}$
 with $\text{rate} - \text{rate}$:

The second class particle: attractive case

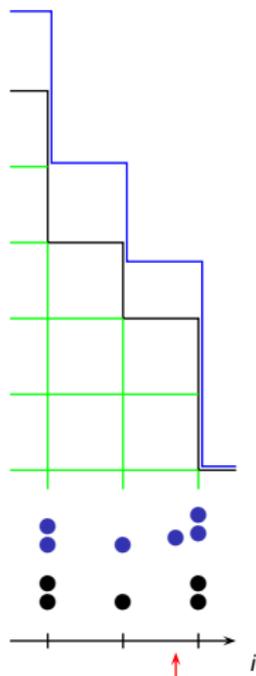
States ω and $\tilde{\omega}$ only differ at one site.



Growth on the right:
 $\text{rate} \leq \text{rate}$
 with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



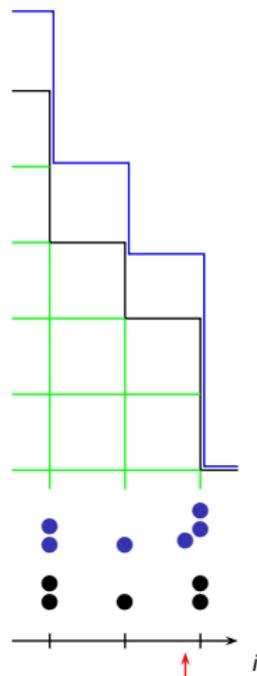
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



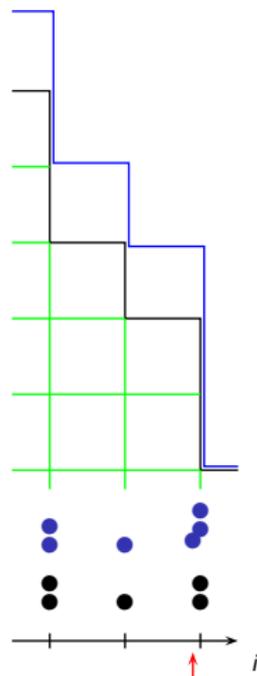
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



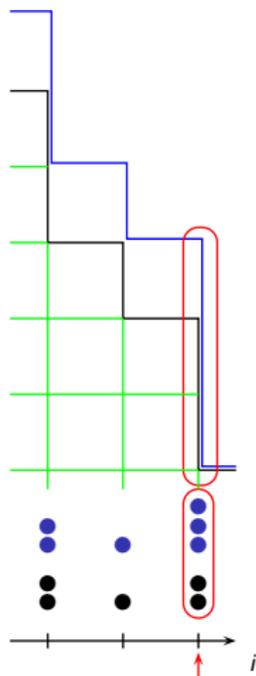
Growth on the right:

$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.



Growth on the right:

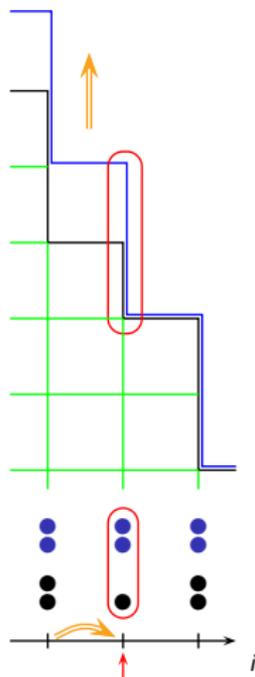
$\text{rate} \leq \text{rate}$

with $\text{rate} - \text{rate}$:

The second class particle: attractive case

States ω and ω' only differ at one site.

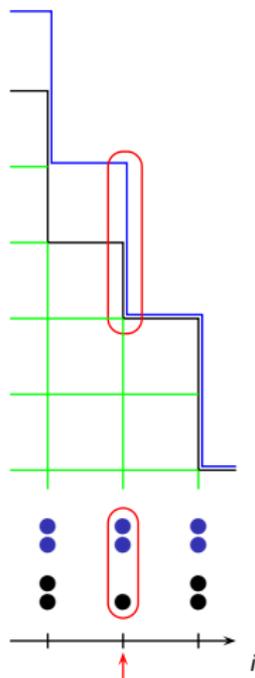
Growth on the left:
rate \geq rate



The second class particle: attractive case

States ω and ω' only differ at one site.

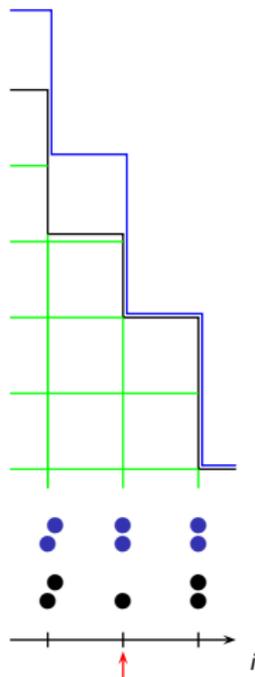
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

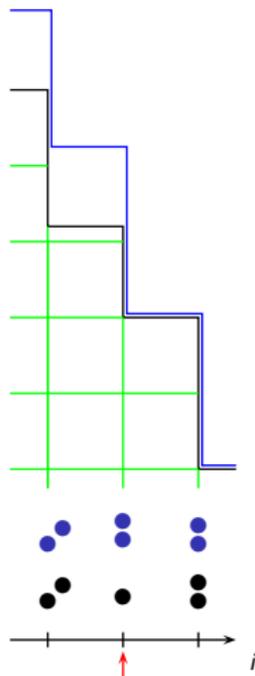
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

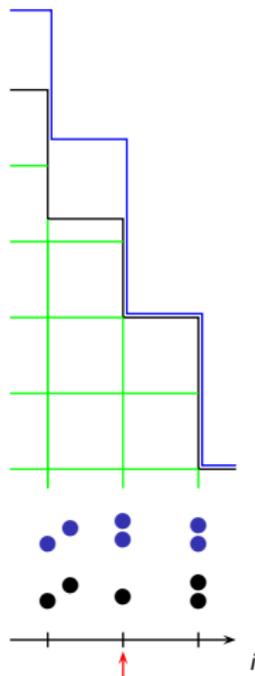
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

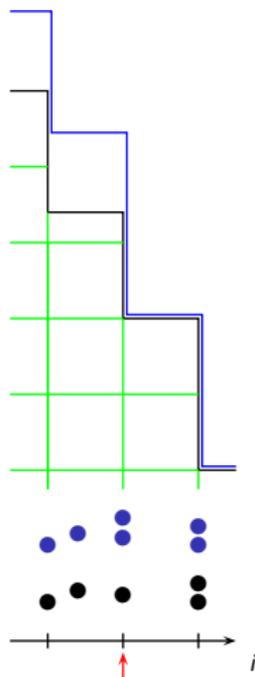
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

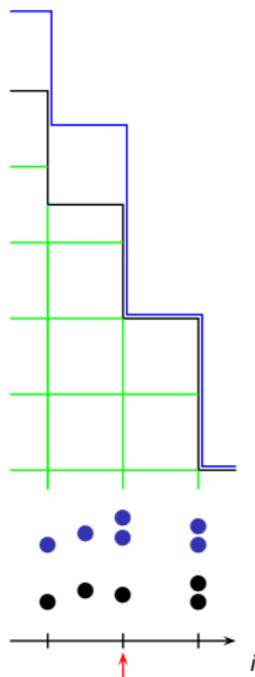
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

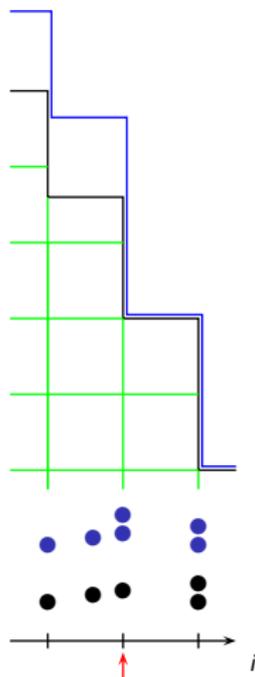
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

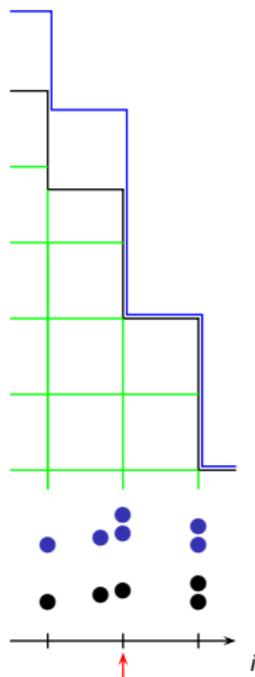
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

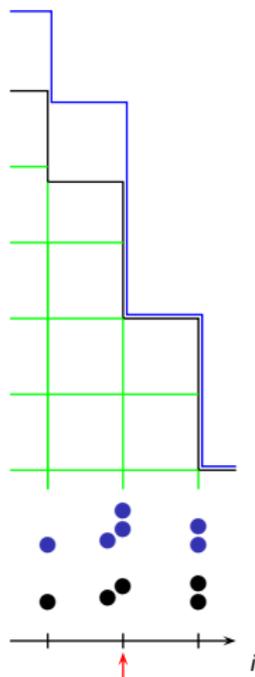
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

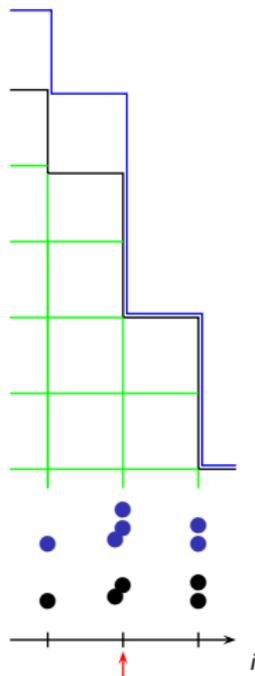
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

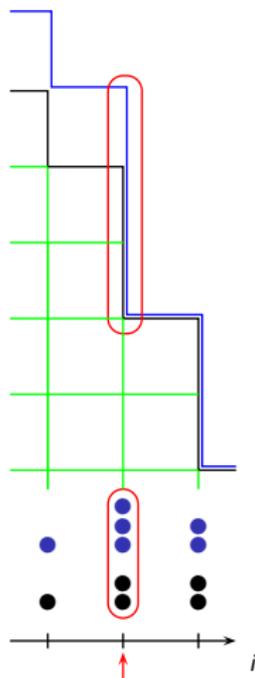
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

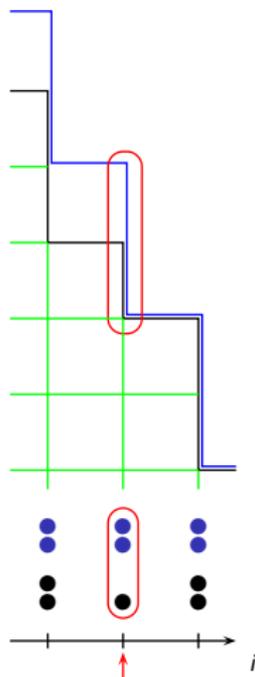
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with rate :



The second class particle: attractive case

States ω and ω' only differ at one site.

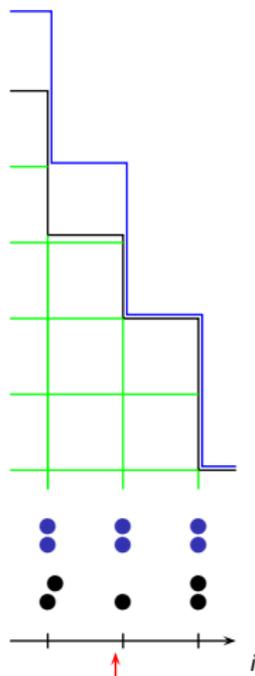
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

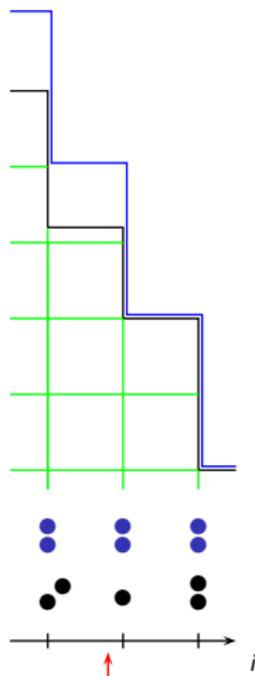
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

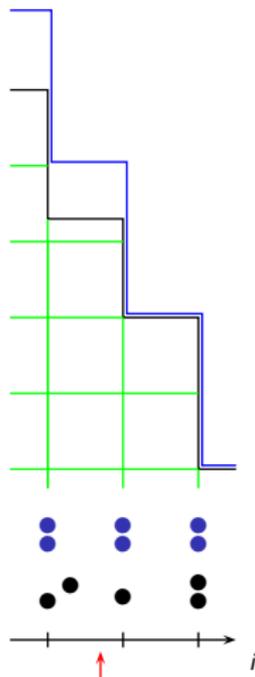
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and ω' only differ at one site.

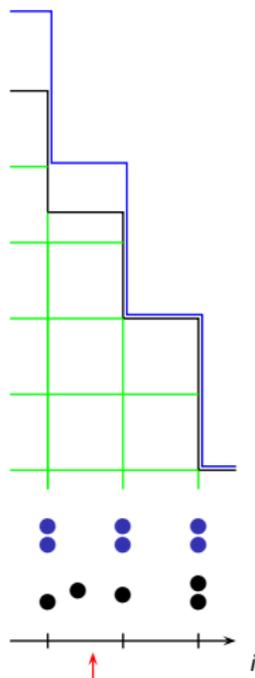
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

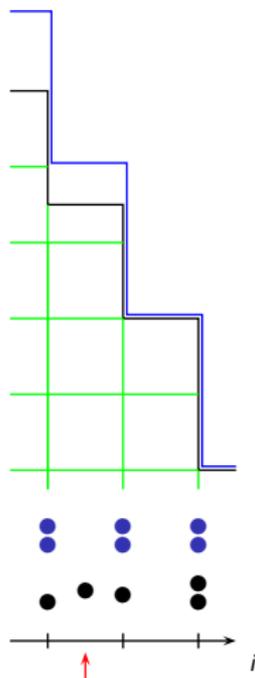
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

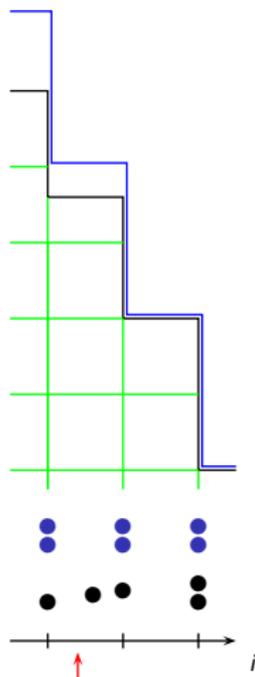
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

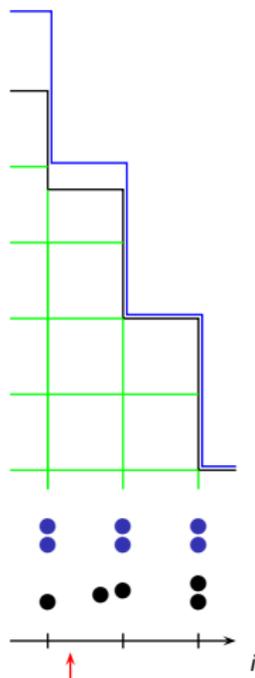
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

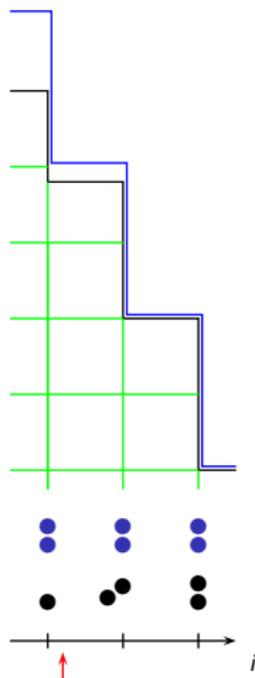
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

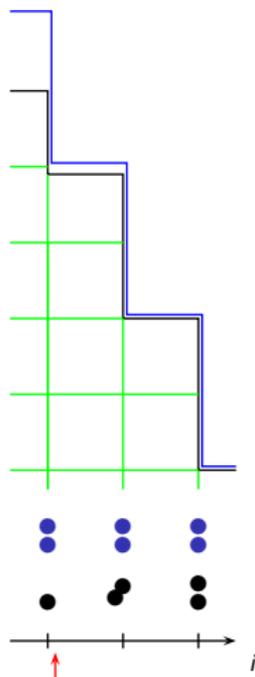
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and $\tilde{\omega}$ only differ at one site.

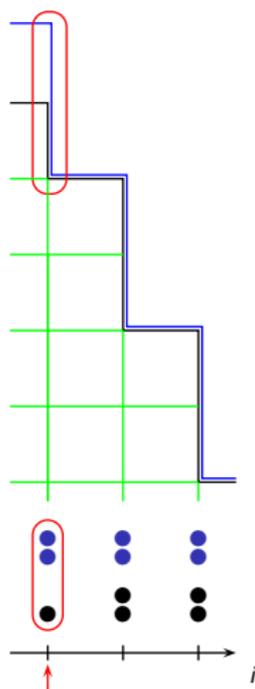
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

States ω and ω' only differ at one site.

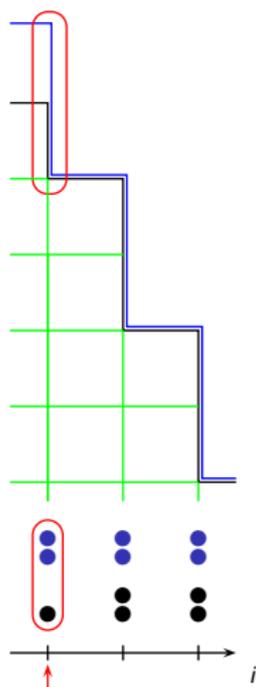
Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:



The second class particle: attractive case

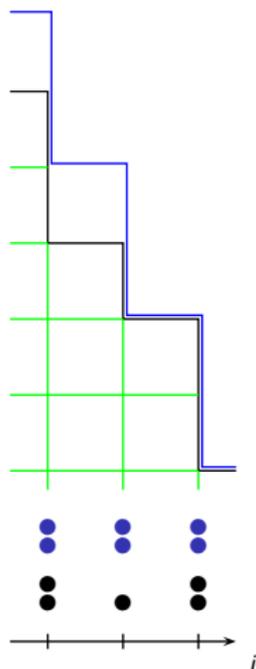
States ω and ω' only differ at one site.

Growth on the left:
 $\text{rate} \geq \text{rate}$
 with $\text{rate} - \text{rate}$:

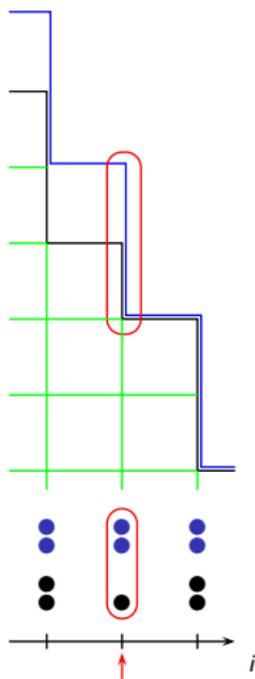


A single discrepancy \uparrow , the *second class particle*, is conserved.

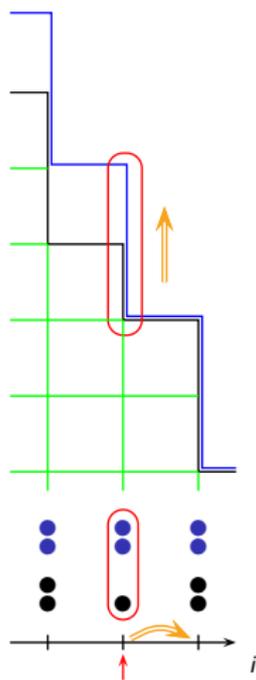
The second class particle: non-attractive case



The second class particle: non-attractive case

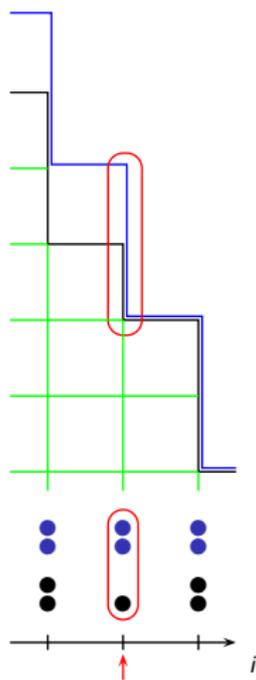


The second class particle: non-attractive case



Growth on the right:
 $\text{rate} > \text{rate}$

The second class particle: non-attractive case

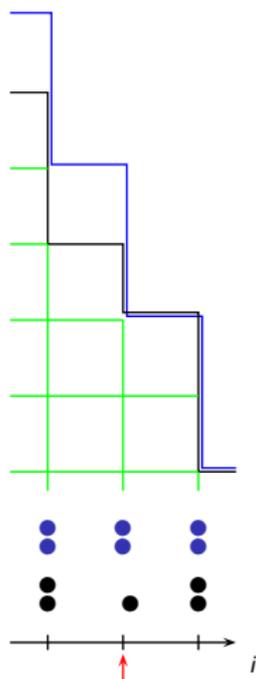


Growth on the right:

rate $>$ rate

rate-rate:

The second class particle: non-attractive case

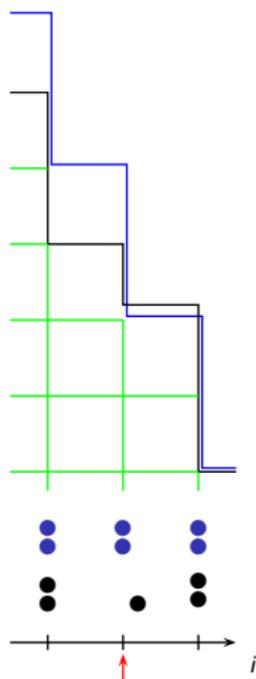


Growth on the right:

$\text{rate} > \text{rate}$

$\text{rate} - \text{rate}$:

The second class particle: non-attractive case

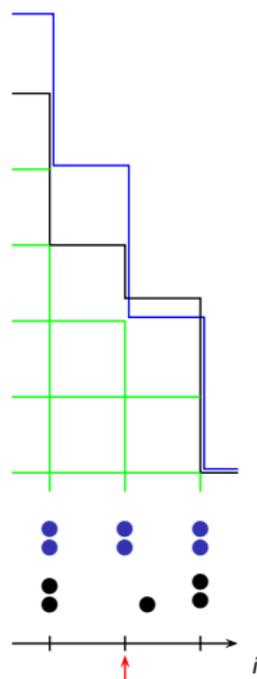


Growth on the right:

rate $>$ rate

rate - rate:

The second class particle: non-attractive case

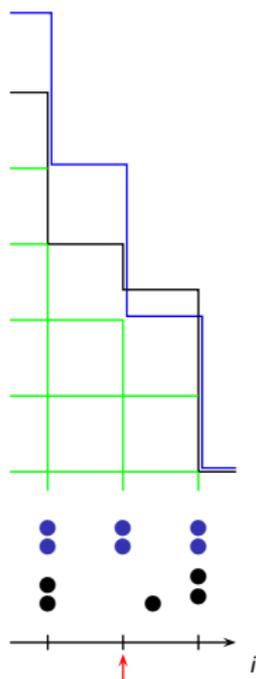


Growth on the right:

rate $>$ rate

rate - rate:

The second class particle: non-attractive case

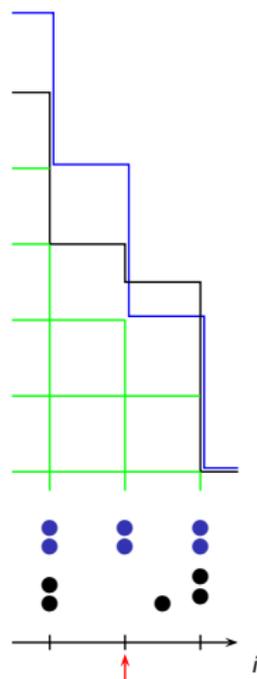


Growth on the right:

rate $>$ rate

rate - rate:

The second class particle: non-attractive case

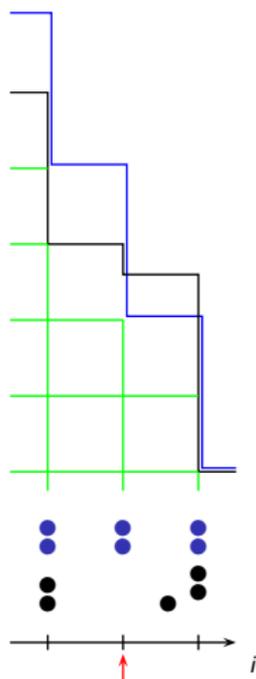


Growth on the right:

rate $>$ rate

rate - rate:

The second class particle: non-attractive case

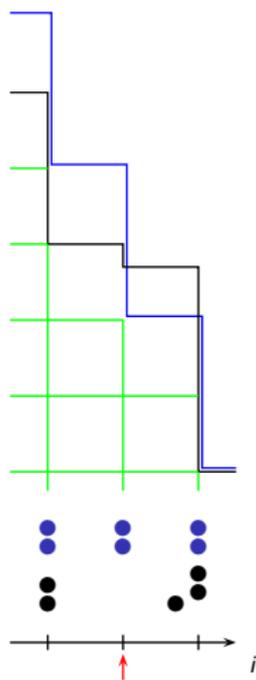


Growth on the right:

rate $>$ rate

rate - rate:

The second class particle: non-attractive case

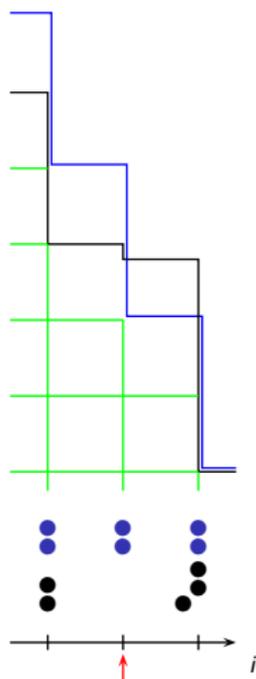


Growth on the right:

rate $>$ rate

rate - rate:

The second class particle: non-attractive case

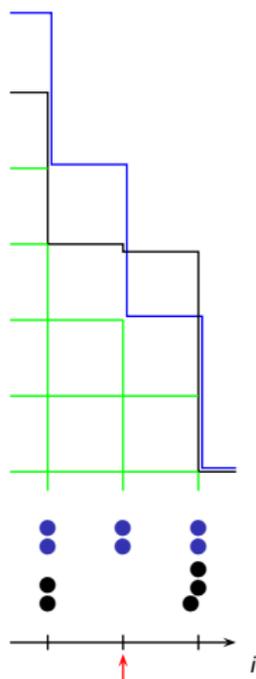


Growth on the right:

$\text{rate} > \text{rate}$

$\text{rate} - \text{rate}:$

The second class particle: non-attractive case

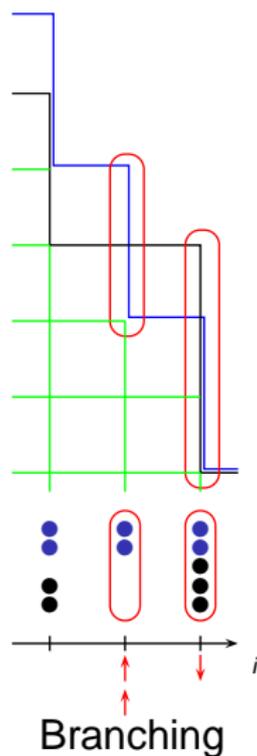


Growth on the right:

rate $>$ rate

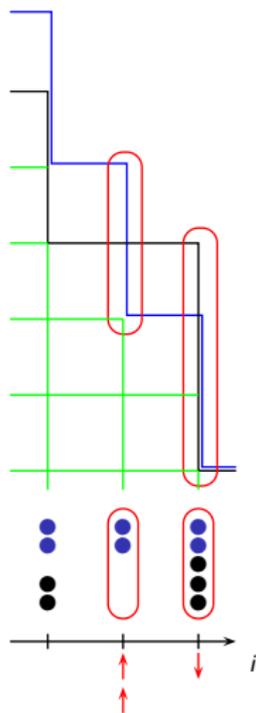
rate - rate:

The second class particle: non-attractive case

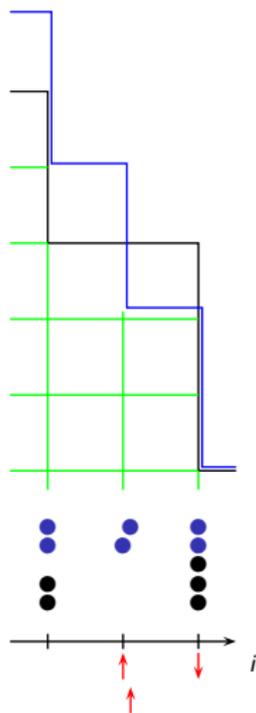


Growth on the right:
 $\text{rate} > \text{rate}$
 $\text{rate} - \text{rate}:$

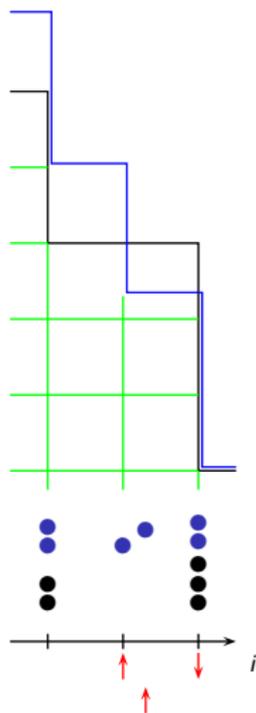
The second class particle: non-attractive case



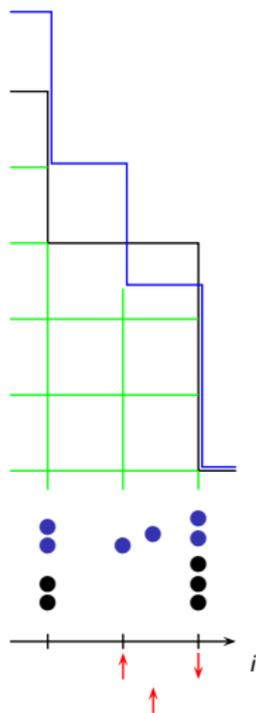
The second class particle: non-attractive case



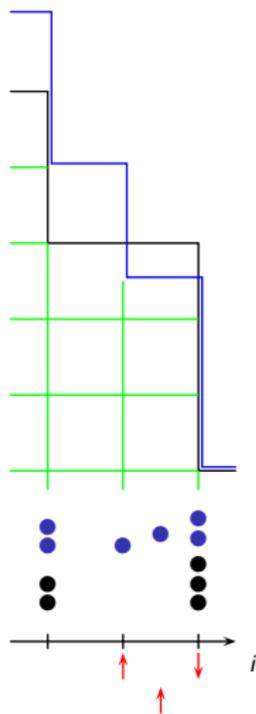
The second class particle: non-attractive case



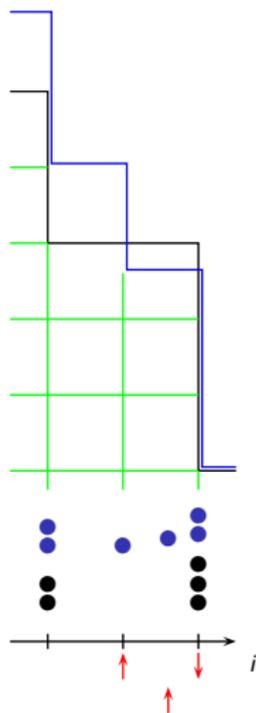
The second class particle: non-attractive case



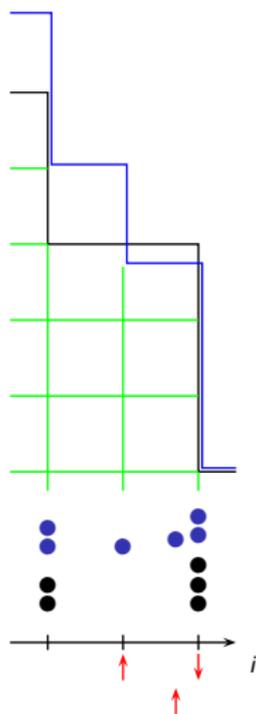
The second class particle: non-attractive case



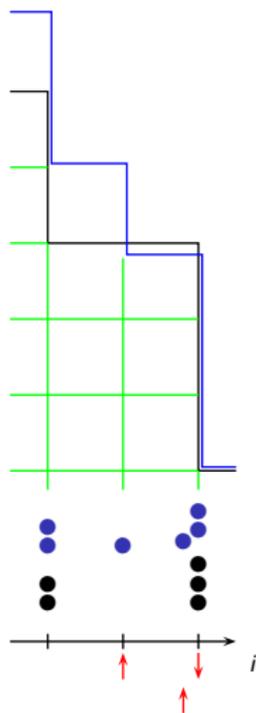
The second class particle: non-attractive case



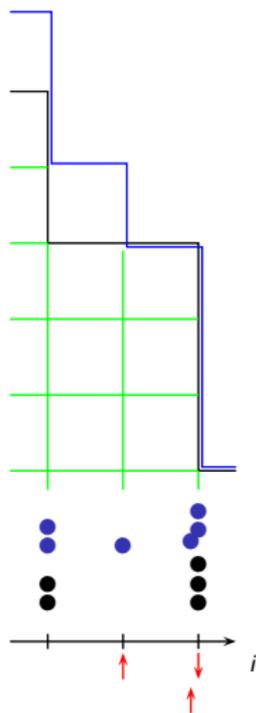
The second class particle: non-attractive case



The second class particle: non-attractive case

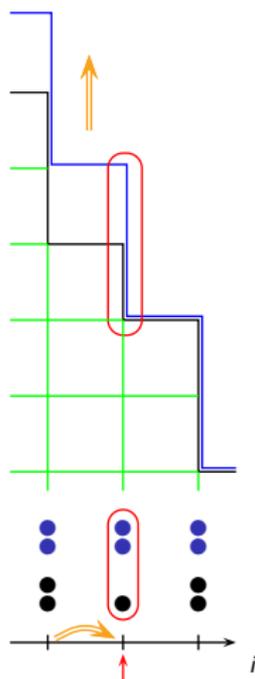


The second class particle: non-attractive case



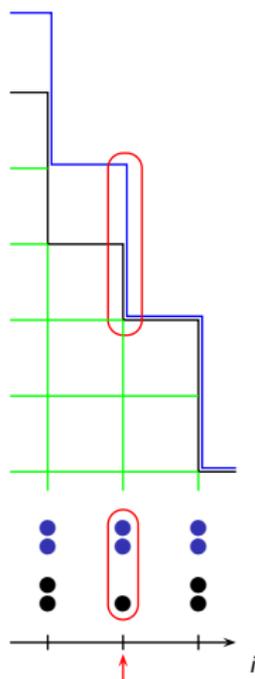
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$



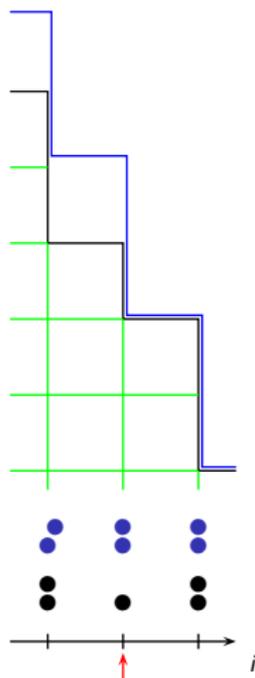
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



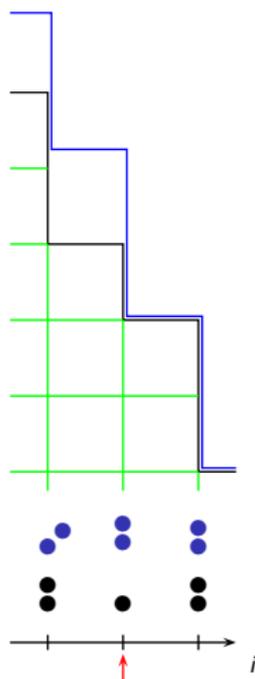
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



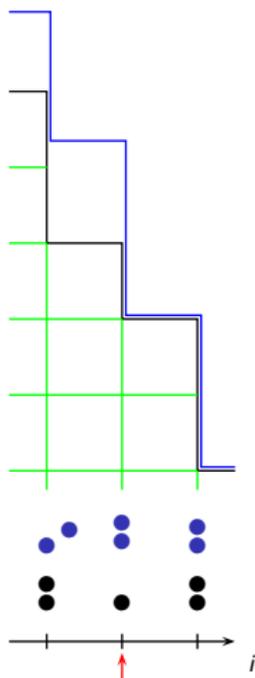
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



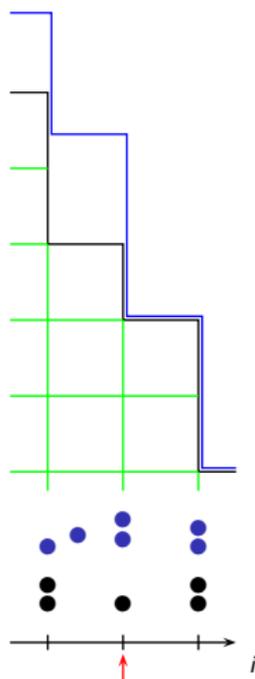
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



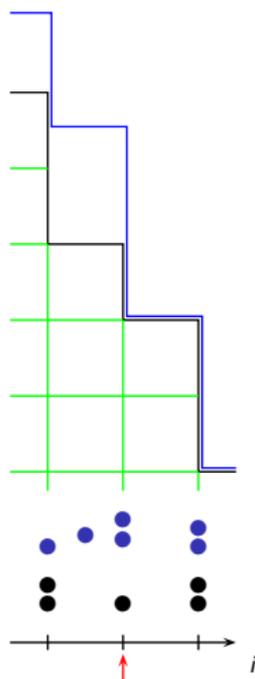
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



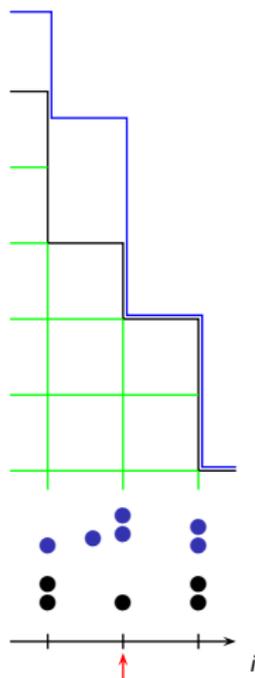
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



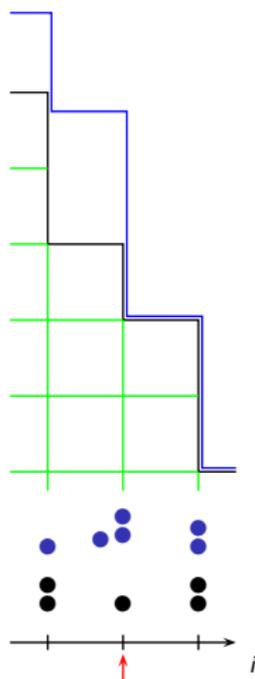
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



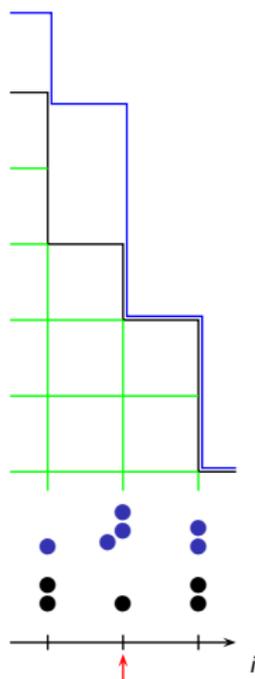
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



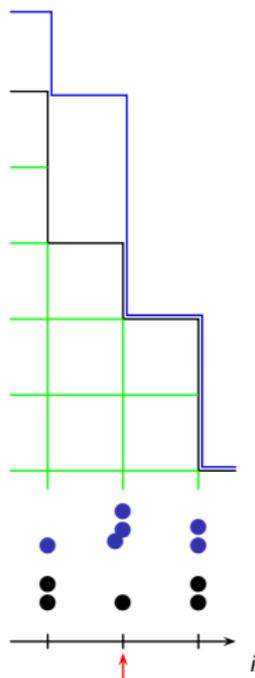
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



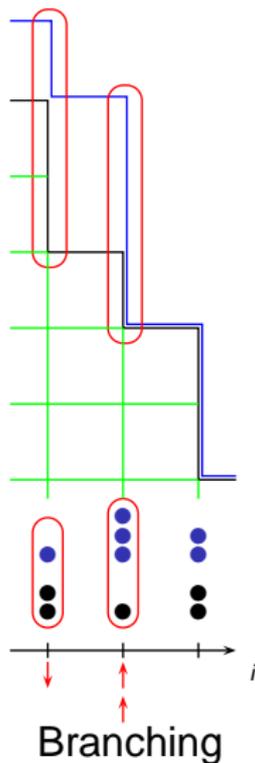
The second class particle: non-attractive case

Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:

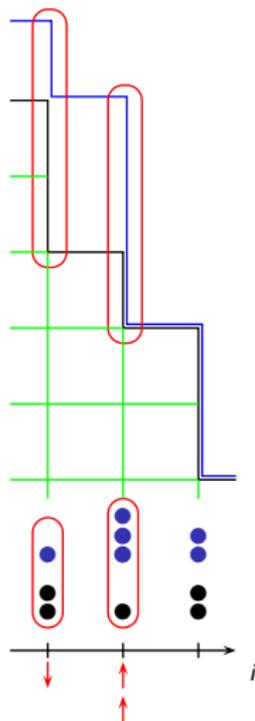


The second class particle: non-attractive case

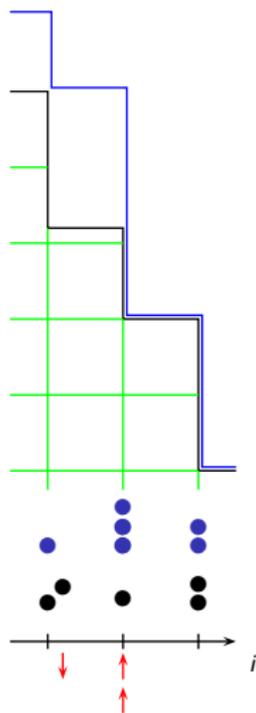
Growth on the left:
 $\text{rate} < \text{rate}$
 with $\text{rate} - \text{rate}$:



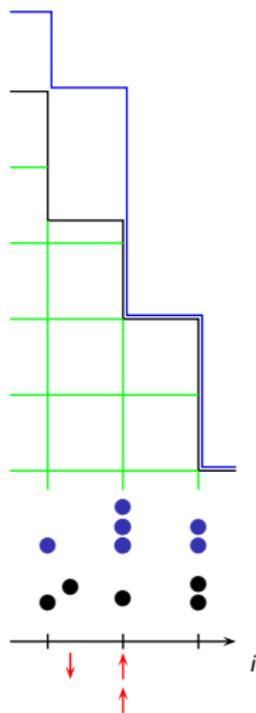
The second class particle: non-attractive case



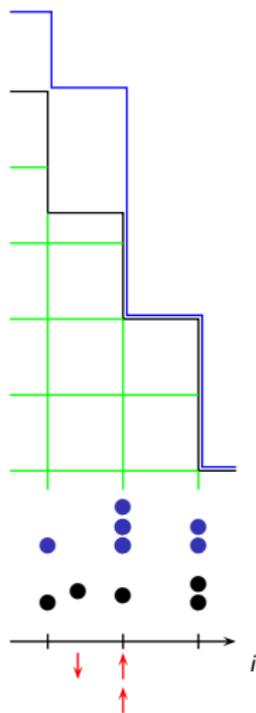
The second class particle: non-attractive case



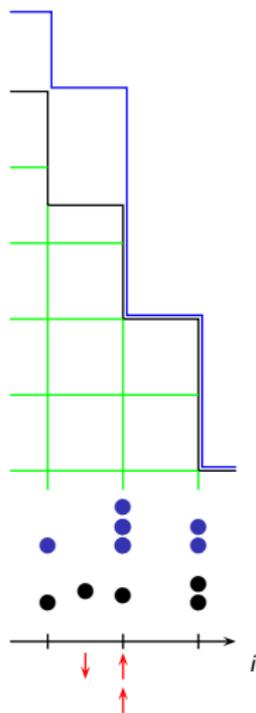
The second class particle: non-attractive case



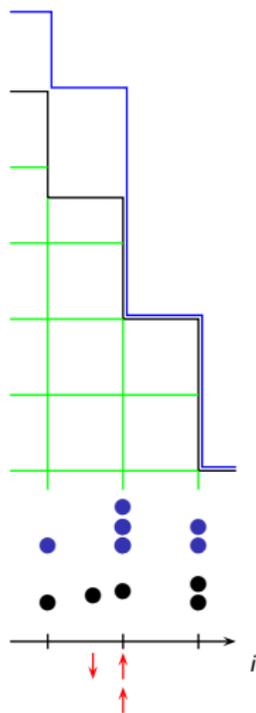
The second class particle: non-attractive case



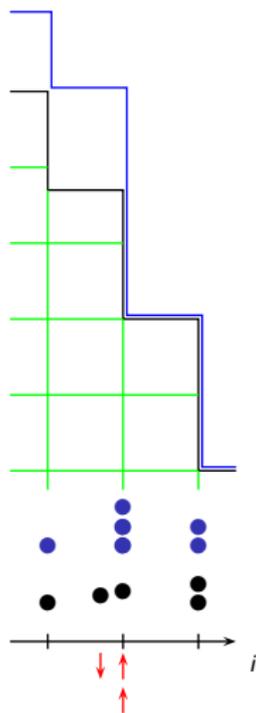
The second class particle: non-attractive case



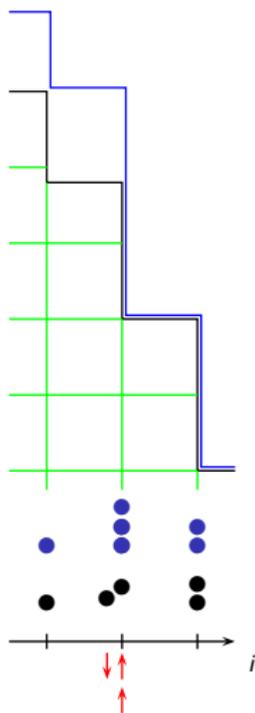
The second class particle: non-attractive case



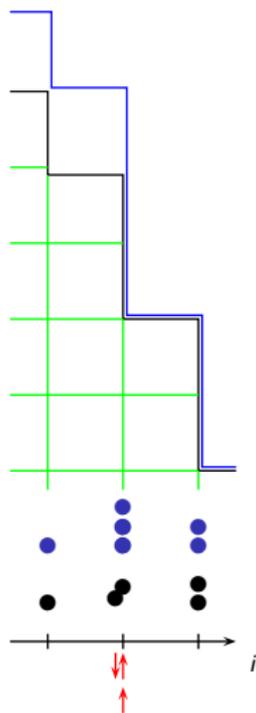
The second class particle: non-attractive case



The second class particle: non-attractive case



The second class particle: non-attractive case



On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\frac{d}{dt} \rho_i = \frac{d}{dt} \mathbf{E} \omega_i$$

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\begin{aligned} \frac{d}{dt} \rho_i &= \frac{d}{dt} \mathbf{E} \omega_i \\ &= \lim_{t \rightarrow 0} \frac{\mathbf{P}\{\omega_{i-1} = 1, \omega_i = 0\}t - \mathbf{P}\{\omega_i = 1, \omega_{i+1} = 0\}t + o(t)}{t} \end{aligned}$$

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\begin{aligned} \frac{d}{dt} \varrho_i &= \frac{d}{dt} \mathbf{E} \omega_i \\ &= \lim_{t \rightarrow 0} \frac{\mathbf{P}\{\omega_{i-1} = 1, \omega_i = 0\}t - \mathbf{P}\{\omega_i = 1, \omega_{i+1} = 0\}t + o(t)}{t} \\ &= \varrho_{i-1}[1 - \varrho_i] - \varrho_i[1 - \varrho_{i+1}]. \end{aligned}$$

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\begin{aligned} \frac{d}{dt} \varrho_i &= \frac{d}{dt} \mathbf{E} \omega_i \\ &= \lim_{t \rightarrow 0} \frac{\mathbf{P}\{\omega_{i-1} = 1, \omega_i = 0\}t - \mathbf{P}\{\omega_i = 1, \omega_{i+1} = 0\}t + o(t)}{t} \\ &= \varrho_{i-1}[1 - \varrho_i] - \varrho_i[1 - \varrho_{i+1}]. \end{aligned}$$

Define now $T = t \cdot \varepsilon$, $X = i \cdot \varepsilon$, $\hat{\varrho}(T, X) = \varrho_i(t) = \varrho_{\frac{X}{\varepsilon}}\left(\frac{T}{\varepsilon}\right)$.

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\begin{aligned} \frac{d}{dt} \varrho_i &= \frac{d}{dt} \mathbf{E} \omega_i \\ &= \lim_{t \rightarrow 0} \frac{\mathbf{P}\{\omega_{i-1} = 1, \omega_i = 0\}t - \mathbf{P}\{\omega_i = 1, \omega_{i+1} = 0\}t + o(t)}{t} \\ &= \varrho_{i-1}[1 - \varrho_i] - \varrho_i[1 - \varrho_{i+1}]. \end{aligned}$$

Define now $T = t \cdot \varepsilon$, $X = i \cdot \varepsilon$, $\hat{\varrho}(T, X) = \varrho_i(t) = \varrho_{\frac{X}{\varepsilon}}\left(\frac{T}{\varepsilon}\right)$.

$$\varepsilon \frac{\partial}{\partial T} \hat{\varrho} = \hat{\varrho}(T, X - \varepsilon)[1 - \hat{\varrho}(T, X)] - \hat{\varrho}(T, X)[1 - \hat{\varrho}(T, X + \varepsilon)]$$

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\begin{aligned} \frac{d}{dt} \varrho_i &= \frac{d}{dt} \mathbf{E} \omega_i \\ &= \lim_{t \rightarrow 0} \frac{\mathbf{P}\{\omega_{i-1} = 1, \omega_i = 0\}t - \mathbf{P}\{\omega_i = 1, \omega_{i+1} = 0\}t + o(t)}{t} \\ &= \varrho_{i-1}[1 - \varrho_i] - \varrho_i[1 - \varrho_{i+1}]. \end{aligned}$$

Define now $T = t \cdot \varepsilon$, $X = i \cdot \varepsilon$, $\hat{\varrho}(T, X) = \varrho_i(t) = \varrho_{\frac{X}{\varepsilon}}\left(\frac{T}{\varepsilon}\right)$.

$$\varepsilon \frac{\partial}{\partial T} \hat{\varrho} = \hat{\varrho}(T, X - \varepsilon)[1 - \hat{\varrho}(T, X)] - \hat{\varrho}(T, X)[1 - \hat{\varrho}(T, X + \varepsilon)]$$

$$\frac{\partial}{\partial T} \hat{\varrho} = \frac{\hat{\varrho}(T, X - \varepsilon)[1 - \hat{\varrho}(T, X)] - \hat{\varrho}(T, X)[1 - \hat{\varrho}(T, X + \varepsilon)]}{\varepsilon}$$

On large scales

Let us now allow the density to change slowly in space. The change of density at position i :

$$\begin{aligned} \frac{d}{dt} \varrho_i &= \frac{d}{dt} \mathbf{E} \omega_i \\ &= \lim_{t \rightarrow 0} \frac{\mathbf{P}\{\omega_{i-1} = 1, \omega_i = 0\}t - \mathbf{P}\{\omega_i = 1, \omega_{i+1} = 0\}t + o(t)}{t} \\ &= \varrho_{i-1}[1 - \varrho_i] - \varrho_i[1 - \varrho_{i+1}]. \end{aligned}$$

Define now $T = t \cdot \varepsilon$, $X = i \cdot \varepsilon$, $\hat{\varrho}(T, X) = \varrho_i(t) = \varrho_{\frac{X}{\varepsilon}}\left(\frac{T}{\varepsilon}\right)$.

$$\varepsilon \frac{\partial}{\partial T} \hat{\varrho} = \hat{\varrho}(T, X - \varepsilon)[1 - \hat{\varrho}(T, X)] - \hat{\varrho}(T, X)[1 - \hat{\varrho}(T, X + \varepsilon)]$$

$$\frac{\partial}{\partial T} \hat{\varrho} = \frac{\hat{\varrho}(T, X - \varepsilon)[1 - \hat{\varrho}(T, X)] - \hat{\varrho}(T, X)[1 - \hat{\varrho}(T, X + \varepsilon)]}{\varepsilon}$$

$$\frac{\partial}{\partial T} \hat{\varrho} + \frac{\partial}{\partial X} [\hat{\varrho}(1 - \hat{\varrho})] = 0 \quad (\text{Burgers eq.}).$$

Burgers eq.: characteristics

$$\frac{\partial}{\partial T} \hat{\rho} + \frac{\partial}{\partial X} [\hat{\rho}(1 - \hat{\rho})] = 0 \quad \text{Burgers eq.: nonlinear PDE.}$$

Burgers eq.: characteristics

$$\frac{\partial}{\partial T} \hat{\rho} + \frac{\partial}{\partial X} [\hat{\rho}(1 - \hat{\rho})] = 0 \quad \text{Burgers eq.: nonlinear PDE.}$$

Characteristics: find a path $X(T)$ where $\hat{\rho}(T, X(T))$ is a constant:

$$\frac{d}{dT} \hat{\rho}(T, X(T)) = 0$$

Burgers eq.: characteristics

$$\frac{\partial}{\partial T} \hat{\rho} + \frac{\partial}{\partial X} [\hat{\rho}(1 - \hat{\rho})] = 0 \quad \text{Burgers eq.: nonlinear PDE.}$$

Characteristics: find a path $X(T)$ where $\hat{\rho}(T, X(T))$ is a constant:

$$\begin{aligned} \frac{d}{dT} \hat{\rho}(T, X(T)) &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + \dot{X}(T) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \end{aligned}$$

Burgers eq.: characteristics

$$\frac{\partial}{\partial T} \hat{\rho} + \frac{\partial}{\partial X} [\hat{\rho}(1 - \hat{\rho})] = 0 \quad \text{Burgers eq.: nonlinear PDE.}$$

Characteristics: find a path $X(T)$ where $\hat{\rho}(T, X(T))$ is a constant:

$$\begin{aligned} \frac{d}{dT} \hat{\rho}(T, X(T)) &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + \dot{X}(T) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + (1 - 2\hat{\rho}) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \end{aligned}$$

Burgers eq.: characteristics

$$\frac{\partial}{\partial T} \hat{\rho} + \frac{\partial}{\partial X} [\hat{\rho}(1 - \hat{\rho})] = 0 \quad \text{Burgers eq.: nonlinear PDE.}$$

Characteristics: find a path $X(T)$ where $\hat{\rho}(T, X(T))$ is a constant:

$$\begin{aligned} \frac{d}{dT} \hat{\rho}(T, X(T)) &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + \dot{X}(T) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + (1 - 2\hat{\rho}) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \end{aligned}$$

The characteristic velocity: $\dot{X}(T) = 1 - 2\hat{\rho}$.

Burgers eq.: characteristics

$$\frac{\partial}{\partial T} \hat{\rho} + \frac{\partial}{\partial X} [\hat{\rho}(1 - \hat{\rho})] = 0 \quad \text{Burgers eq.: nonlinear PDE.}$$

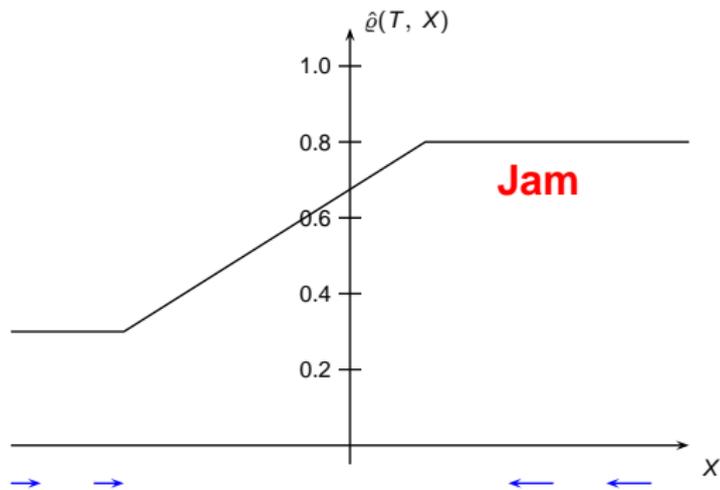
Characteristics: find a path $X(T)$ where $\hat{\rho}(T, X(T))$ is a constant:

$$\begin{aligned} \frac{d}{dT} \hat{\rho}(T, X(T)) &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + \dot{X}(T) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \\ \frac{\partial}{\partial T} \hat{\rho} + (1 - 2\hat{\rho}) \cdot \frac{\partial}{\partial X} \hat{\rho} &= 0 \end{aligned}$$

The characteristic velocity: $\dot{X}(T) = 1 - 2\hat{\rho}$.

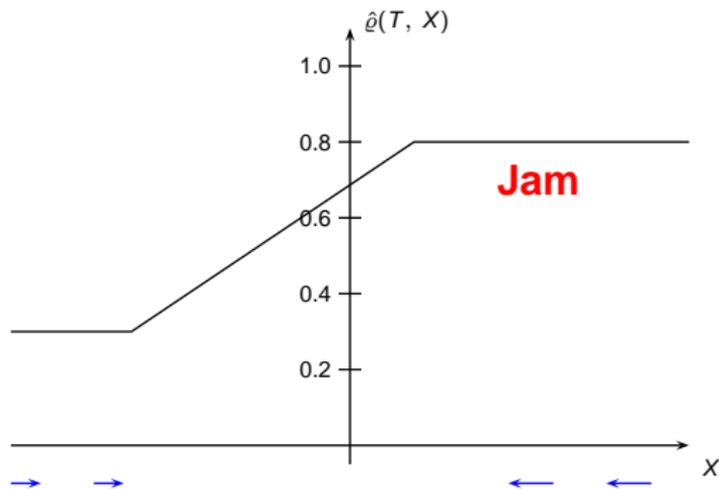
Second class particles are known to follow the characteristics.

On large scales



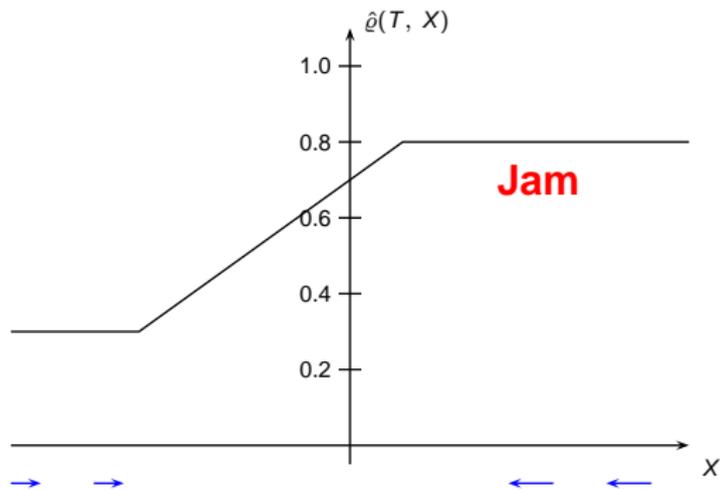
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



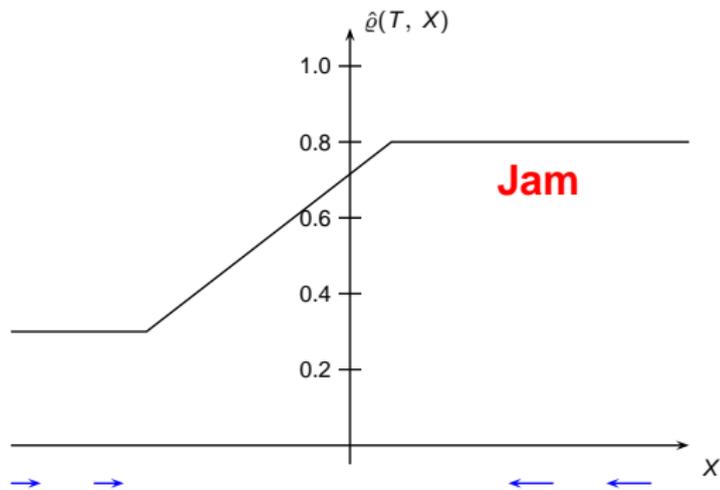
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



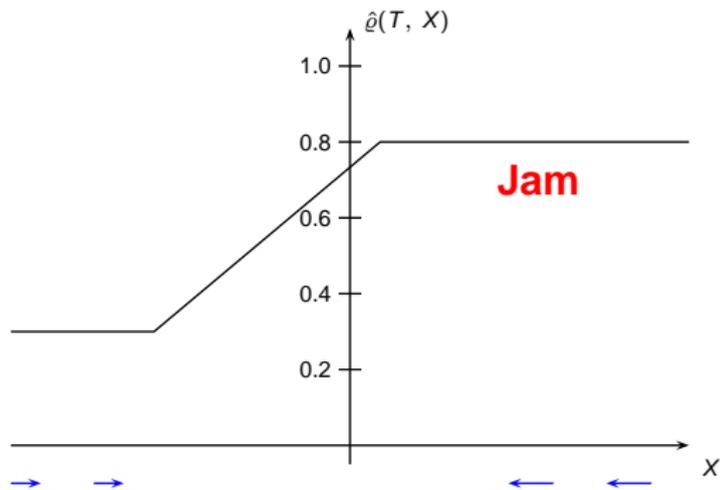
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



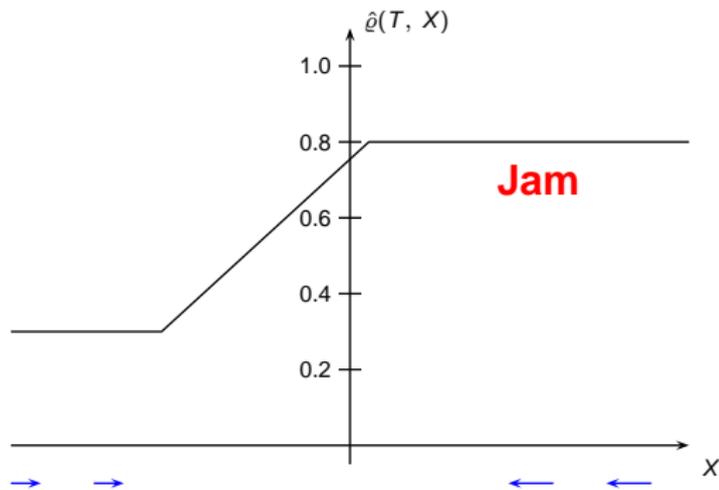
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



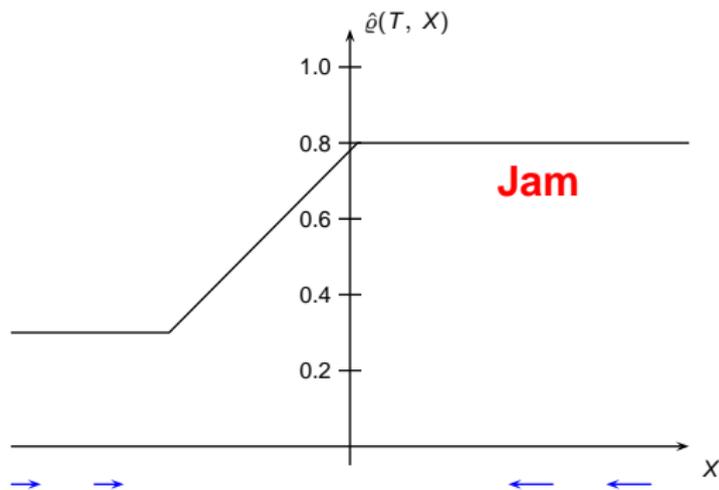
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



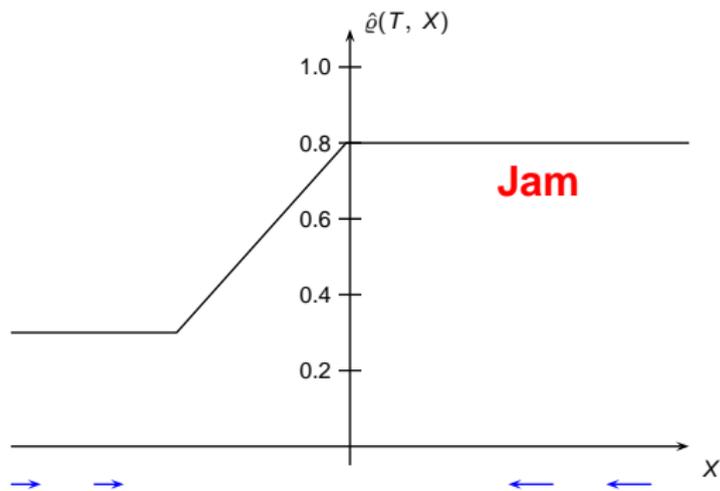
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



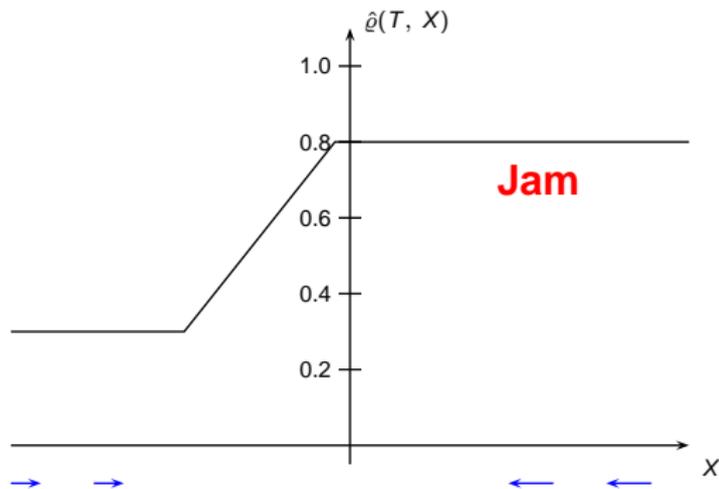
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



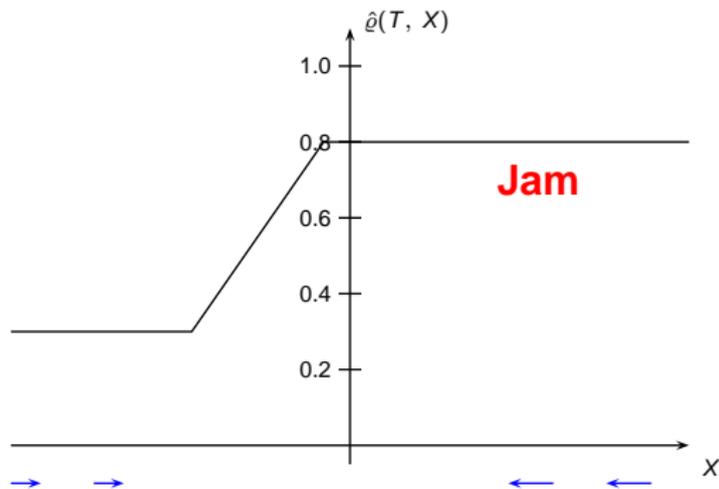
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



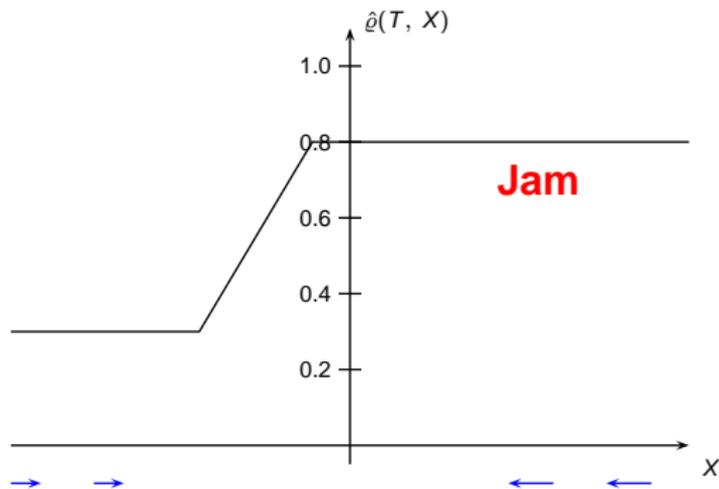
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



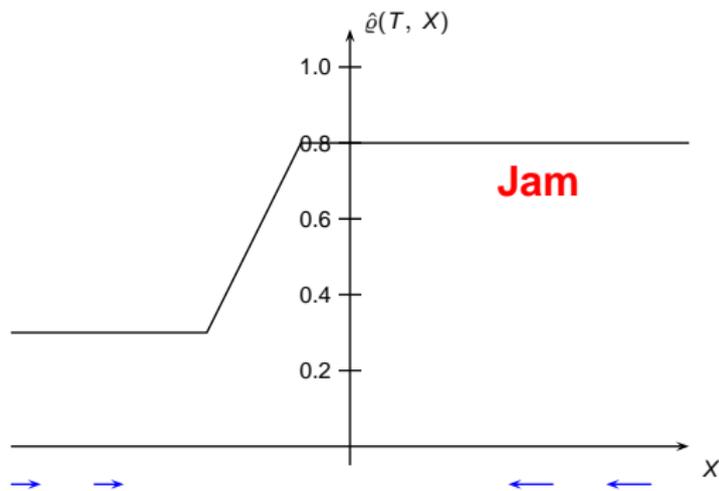
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



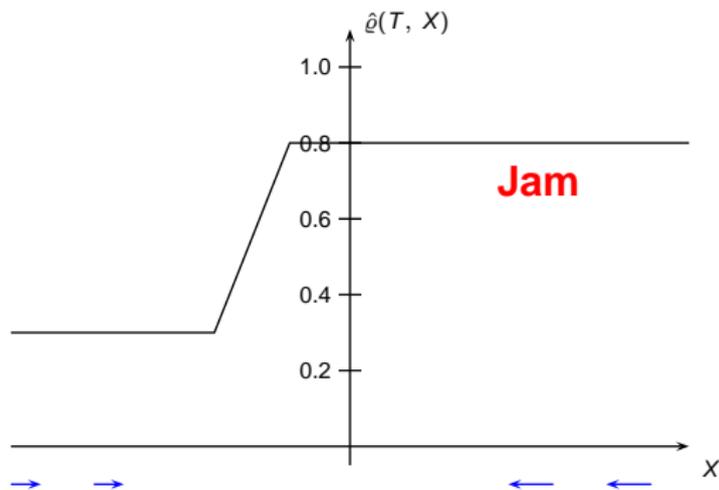
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



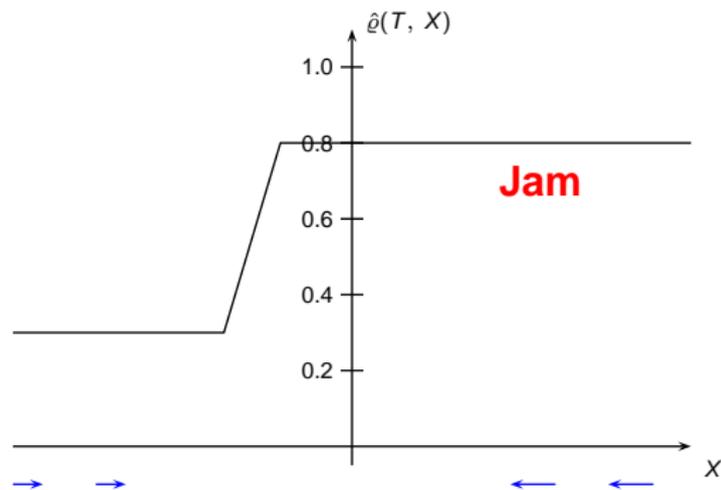
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



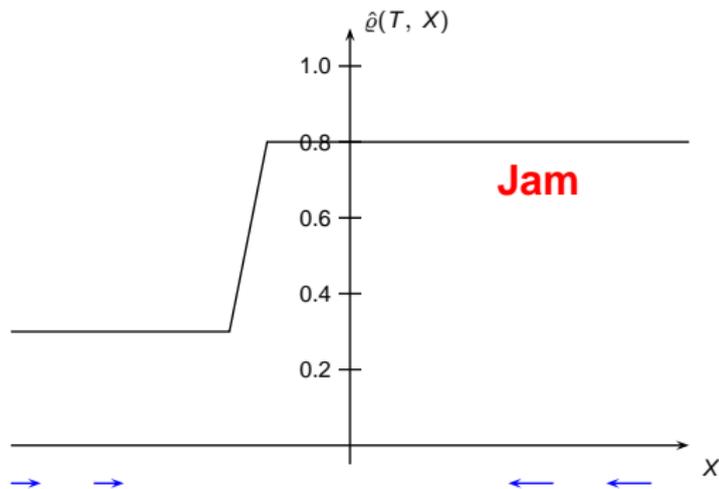
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



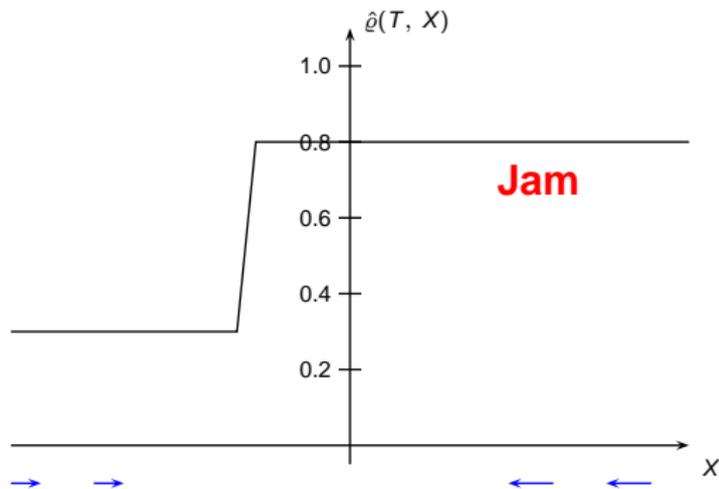
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



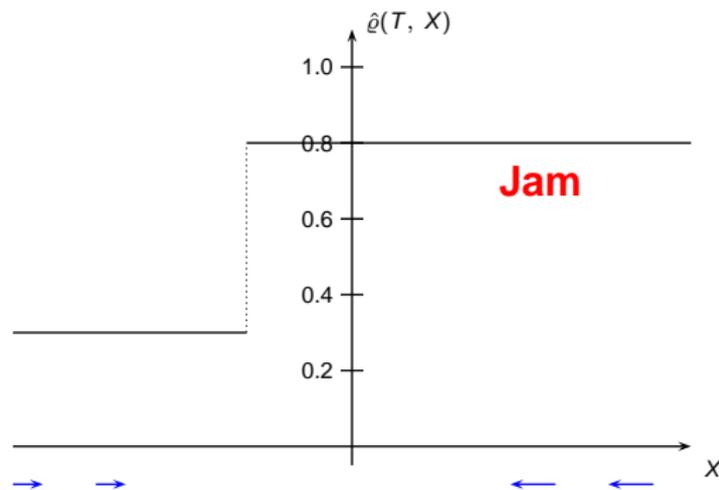
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



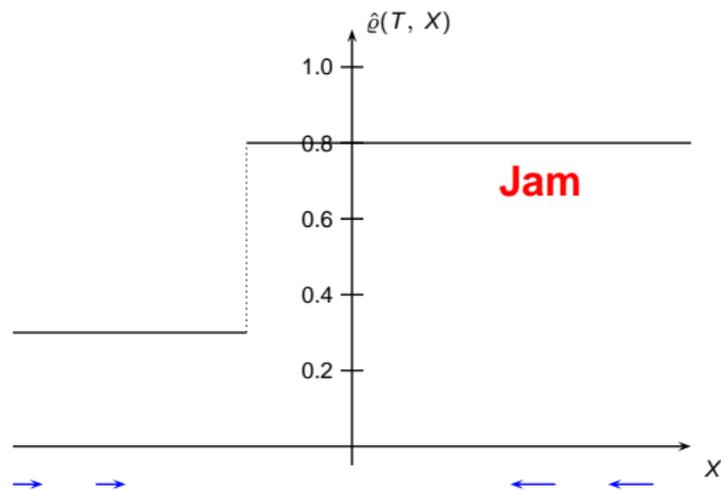
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



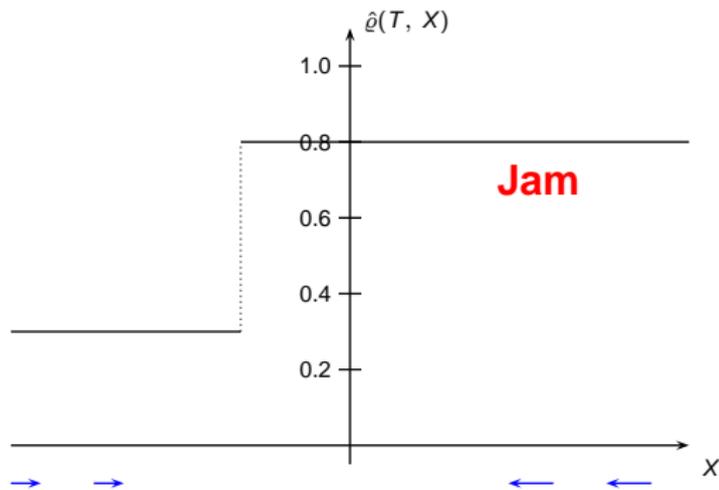
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



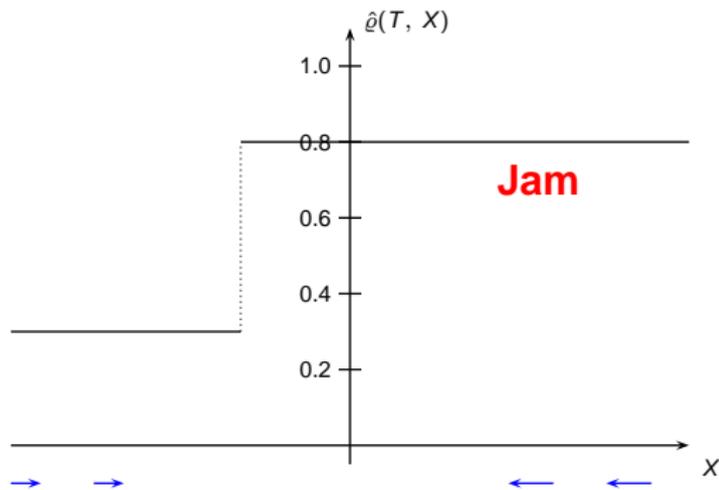
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



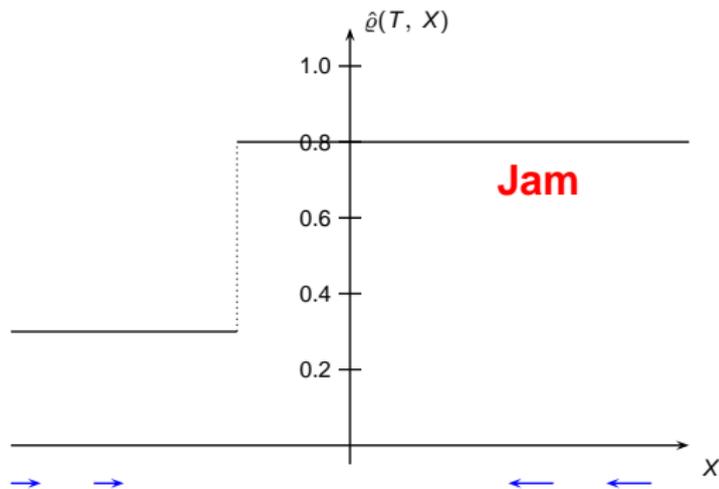
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



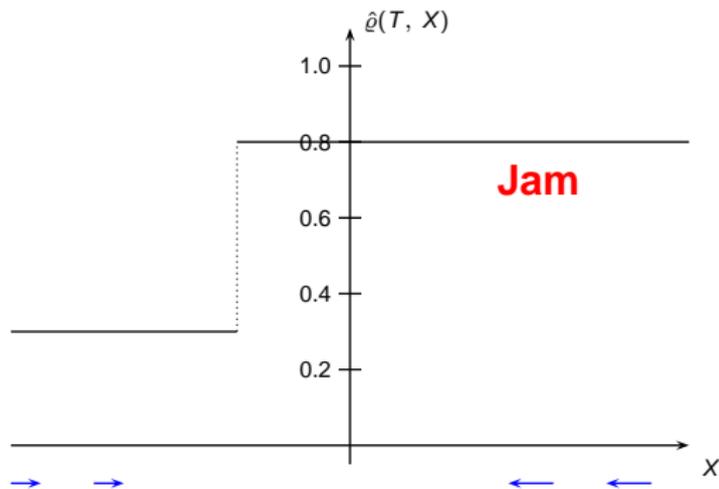
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



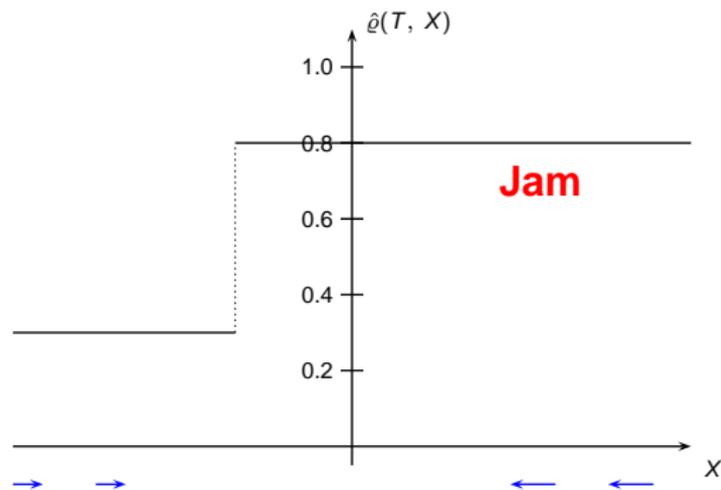
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



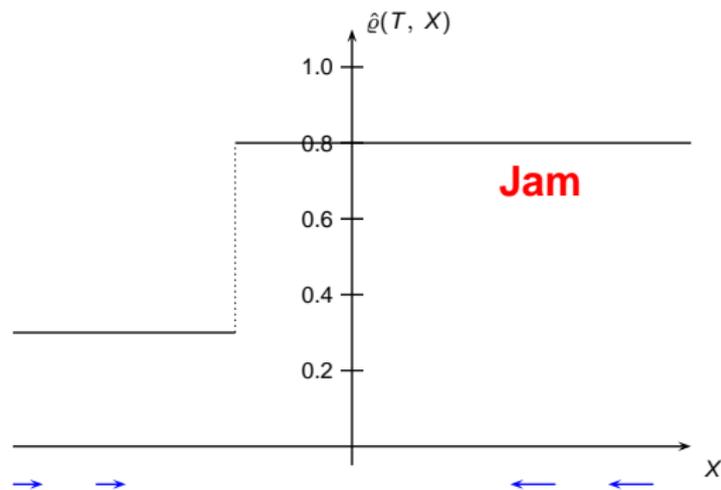
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



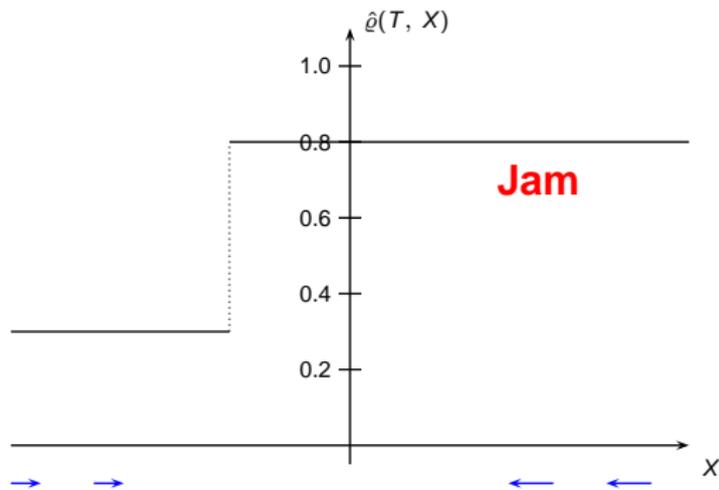
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



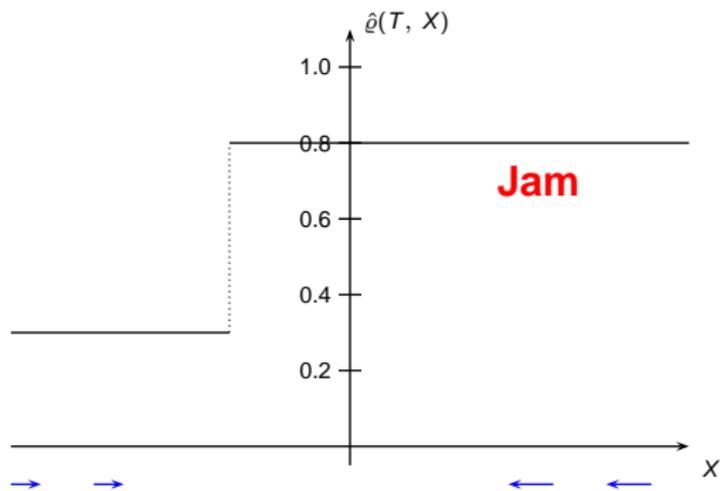
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



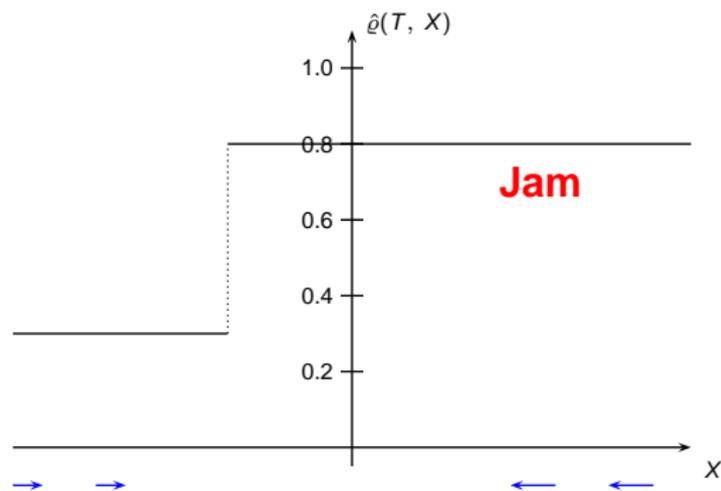
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



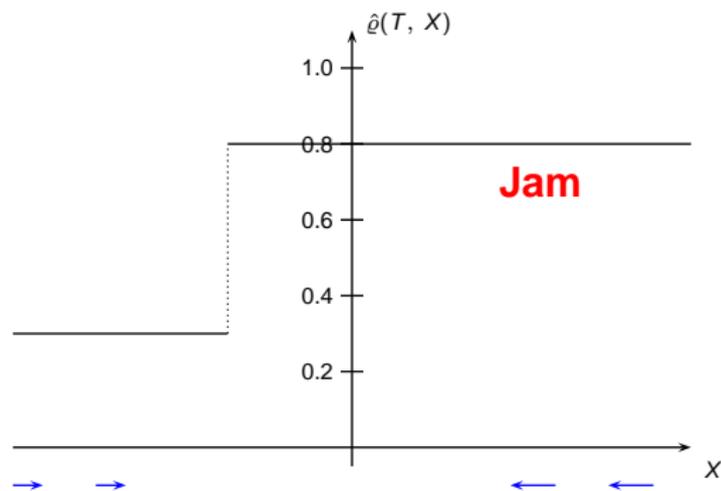
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



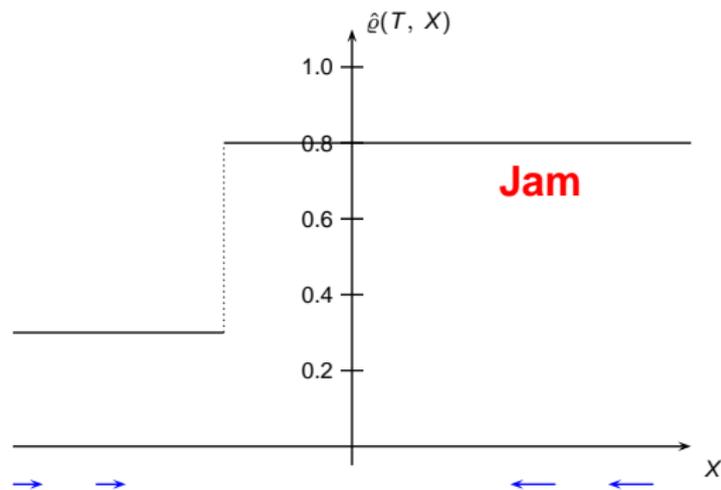
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



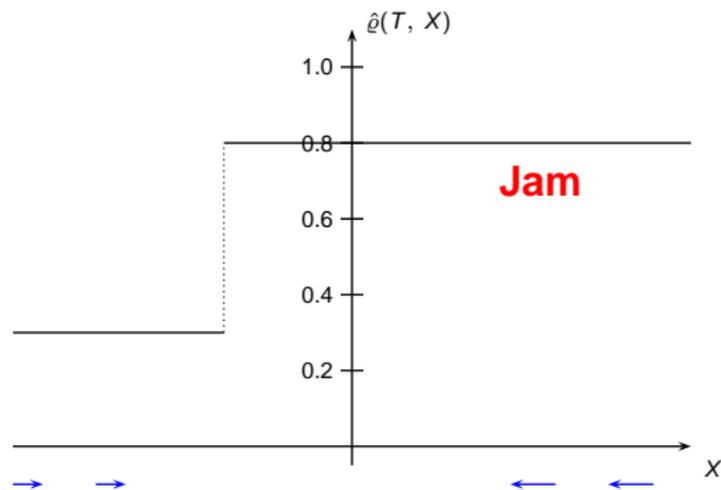
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



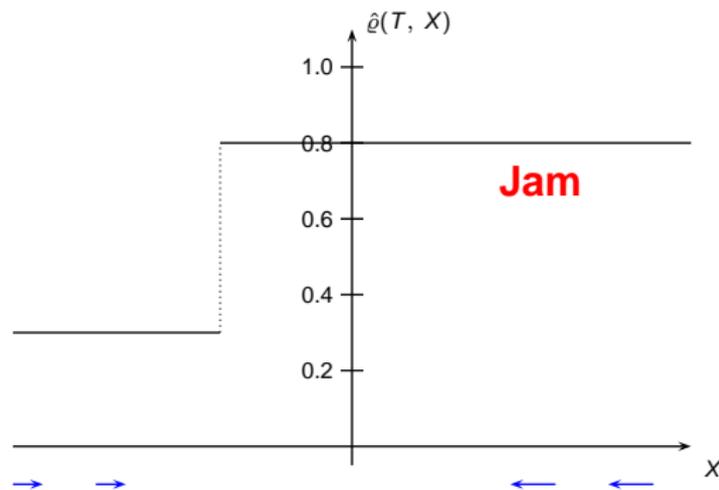
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



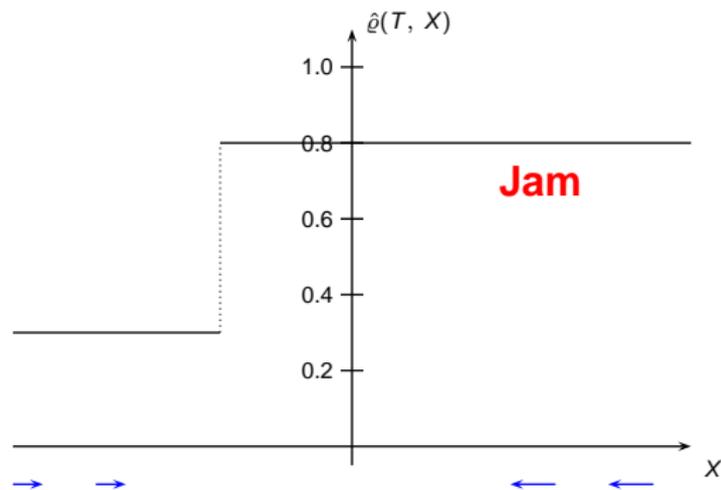
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



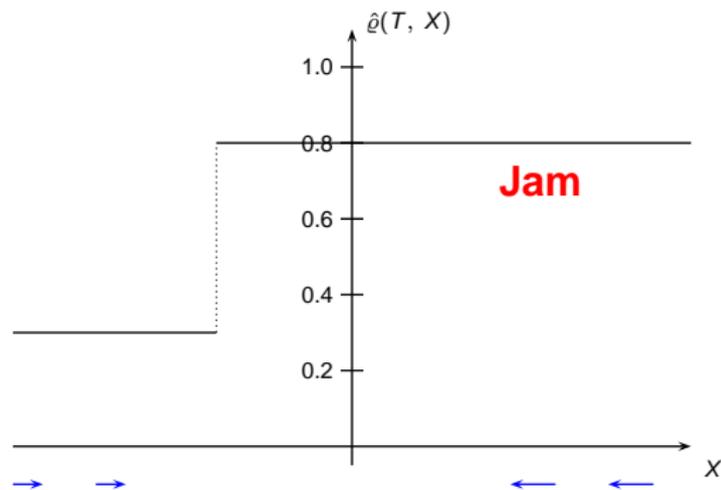
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



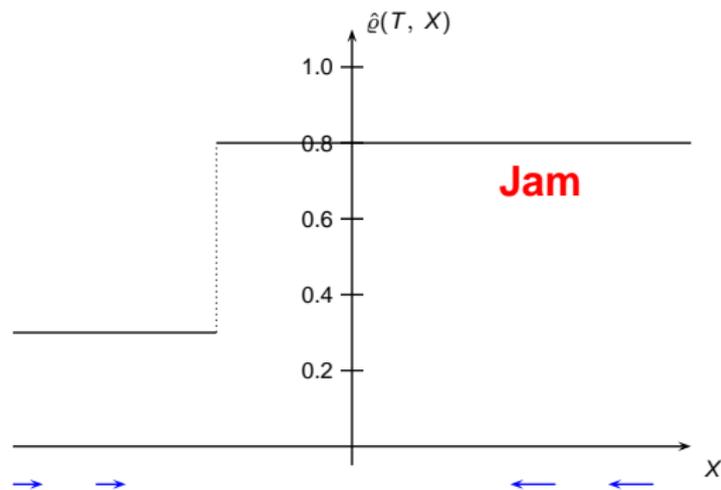
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



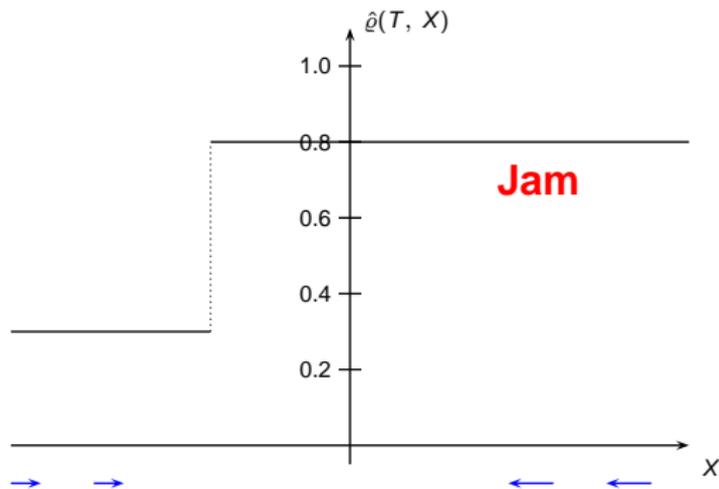
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



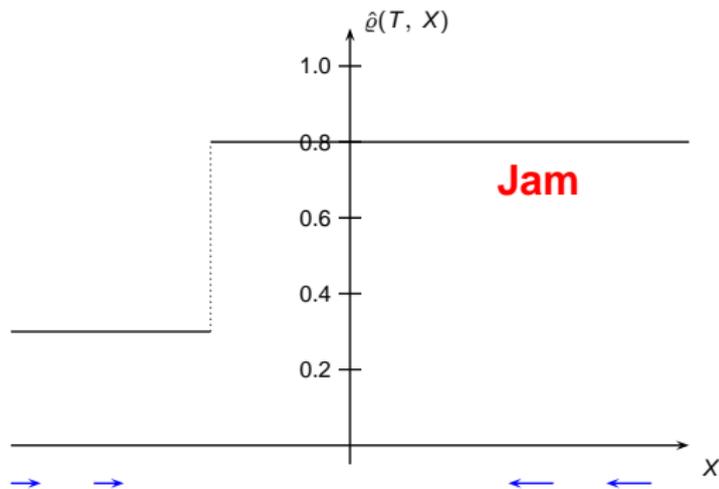
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



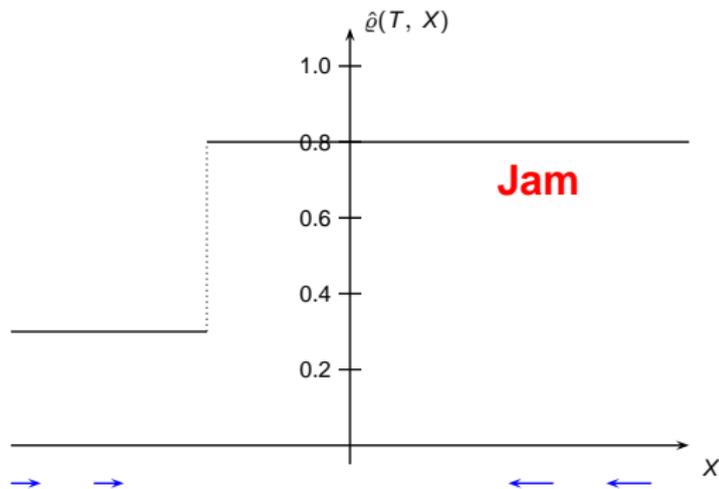
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



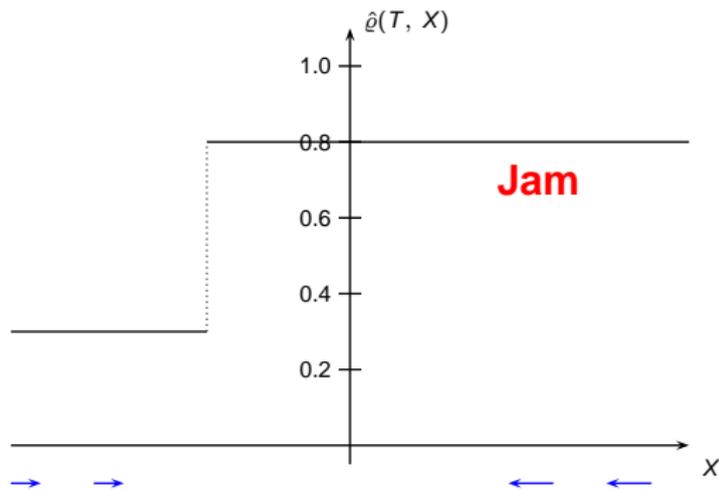
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



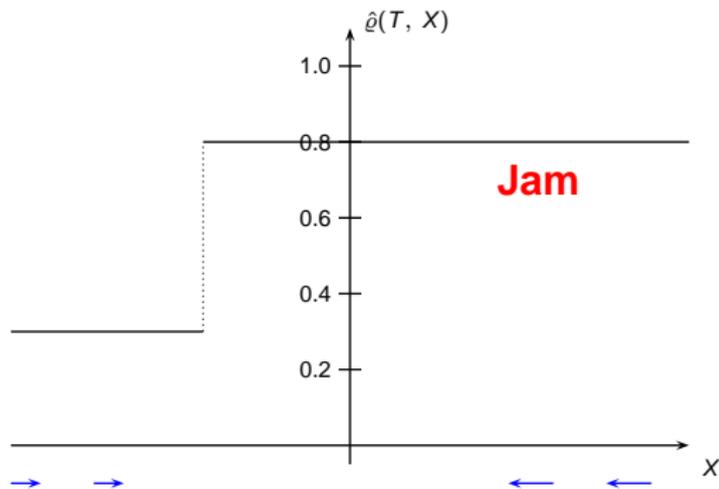
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



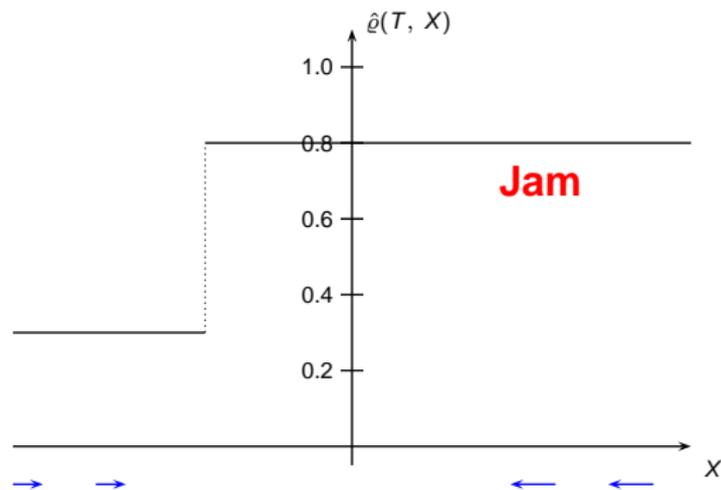
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



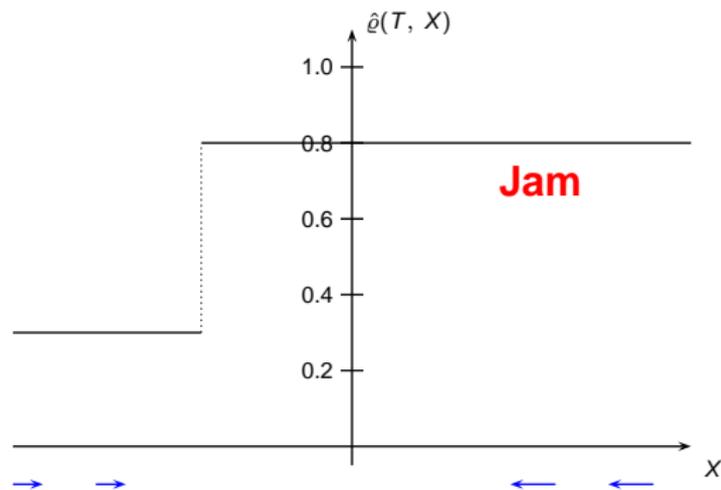
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



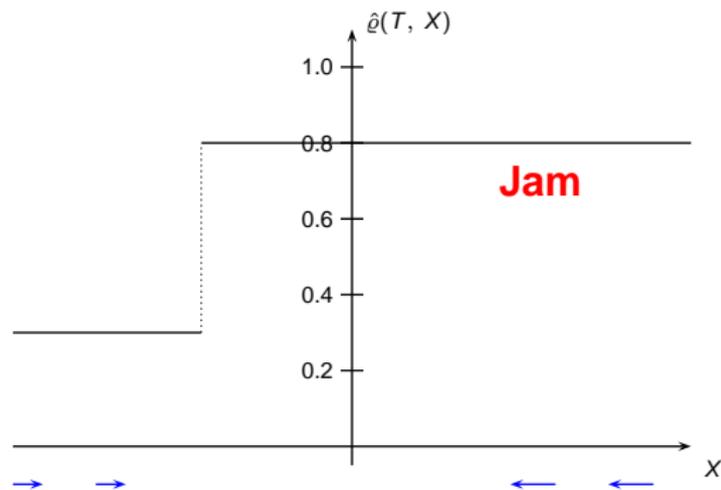
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



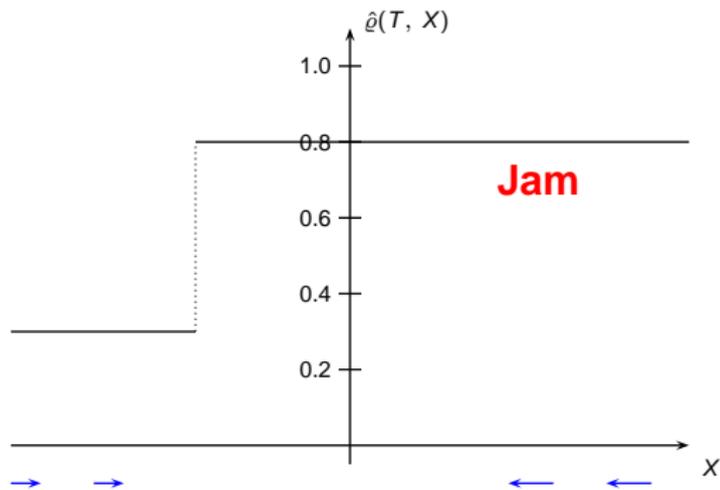
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



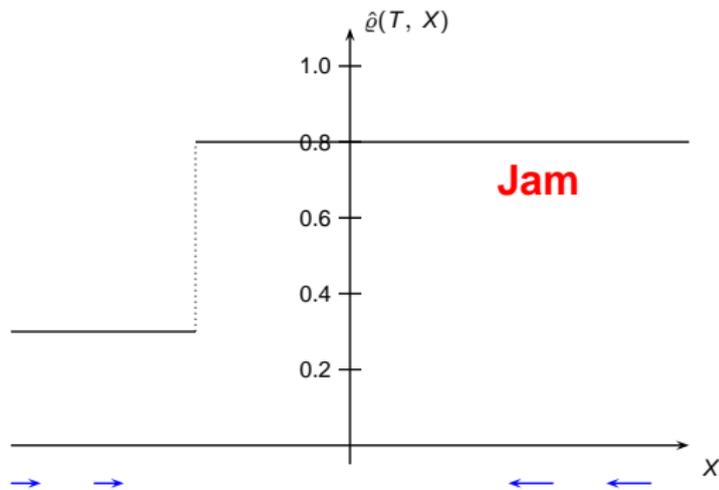
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



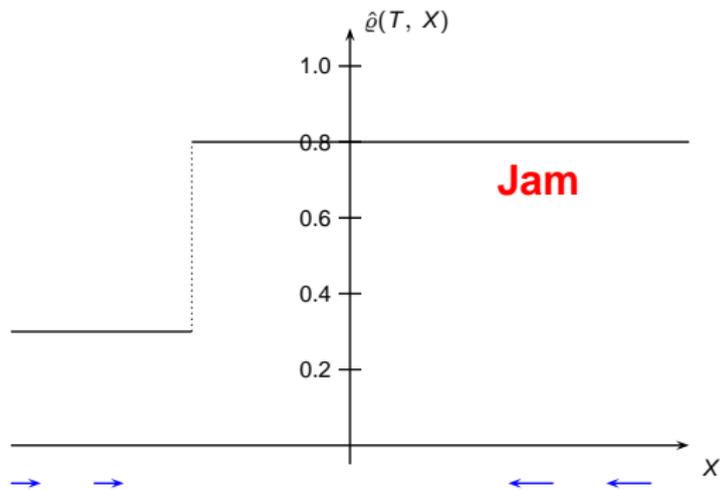
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



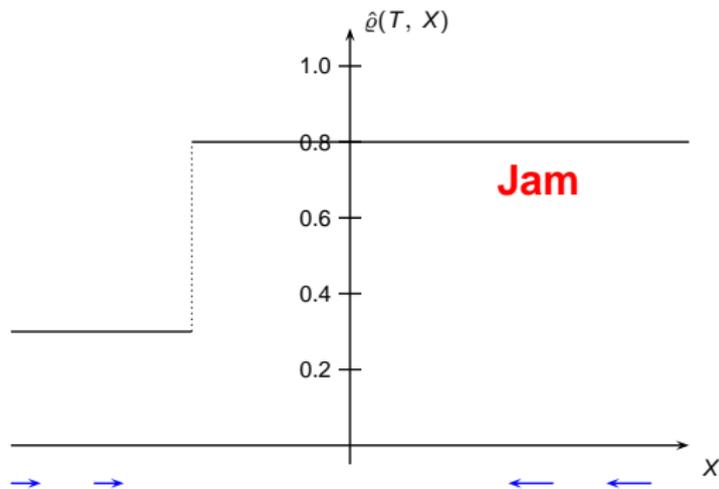
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



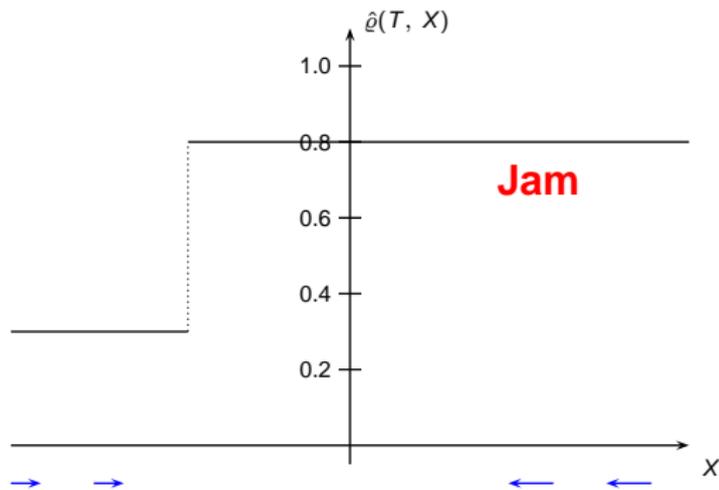
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



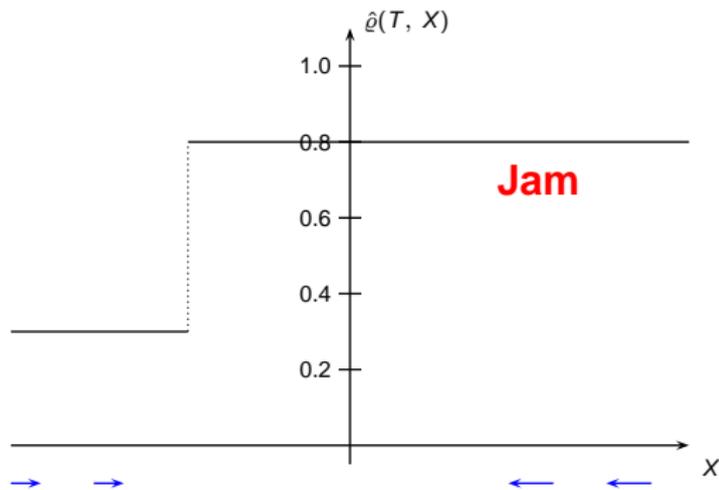
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



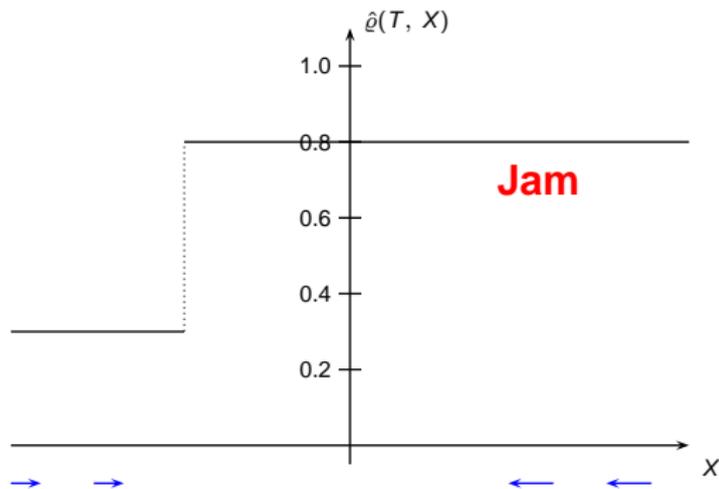
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



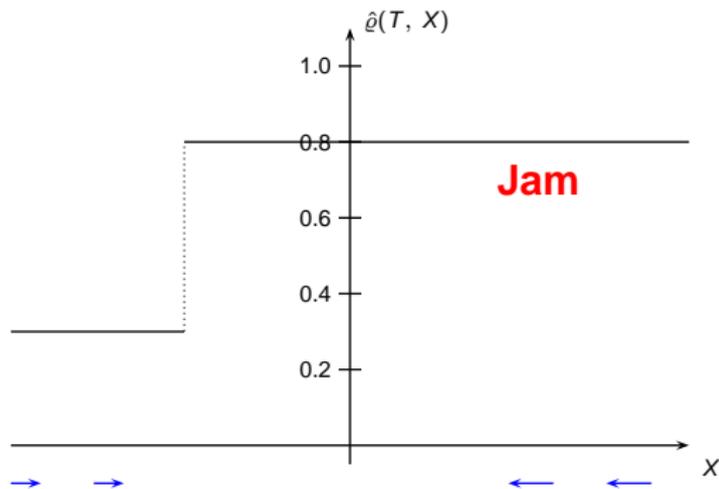
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



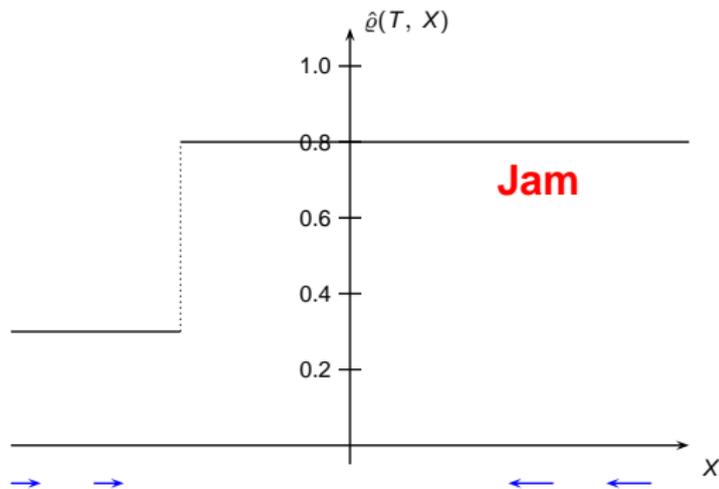
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



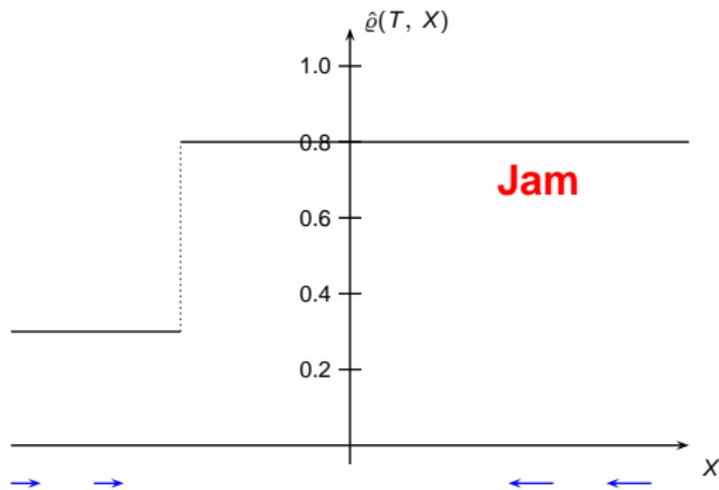
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



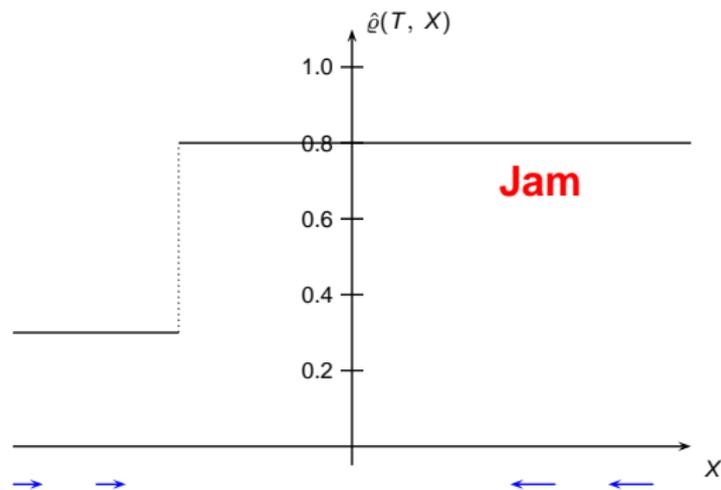
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



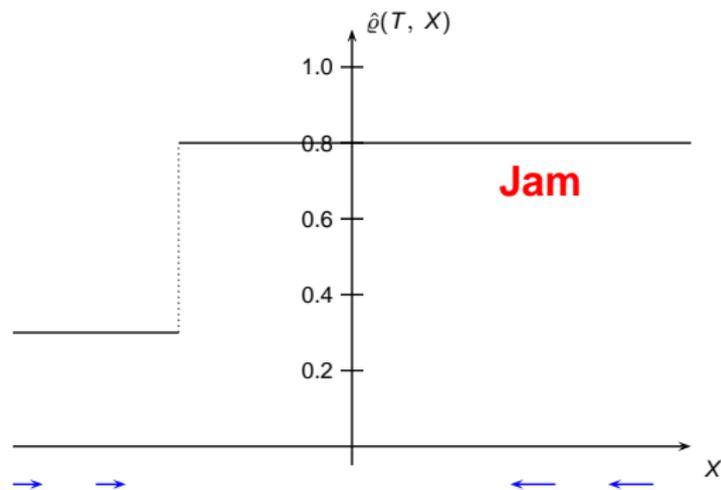
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



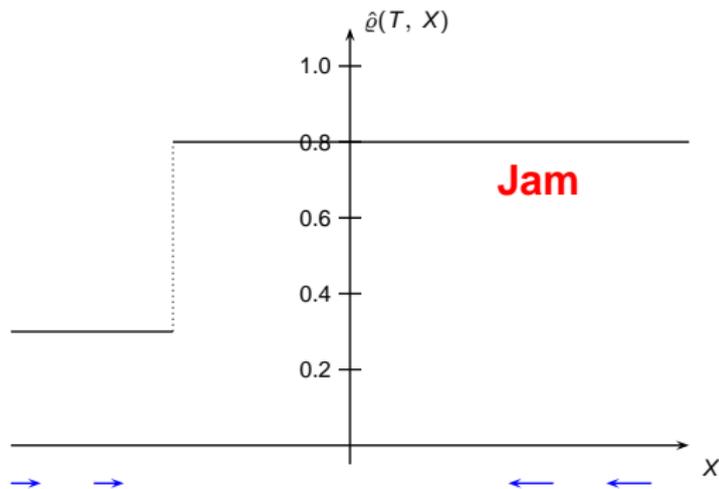
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



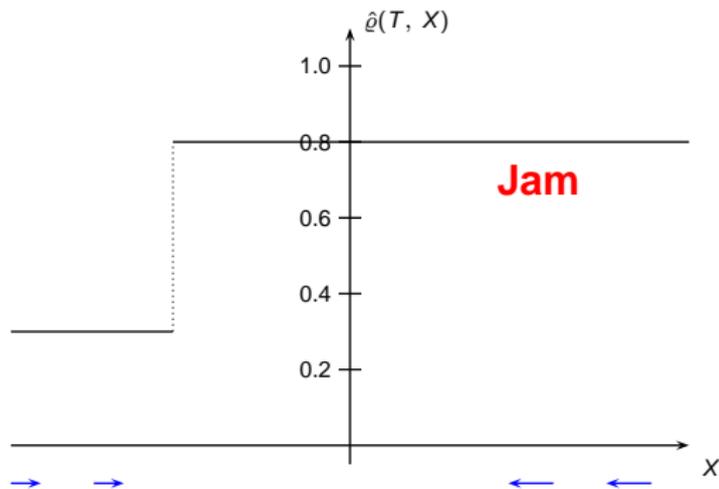
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



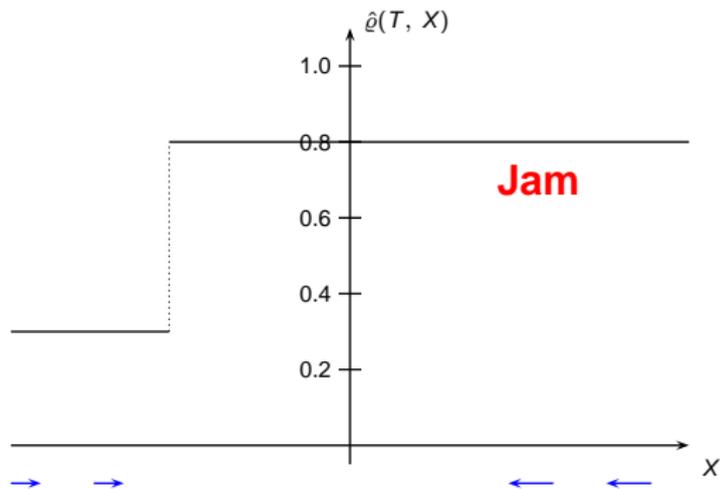
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



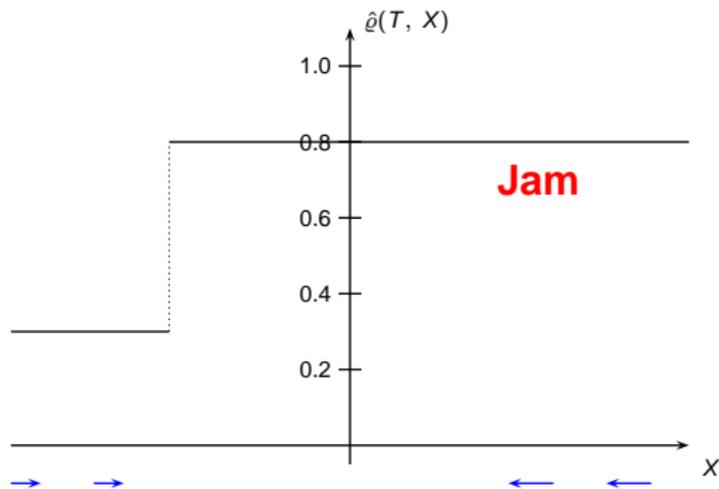
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



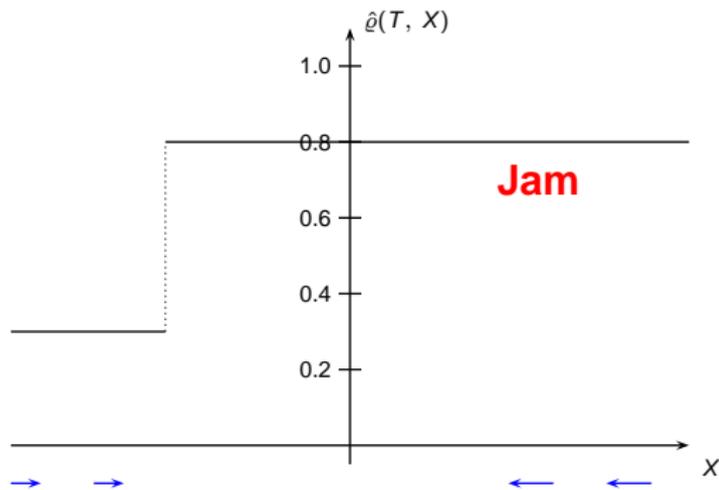
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



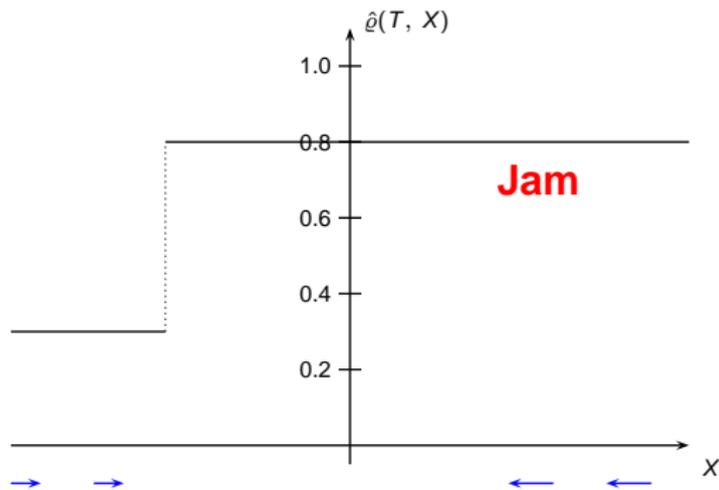
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



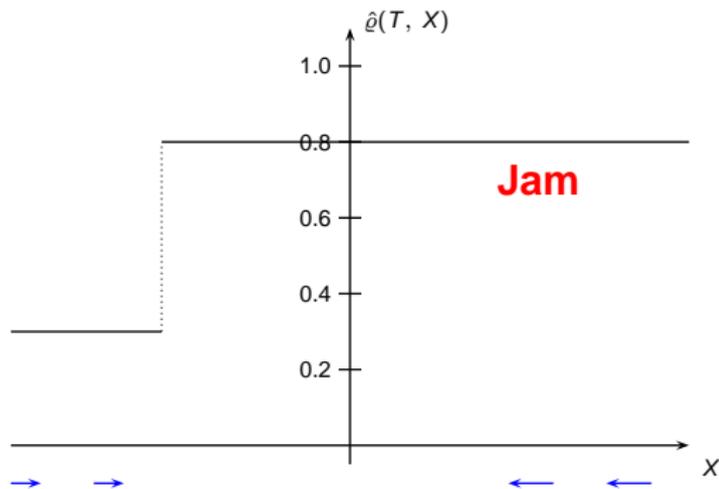
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



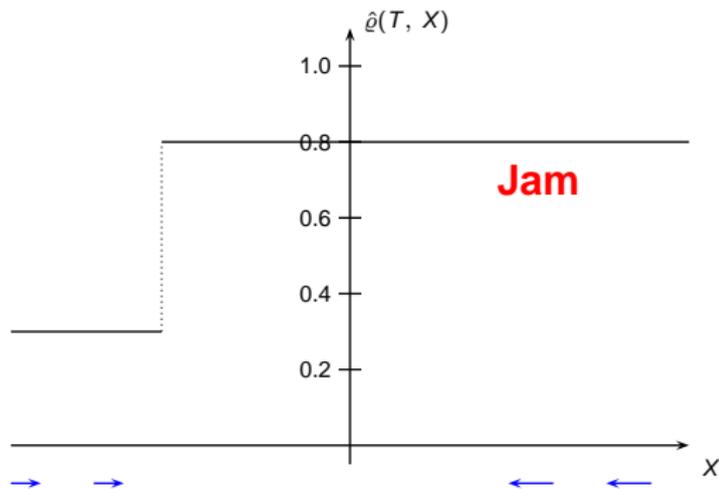
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



$$\dot{X}(T) = 1 - 2\hat{\rho}$$

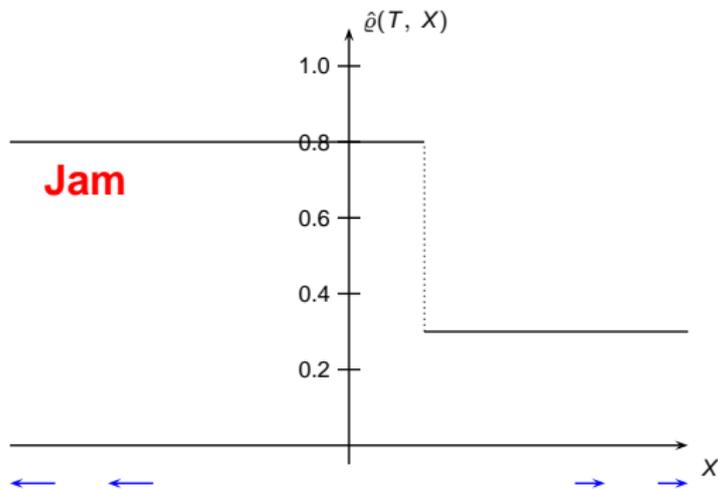
On large scales



$$\dot{X}(T) = 1 - 2\hat{\rho}$$

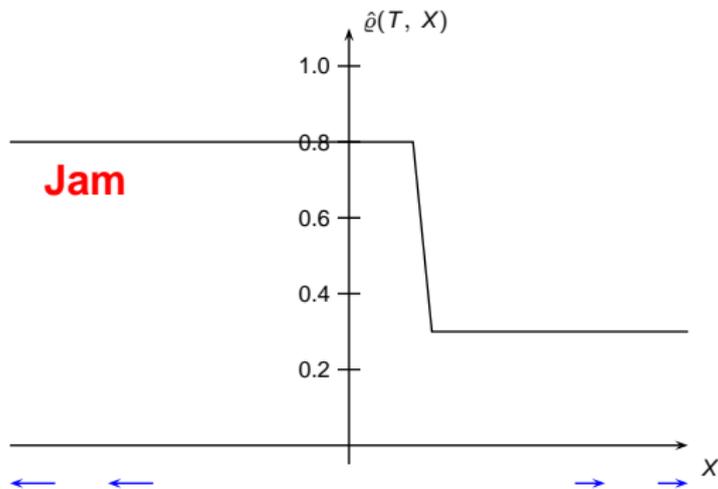
Shock

On large scales



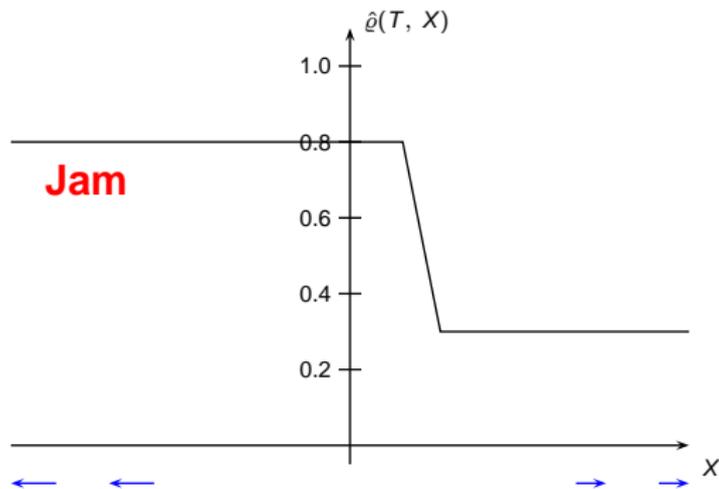
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



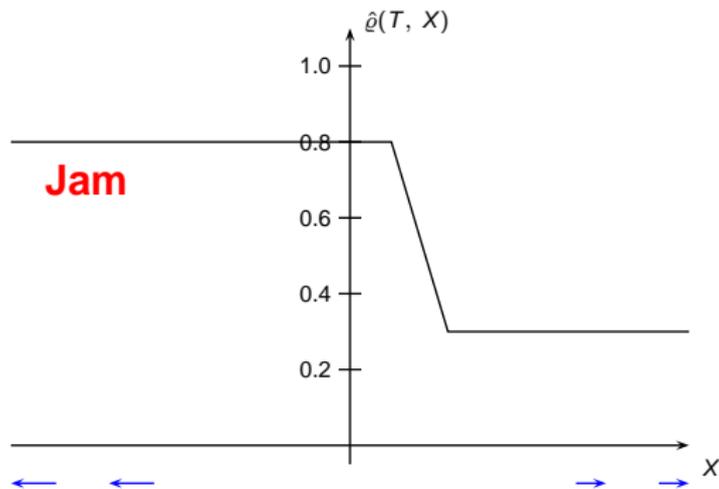
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



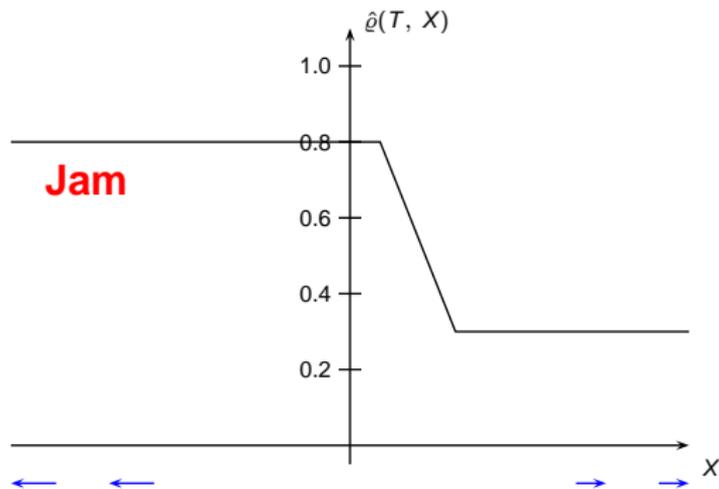
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



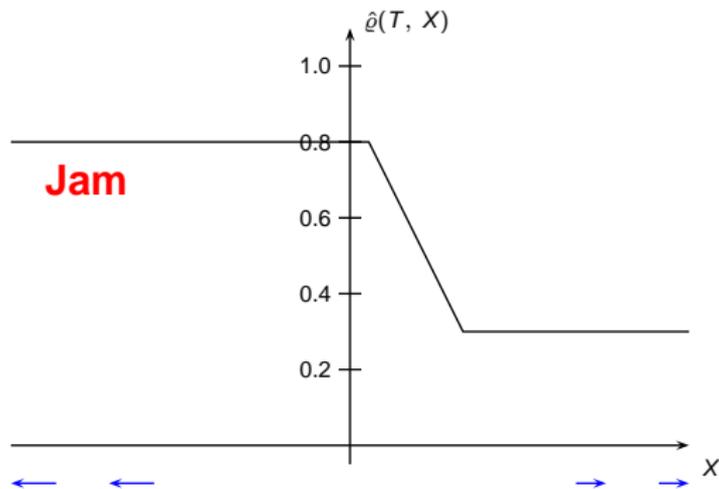
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



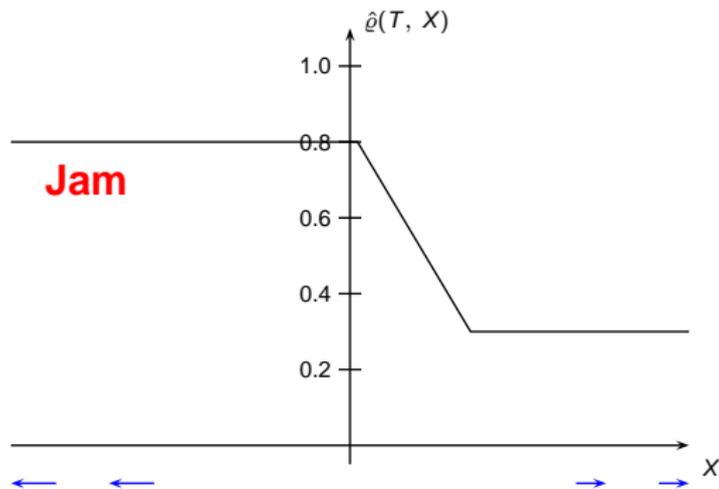
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



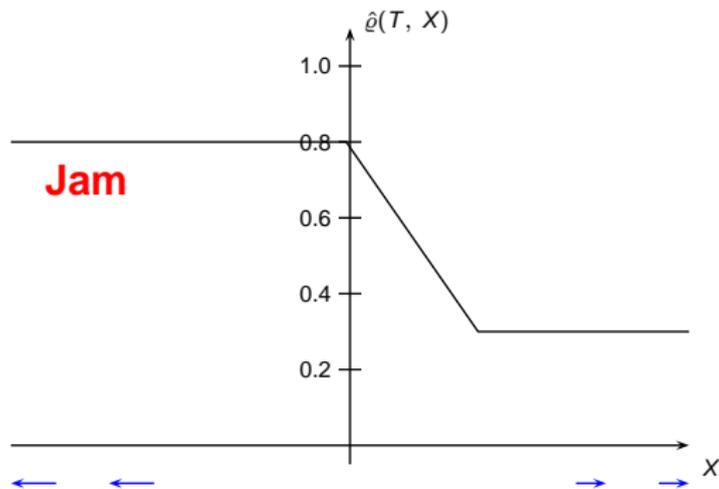
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



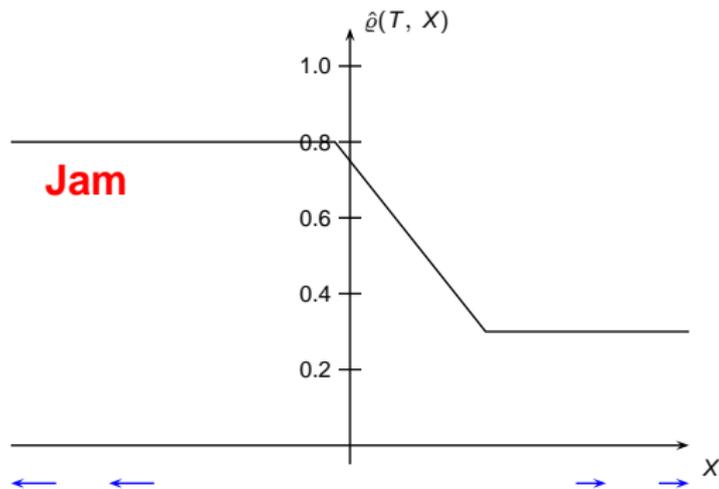
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



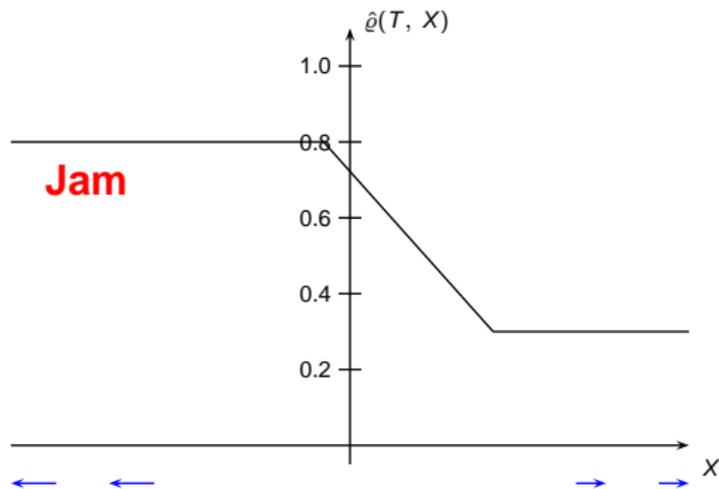
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



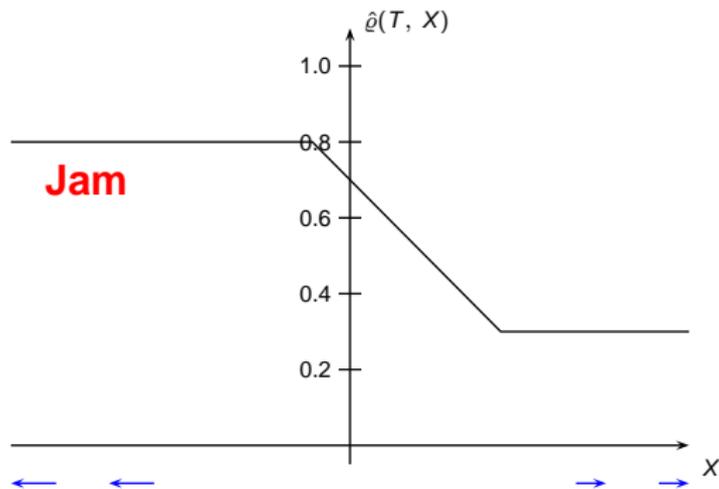
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



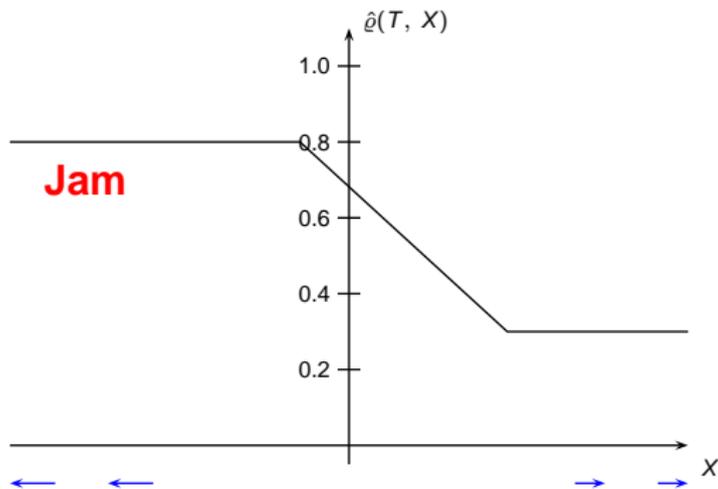
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



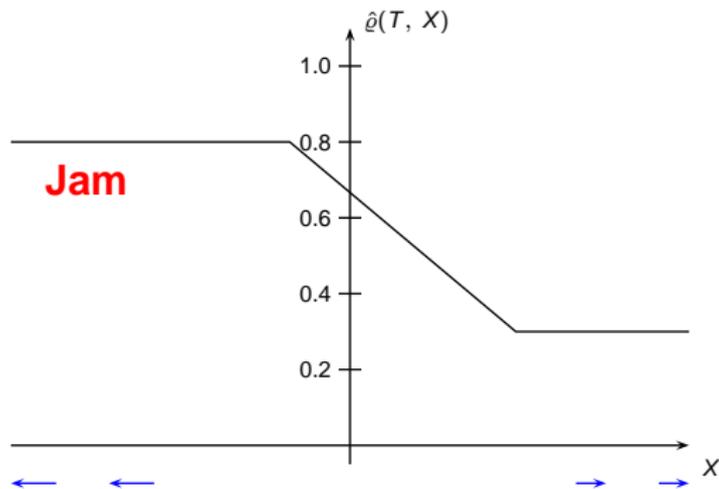
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



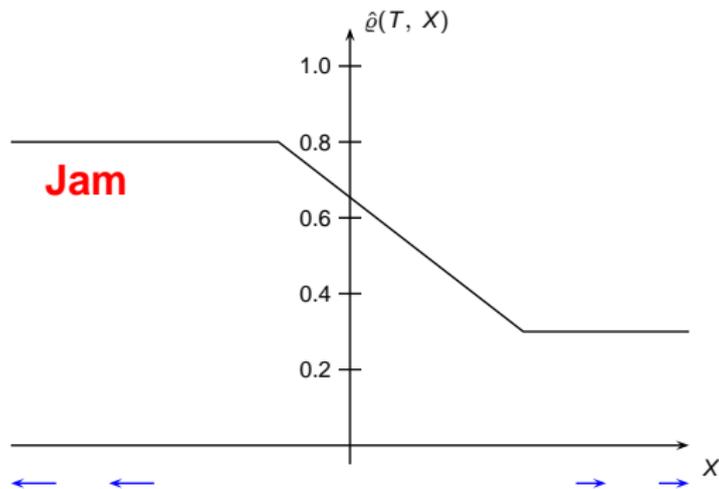
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



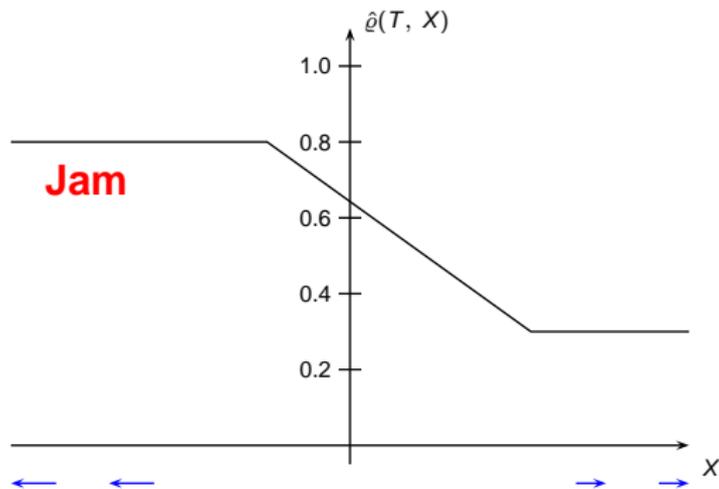
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



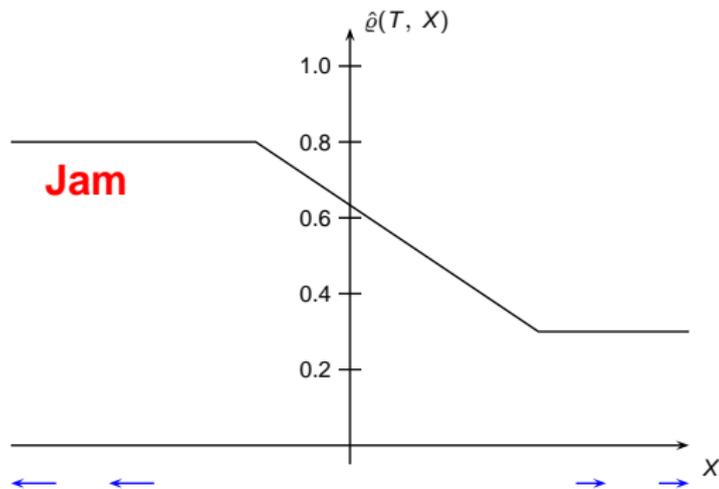
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



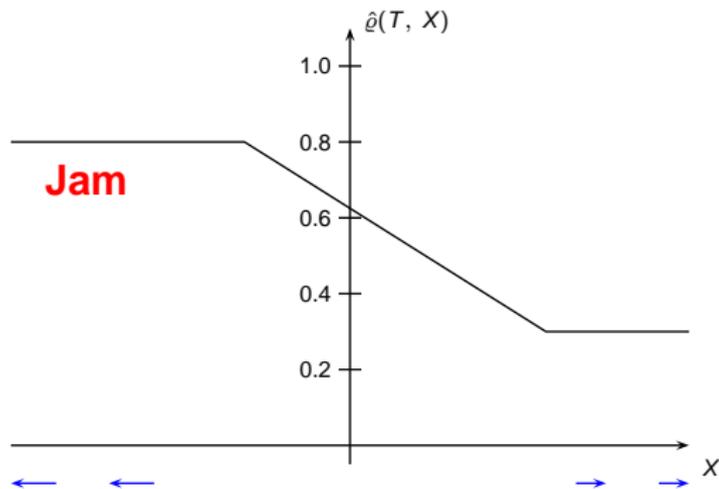
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



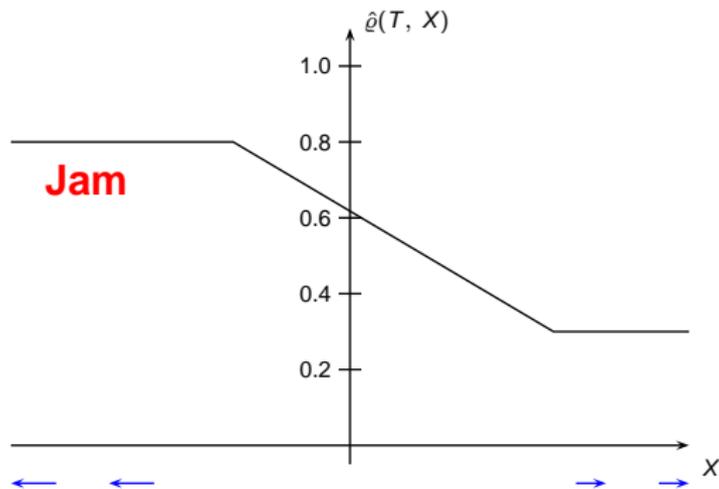
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



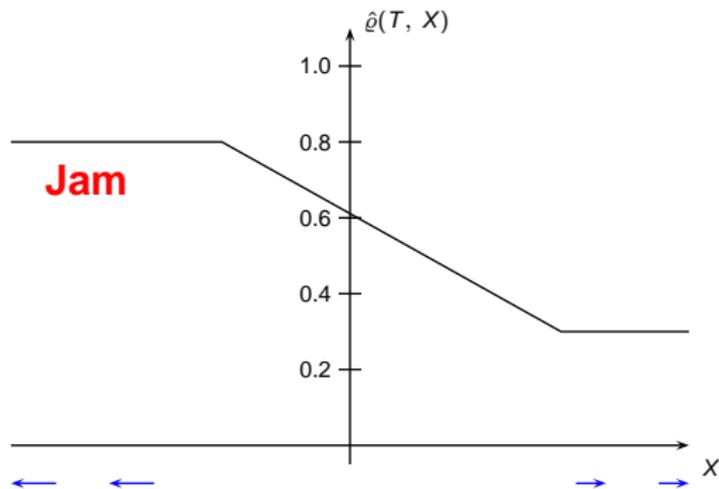
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



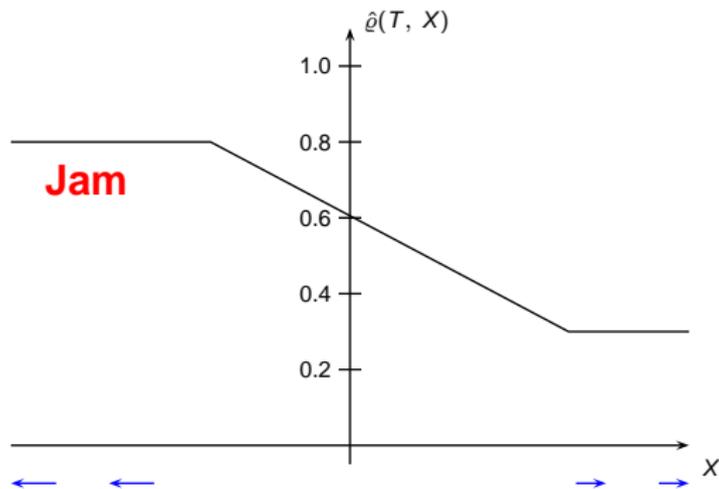
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



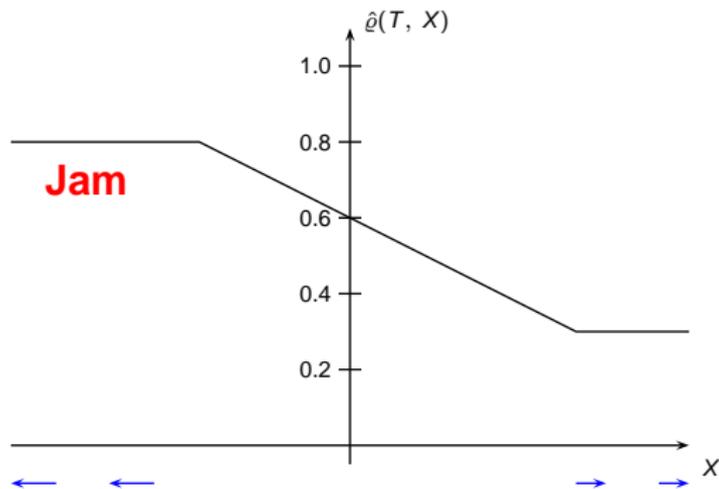
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



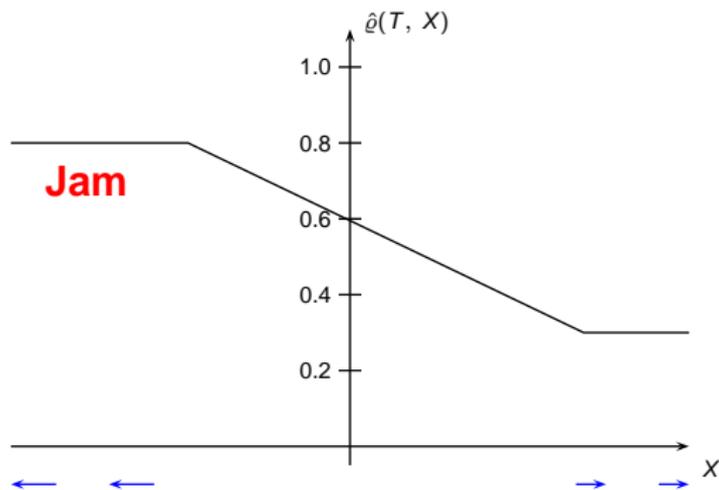
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



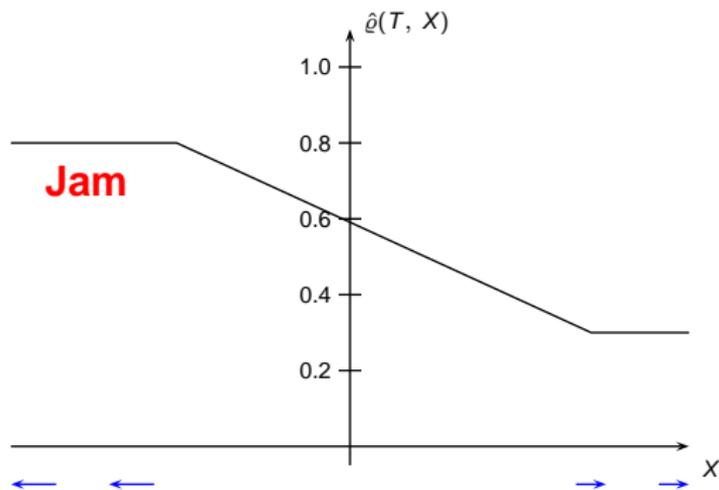
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



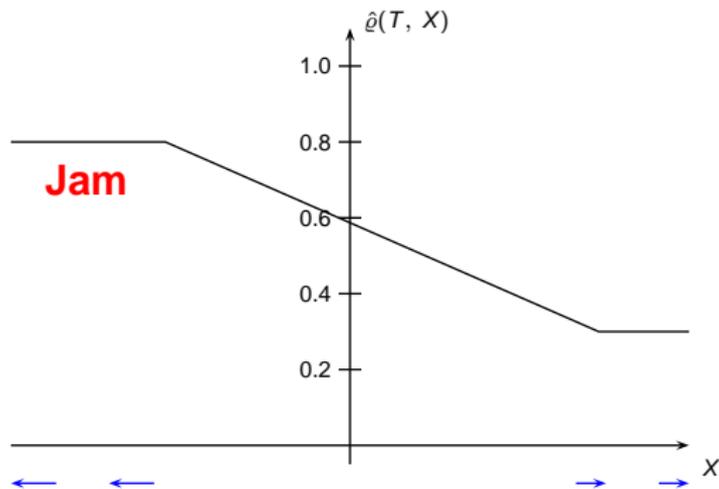
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



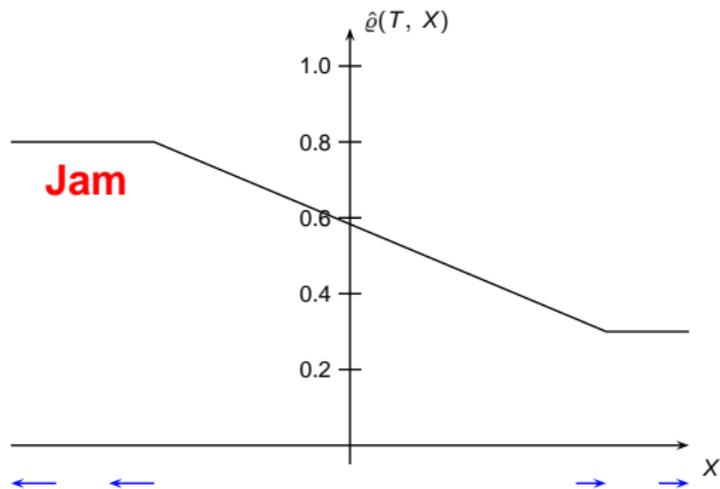
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



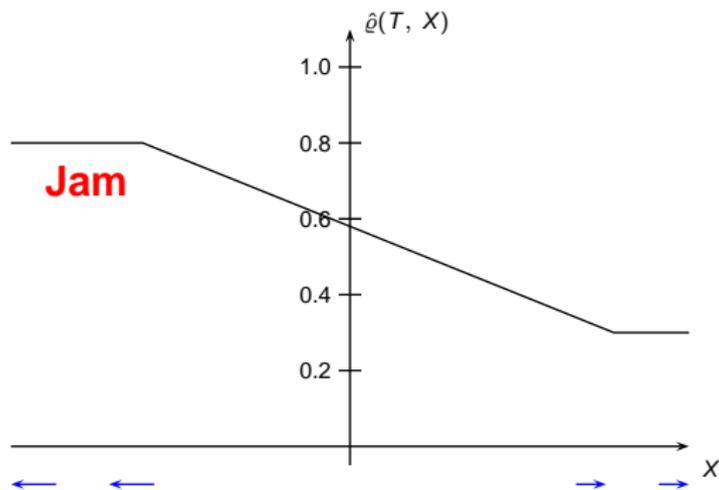
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



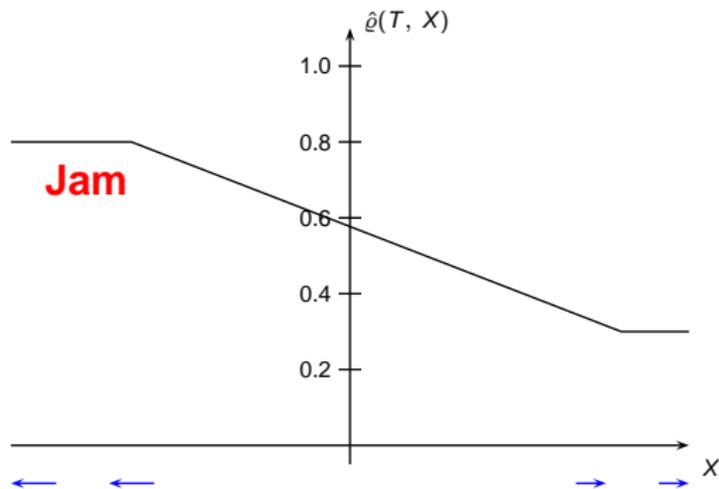
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



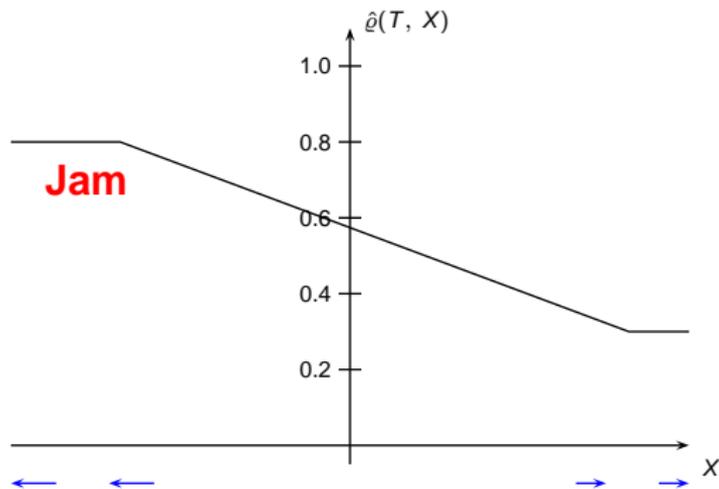
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



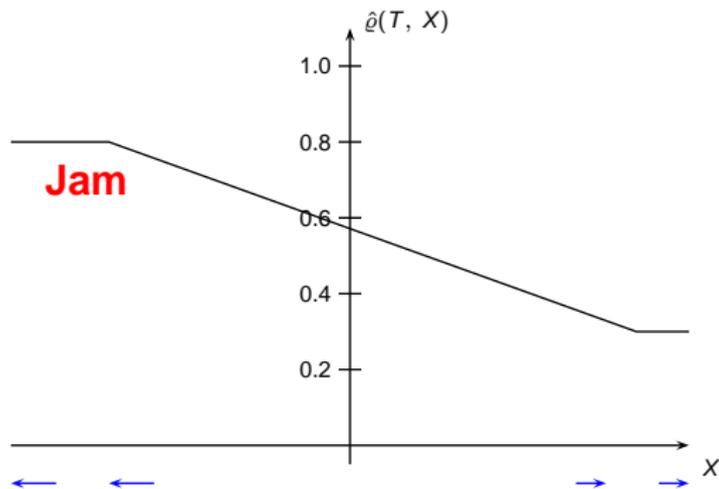
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



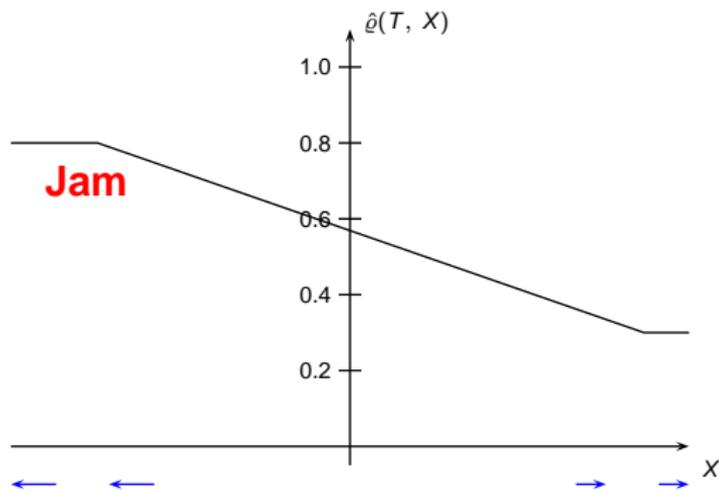
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



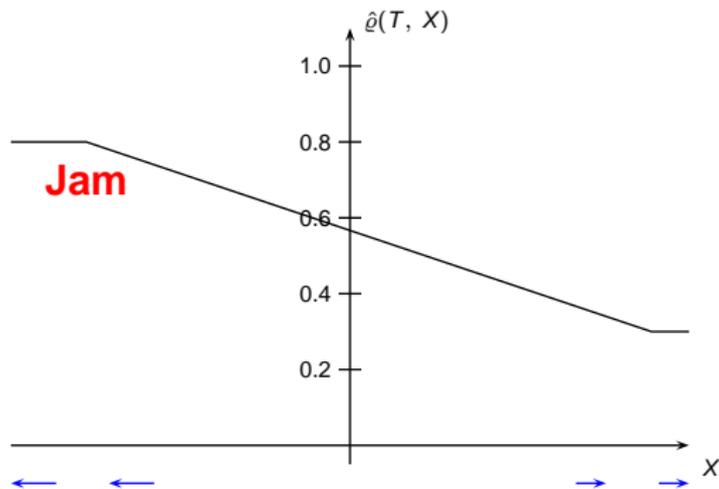
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



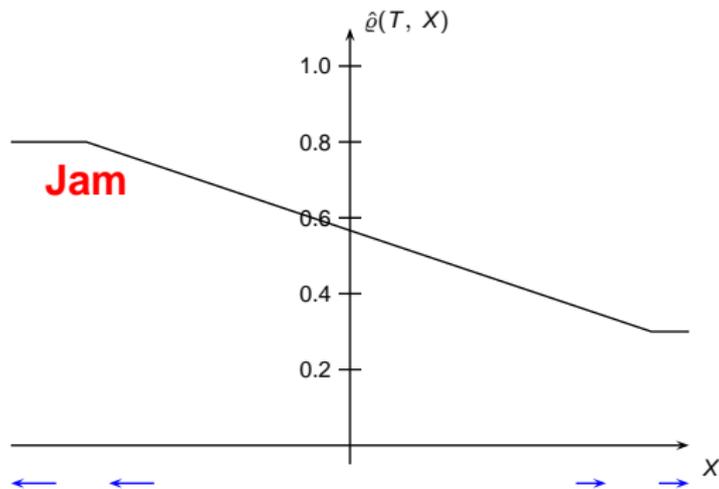
$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



$$\dot{X}(T) = 1 - 2\hat{\rho}$$

On large scales



$$\dot{X}(T) = 1 - 2\hat{\rho}$$

Rarefaction wave

The second class particle: non-attractive case

We are facing a

- ▶ nearest neighbour
- ▶ parity conserving
- ▶ branching
- ▶ annihilating process
- ▶ on the dynamic background of first class particles.

The aim is to control the number of \uparrow and \downarrow 's. Idea from Bálint Tóth.

\rightsquigarrow `homog2.avi`

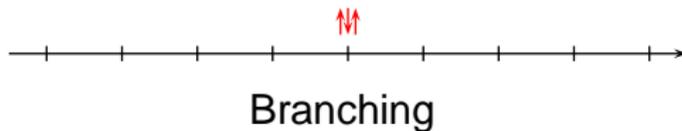
A mean field model

A model we can say something about:



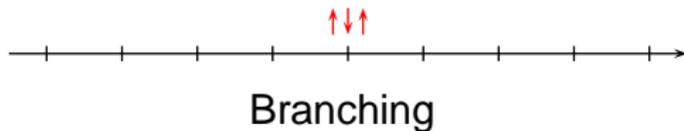
A mean field model

A model we can say something about:



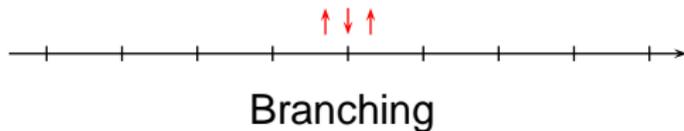
A mean field model

A model we can say something about:



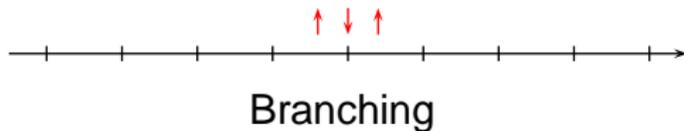
A mean field model

A model we can say something about:



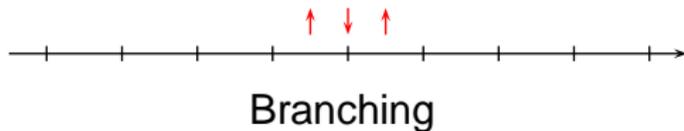
A mean field model

A model we can say something about:



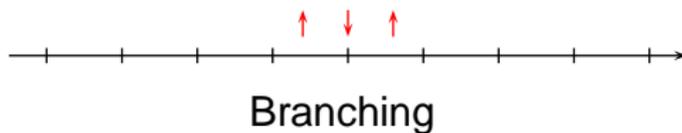
A mean field model

A model we can say something about:



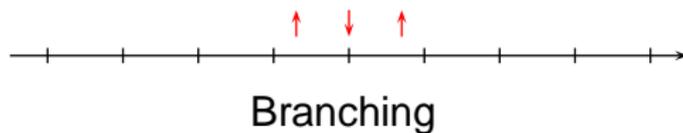
A mean field model

A model we can say something about:



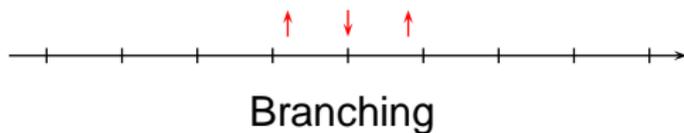
A mean field model

A model we can say something about:



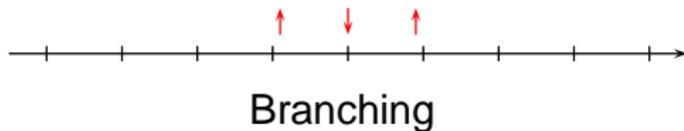
A mean field model

A model we can say something about:



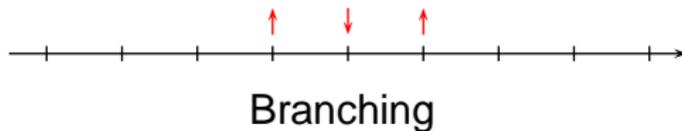
A mean field model

A model we can say something about:



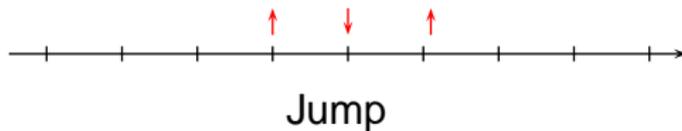
A mean field model

A model we can say something about:



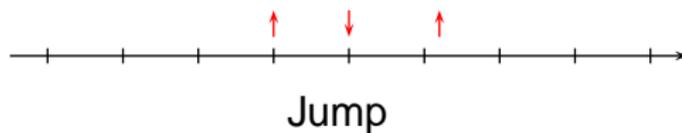
A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



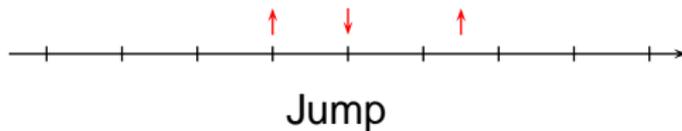
A mean field model

A model we can say something about:



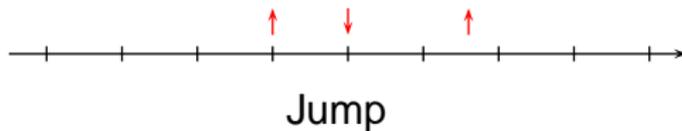
A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



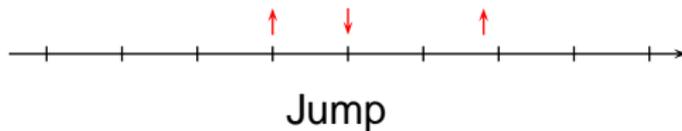
A mean field model

A model we can say something about:



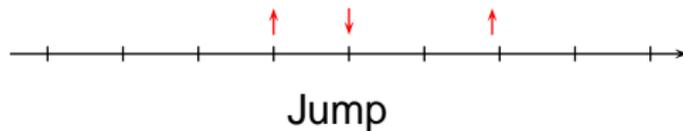
A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



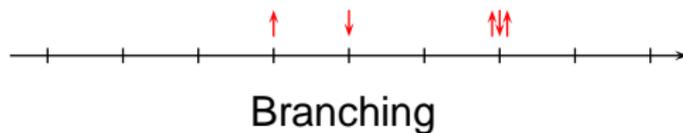
A mean field model

A model we can say something about:



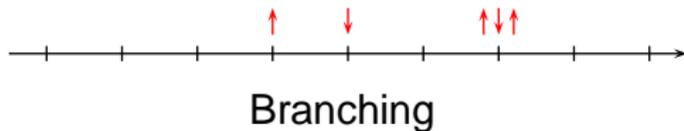
A mean field model

A model we can say something about:



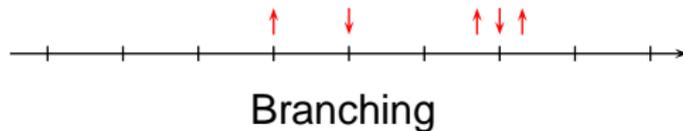
A mean field model

A model we can say something about:



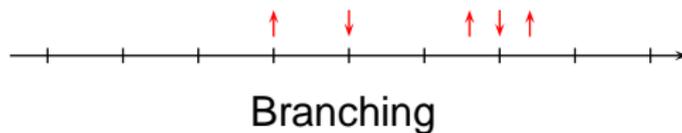
A mean field model

A model we can say something about:



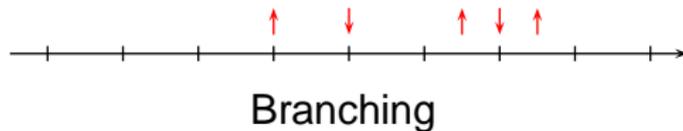
A mean field model

A model we can say something about:



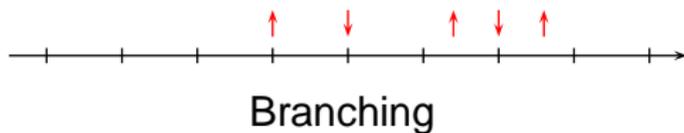
A mean field model

A model we can say something about:



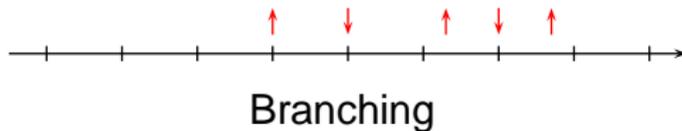
A mean field model

A model we can say something about:



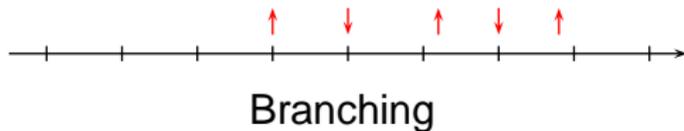
A mean field model

A model we can say something about:



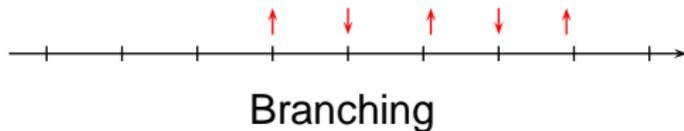
A mean field model

A model we can say something about:



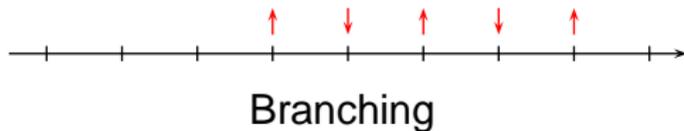
A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



A mean field model

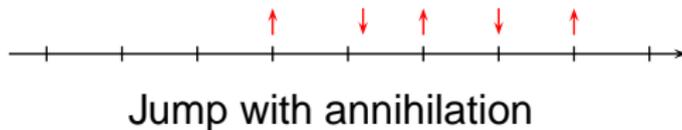
A model we can say something about:



Jump with annihilation

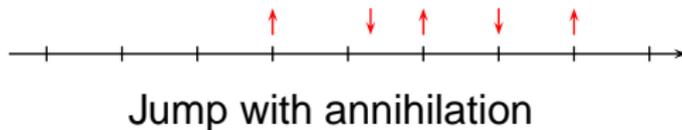
A mean field model

A model we can say something about:



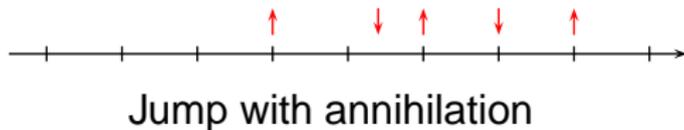
A mean field model

A model we can say something about:



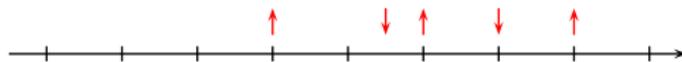
A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



Jump with annihilation

A mean field model

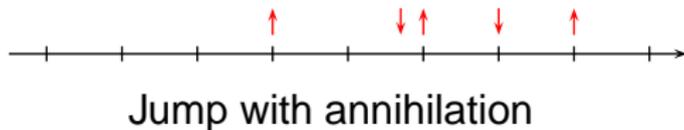
A model we can say something about:



Jump with annihilation

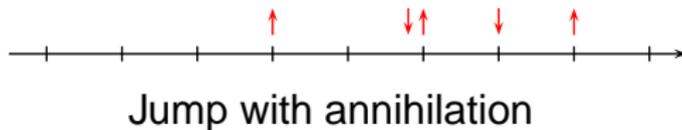
A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



A mean field model

A model we can say something about:



Jump with annihilation

A mean field model

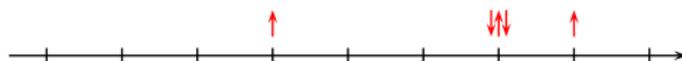
A model we can say something about:



Jump with annihilation

A mean field model

A model we can say something about:



Branching with annihilation

A mean field model

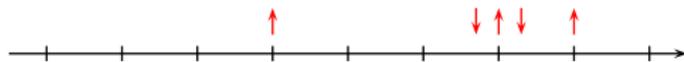
A model we can say something about:



Branching with annihilation

A mean field model

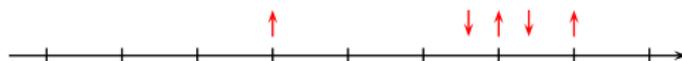
A model we can say something about:



Branching with annihilation

A mean field model

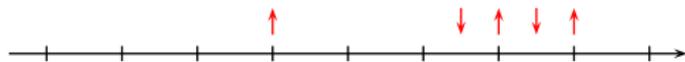
A model we can say something about:



Branching with annihilation

A mean field model

A model we can say something about:



Branching with annihilation

A mean field model

A model we can say something about:



Branching with annihilation

A mean field model

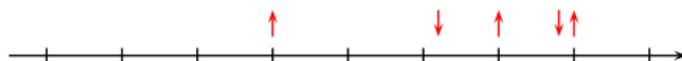
A model we can say something about:



Branching with annihilation

A mean field model

A model we can say something about:



Branching with annihilation

A mean field model

A model we can say something about:



Branching with annihilation

A mean field model

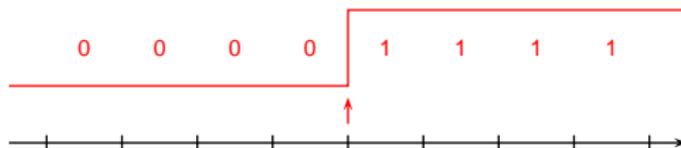
A model we can say something about:



Branching with annihilation

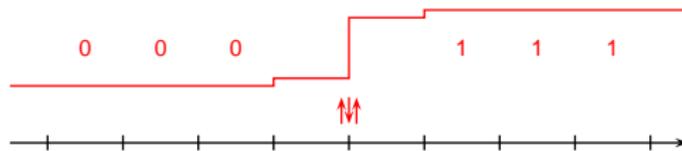
A mean field model

A model we can say something about:



A mean field model

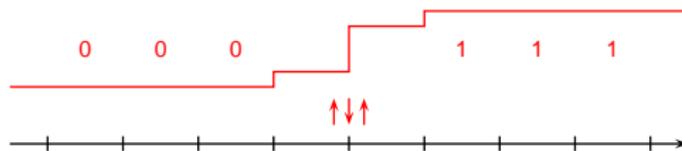
A model we can say something about:



Branching: **exclusion**

A mean field model

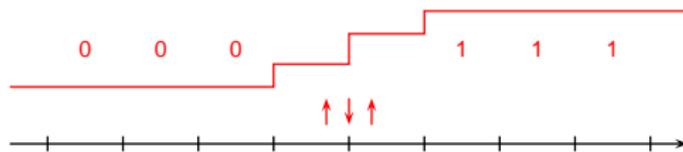
A model we can say something about:



Branching: **exclusion**

A mean field model

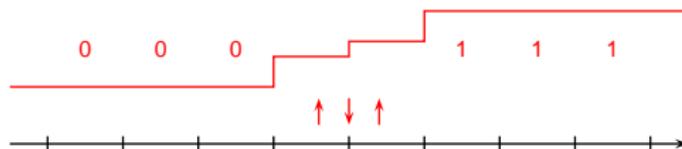
A model we can say something about:



Branching: **exclusion**

A mean field model

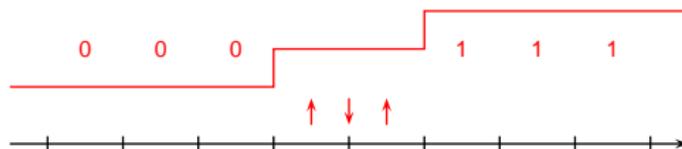
A model we can say something about:



Branching: **exclusion**

A mean field model

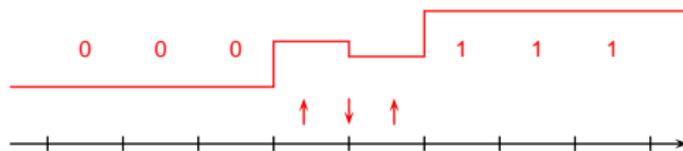
A model we can say something about:



Branching: **exclusion**

A mean field model

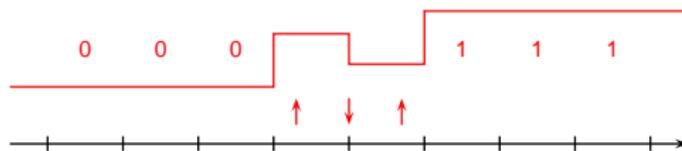
A model we can say something about:



Branching: **exclusion**

A mean field model

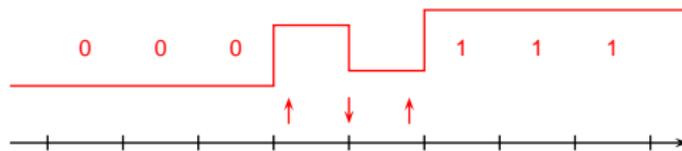
A model we can say something about:



Branching: **exclusion**

A mean field model

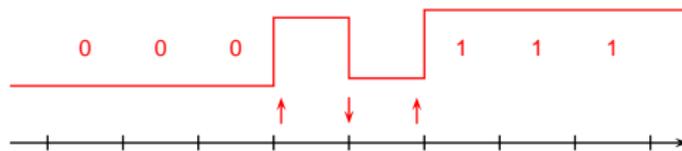
A model we can say something about:



Branching: **exclusion**

A mean field model

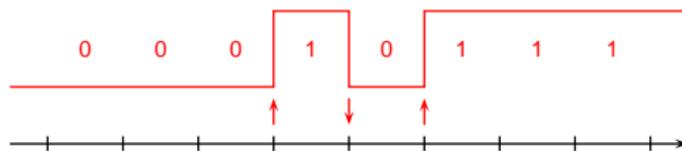
A model we can say something about:



Branching: **exclusion**

A mean field model

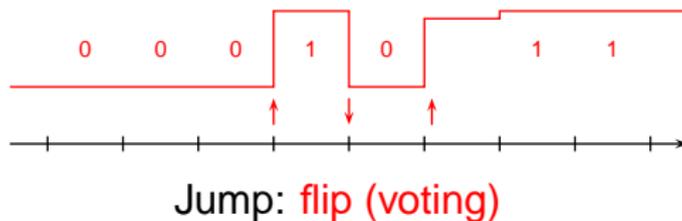
A model we can say something about:



Branching: **exclusion**

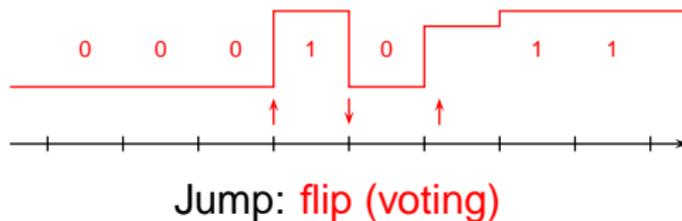
A mean field model

A model we can say something about:



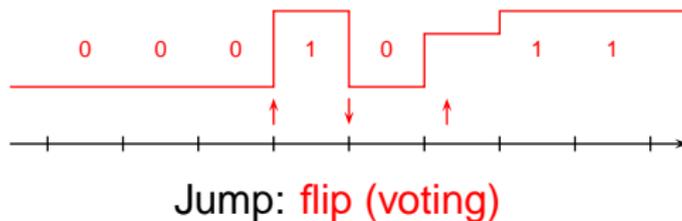
A mean field model

A model we can say something about:



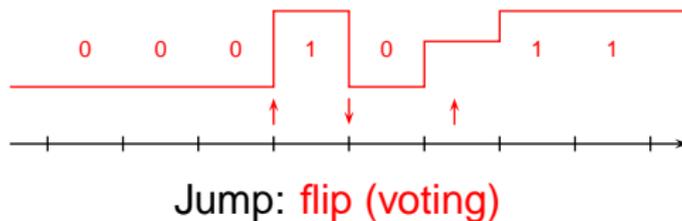
A mean field model

A model we can say something about:



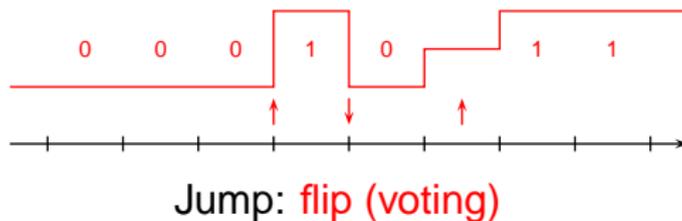
A mean field model

A model we can say something about:



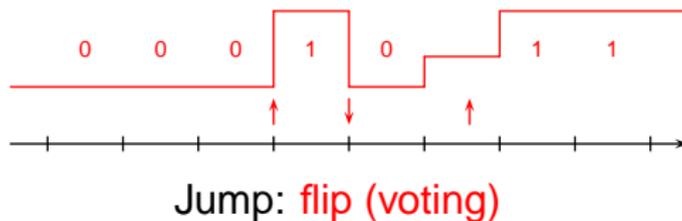
A mean field model

A model we can say something about:



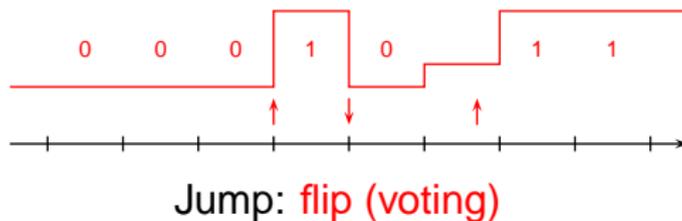
A mean field model

A model we can say something about:



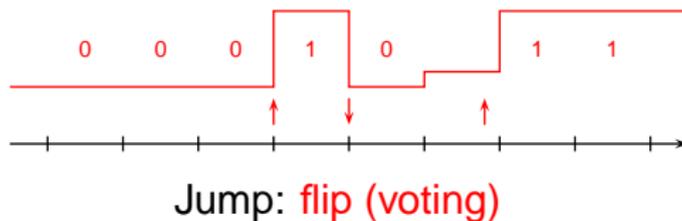
A mean field model

A model we can say something about:



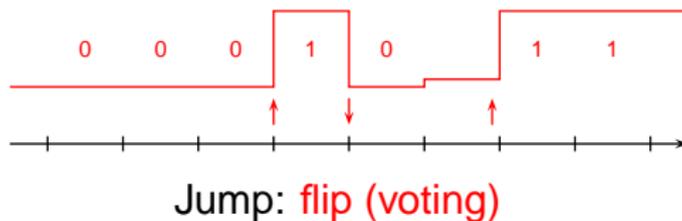
A mean field model

A model we can say something about:



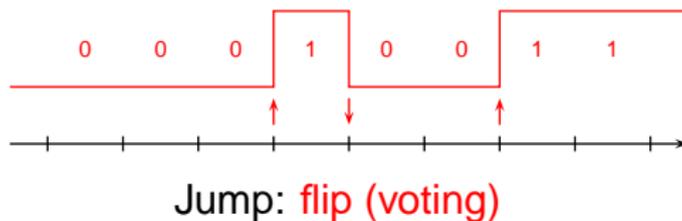
A mean field model

A model we can say something about:



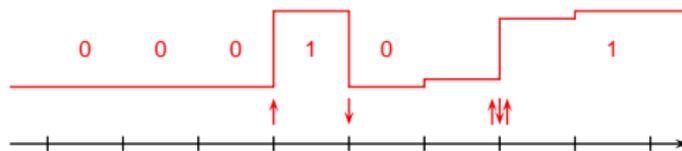
A mean field model

A model we can say something about:



A mean field model

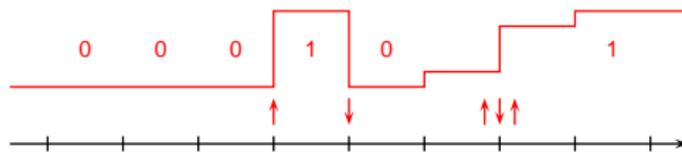
A model we can say something about:



Branching: **exclusion**

A mean field model

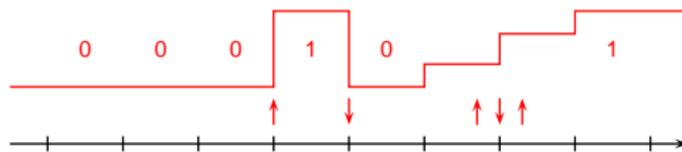
A model we can say something about:



Branching: **exclusion**

A mean field model

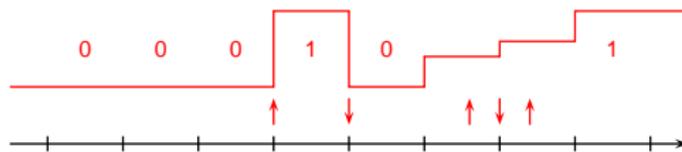
A model we can say something about:



Branching: **exclusion**

A mean field model

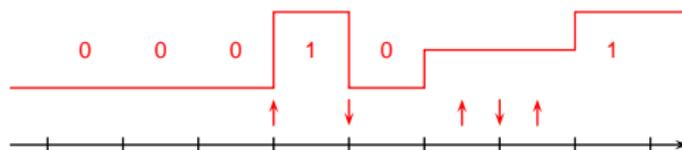
A model we can say something about:



Branching: **exclusion**

A mean field model

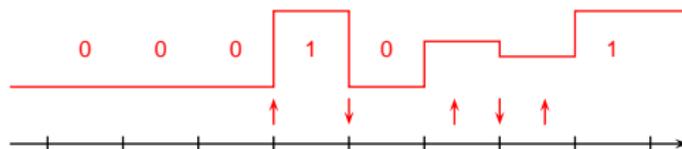
A model we can say something about:



Branching: **exclusion**

A mean field model

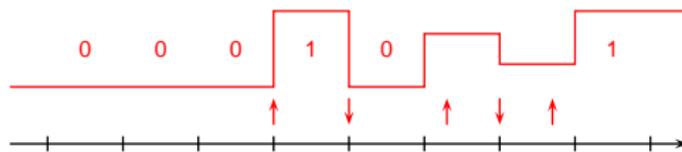
A model we can say something about:



Branching: **exclusion**

A mean field model

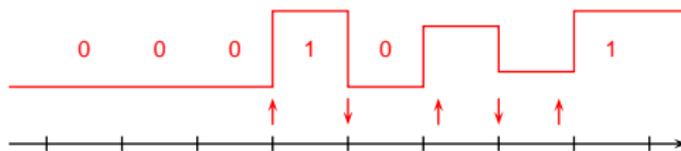
A model we can say something about:



Branching: **exclusion**

A mean field model

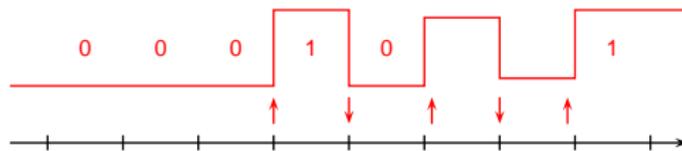
A model we can say something about:



Branching: **exclusion**

A mean field model

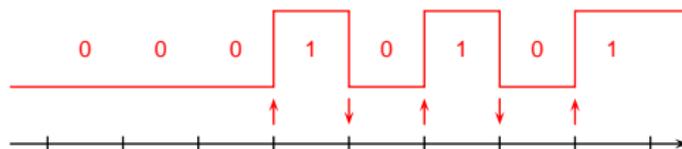
A model we can say something about:



Branching: **exclusion**

A mean field model

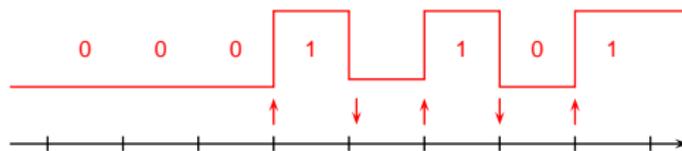
A model we can say something about:



Branching: **exclusion**

A mean field model

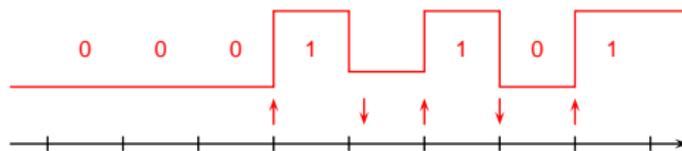
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

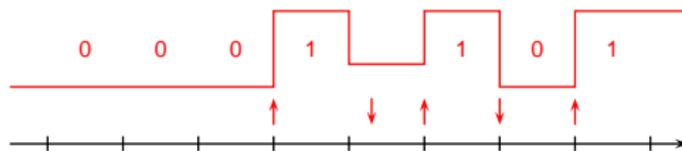
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

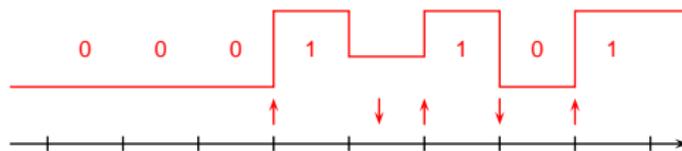
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

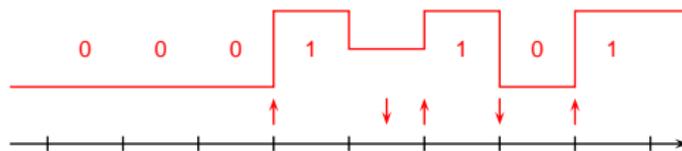
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

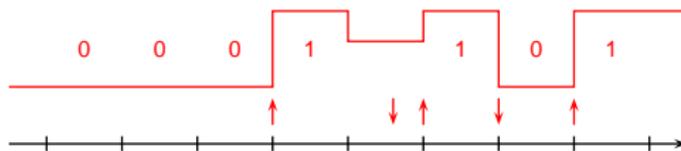
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

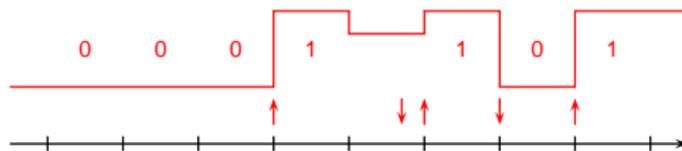
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

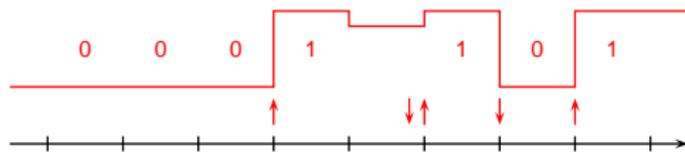
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

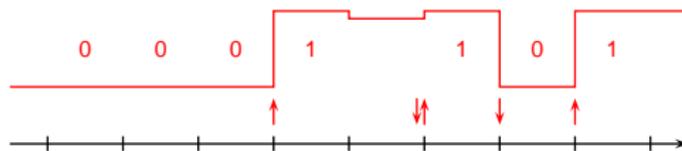
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

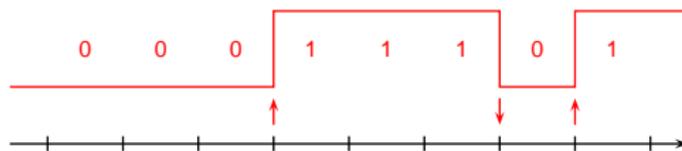
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

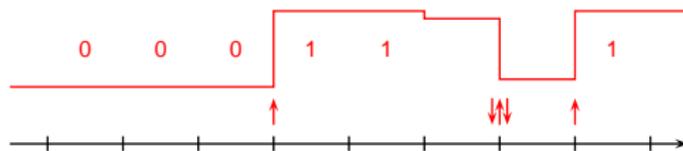
A model we can say something about:



Jump with annihilation: **flip (voting)**

A mean field model

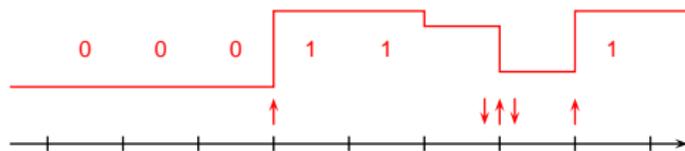
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

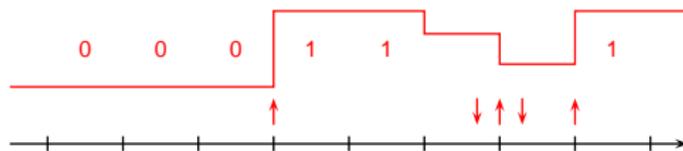
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

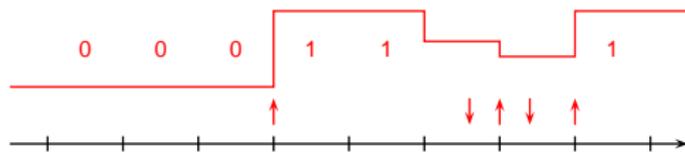
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

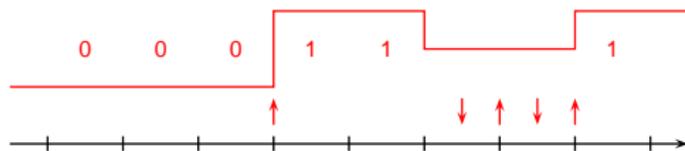
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

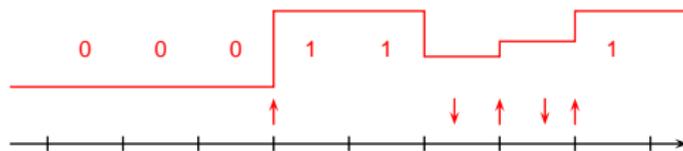
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

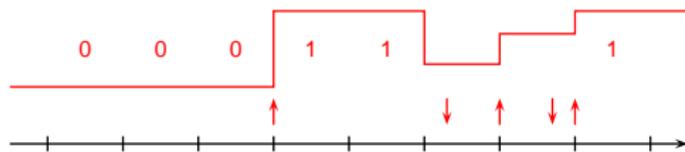
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

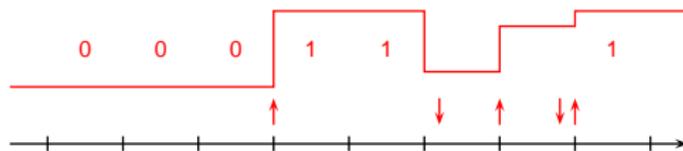
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

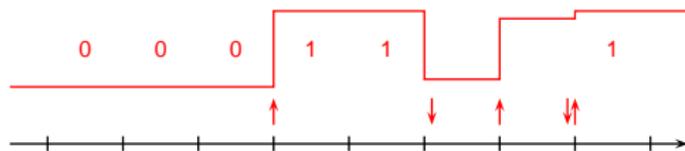
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

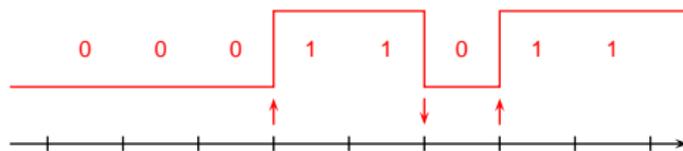
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

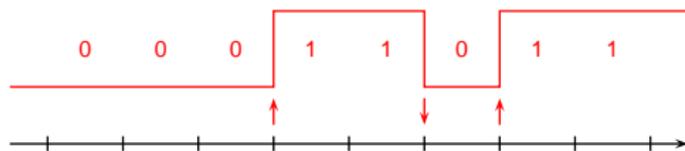
A model we can say something about:



Branching with annihilation: **exclusion**

A mean field model

A model we can say something about:

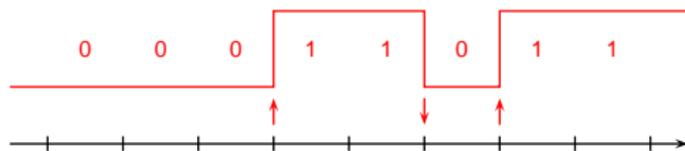


Branching with annihilation: **exclusion**

- ▶ Double branching-annihilating random walks (DBARW)

A mean field model

A model we can say something about:

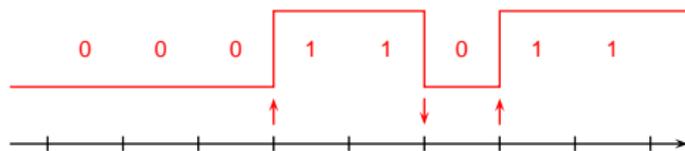


Branching with annihilation: **exclusion**

- ▶ Double branching-annihilating random walks (DBARW)
- ▶ \uparrow 's and \downarrow 's always alternate;

A mean field model

A model we can say something about:

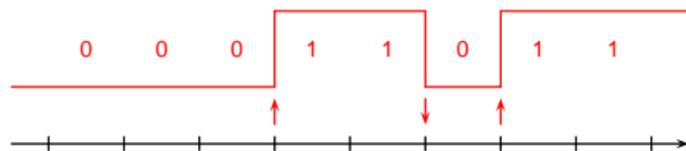


Branching with annihilation: **exclusion**

- ▶ Double branching-annihilating random walks (DBARW)
- ▶ \uparrow 's and \downarrow 's always alternate;
- ▶ their algebraic sum is constant in time.

A mean field model

A model we can say something about:

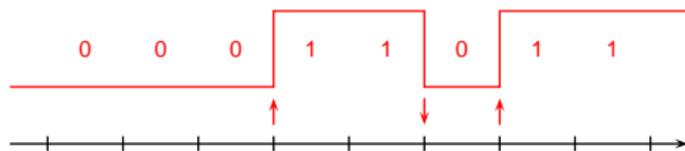


Branching with annihilation: **exclusion**

- ▶ Double branching-annihilating random walks (DBARW)
- ▶ \uparrow 's and \downarrow 's always alternate;
- ▶ their algebraic sum is constant in time.
- ▶ **Nothing is monotone.**

A mean field model

A model we can say something about:

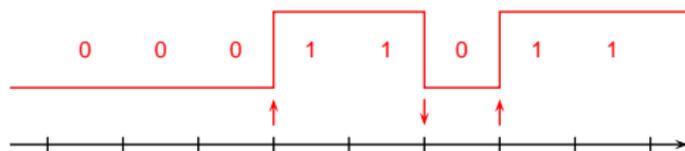


Branching with annihilation: **exclusion**

- ▶ Double branching-annihilating random walks (DBARW)
- ▶ \uparrow 's and \downarrow 's always alternate;
- ▶ their algebraic sum is constant in time.
- ▶ **Nothing is monotone.**

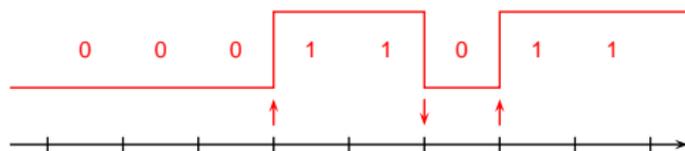
Question: Is the process, as seen by the leftmost \uparrow , recurrent?

DBARW



First instance of DBARW we could find in the literature: [A. Sudbury '90](#). Positive recurrence: [V. Belitsky, P.A. Ferrari, M.V. Menshikov and S.Y. Popov '01](#); [A. Sturm and J.M. Swart '08](#).
Results are very sensitive to the details of branching.

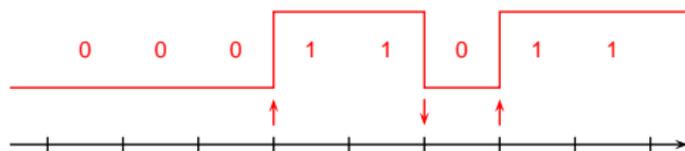
DBARW



First instance of DBARW we could find in the literature: [A. Sudbury '90](#). Positive recurrence: [V. Belitsky, P.A. Ferrari, M.V. Menshikov and S.Y. Popov '01](#); [A. Sturm and J.M. Swart '08](#).
Results are very sensitive to the details of branching.

But: true second class particles interact (*common background of first class particles*).

DBARW



First instance of DBARW we could find in the literature: [A. Sudbury '90](#). Positive recurrence: [V. Belitsky, P.A. Ferrari, M.V. Menshikov and S.Y. Popov '01](#); [A. Sturm and J.M. Swart '08](#).
Results are very sensitive to the details of branching.

But: true second class particles interact (*common background of first class particles*).

↪ Repeat the Sturm-Swart proof with configuration dependent jump rates. **Jump rates can depend on the whole configuration.**

DBARW

Conditions on the jumping and branching rates:

- ▶ Translation invariance.

DBARW

Conditions on the jumping and branching rates:

- ▶ Translation invariance.
- ▶ Uniform lower bound on jumping rates: no particles are stuck.

DBARW

Conditions on the jumping and branching rates:

- ▶ Translation invariance.
- ▶ Uniform lower bound on jumping rates: no particles are stuck.
- ▶ Bounds on the branching rates.

DBARW

Conditions on the jumping and branching rates:

- ▶ Translation invariance.
- ▶ Uniform lower bound on jumping rates: no particles are stuck.
- ▶ Bounds on the branching rates.
- ▶ Bounds on the difference for branching rates of \uparrow 's and \downarrow 's.

DBARW

Conditions on the jumping and branching rates:

- ▶ Translation invariance.
- ▶ Uniform lower bound on jumping rates: no particles are stuck.
- ▶ Bounds on the branching rates.
- ▶ Bounds on the difference for branching rates of \uparrow 's and \downarrow 's.
- ▶ Weak dependence on particles far away.

DBARW

Conditions on the jumping and branching rates:

- ▶ Translation invariance.
- ▶ Uniform lower bound on jumping rates: no particles are stuck.
- ▶ Bounds on the branching rates.
- ▶ Bounds on the difference for branching rates of \uparrow 's and \downarrow 's.
- ▶ Weak dependence on particles far away.
- ▶ No repulsion in the jumping rates between particles. (*A bit of repulsion locally is still OK.*)

Positive recurrence

Theorem

Then, starting from a single \uparrow :

- ▶ *The process takes finitely many steps in finite time (construction).*

Positive recurrence

Theorem

Then, starting from a single \uparrow :

- ▶ *The process takes finitely many steps in finite time (construction).*
- ▶ *The width of the process has all moments finite.*

Positive recurrence

Theorem

Then, starting from a single \uparrow :

- ▶ *The process takes finitely many steps in finite time (construction).*
- ▶ *The width of the process has all moments finite.*
- ▶ *The process as seen from the leftmost \uparrow is positive recurrent.*

Positive recurrence

Theorem

Then, starting from a single \uparrow :

- ▶ *The process takes finitely many steps in finite time (construction).*
- ▶ *The width of the process has all moments finite.*
- ▶ *The process as seen from the leftmost \uparrow is positive recurrent.*
- ▶ *The stationary distribution sees a finite expected number of particles.*

Positive recurrence

Theorem

Then, starting from a single \uparrow :

- ▶ *The process takes finitely many steps in finite time (construction).*
- ▶ *The width of the process has all moments finite.*
- ▶ *The process as seen from the leftmost \uparrow is positive recurrent.*
- ▶ *The stationary distribution sees a finite expected number of particles.*
- ▶ *(Extension of all this to non nearest neighbour symmetric branching.)*

An example

- ▶ Branching rates: constant.
- ▶ Jump rate to the right:

$$\frac{1}{2} + \sum_{\text{particle on right}} \frac{1}{\text{distance}^{\alpha}},$$

jump rate to the left:

$$\frac{1}{2} + \sum_{\text{particle on left}} \frac{1}{\text{distance}^{\alpha}},$$

$$\alpha > 1.$$

An example

- ▶ Branching rates: constant.
- ▶ Jump rate to the right:

$$\frac{1}{2} + \sum_{\text{particle on right}} \frac{1}{\text{distance}^{\alpha}},$$

jump rate to the left:

$$\frac{1}{2} + \sum_{\text{particle on left}} \frac{1}{\text{distance}^{\alpha}},$$

$$\alpha > 1.$$

Unfortunately we do **not** seem to be there yet... This is **not** covered at the moment. **But a small modification that respects parity in a peculiar way works.**

Another example

- ▶ Branching rates: constant.
- ▶ Jump rate to the right:

$$\frac{1}{2} + \sum_{\text{gaps } L_i \text{ on the right}} \frac{1}{L_i^\alpha}$$

jump rate to the left:

$$\frac{1}{2} + \sum_{\text{gaps } L_i \text{ on the left}} \frac{1}{L_i^\alpha}$$

$\alpha > 1$. (~ like a rank dependent model but decreasing with distance.)

Another example

- ▶ Branching rates: constant.
- ▶ Jump rate to the right:

$$\frac{1}{2} + \sum_{\text{gaps } L_j \text{ on the right}} \frac{1}{L_j^\alpha}$$

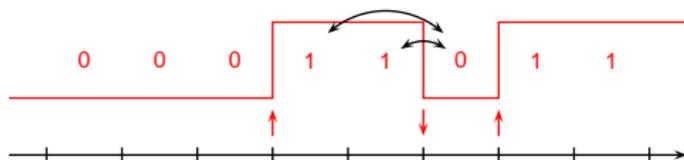
jump rate to the left:

$$\frac{1}{2} + \sum_{\text{gaps } L_j \text{ on the left}} \frac{1}{L_j^\alpha}$$

$\alpha > 1$. (~ like a rank dependent model but decreasing with distance.)

This one is fine.

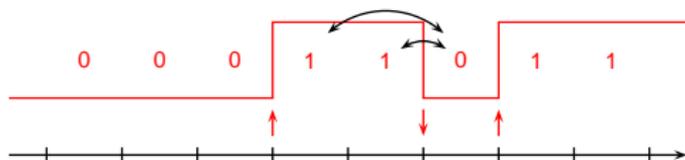
Two words on the proof



Main tool 1: the number of inversions, i.e., wrongly ordered 1-0 pairs.

If there are too many of them, the generator is negative on the number of these pairs.

Two words on the proof



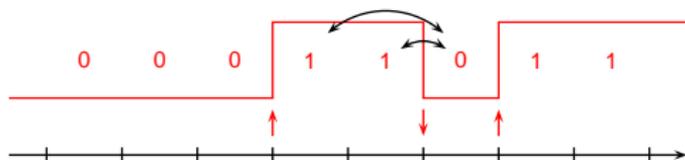
Main tool 1: the number of inversions, i.e., wrongly ordered 1-0 pairs.

If there are too many of them, the generator is negative on the number of these pairs.

Main tool 2: if the process is not tight, then on the long run there cannot be any finite number of particles:

$$\frac{1}{T} \int_0^T \mathbf{P}\{\text{number}(t) < N\} dt \rightarrow 0 \quad (\forall N).$$

Two words on the proof



Main tool 1: the number of inversions, i.e., wrongly ordered 1-0 pairs.

If there are too many of them, the generator is negative on the number of these pairs.

Main tool 2: if the process is not tight, then on the long run there cannot be any finite number of particles:

$$\frac{1}{T} \int_0^T \mathbf{P}\{\text{number}(t) < N\} dt \rightarrow 0 \quad (\forall N).$$

Thank you.