

# Exercises on the Directed Landscape

Based on Lectures and the Paper by Dauvergne, Ortmann, and Virág

## Abstract

These exercises are based on lectures discussing the paper “The Directed Landscape” by Dauvergne, Ortmann, and Virág. They explore properties of the directed landscape using Tracy-Widom tail bounds, Brownian absolute continuity, and modulus of continuity bounds.

**Definition** (Tracy-Widom Tail Bounds). Let  $TW$  denote a Tracy-Widom GUE random variable. There exist constants  $d > 0$  such that for all  $a > 0$ ,

$$\mathbb{P}(TW \leq -a) \leq \exp(1 - da^{3/2}), \quad \mathbb{P}(TW \geq a) \leq \exp(1 - da^3).$$

These bounds apply to the scaled fluctuations of the directed landscape  $\mathcal{L}(p; q)$  at fixed times or positions.

**Definition** (Brownian Absolute Continuity). For the directed landscape  $\mathcal{L}(p; q)$ , the process  $(\mathcal{L}(0, 0; x/2, t) - \mathcal{L}(0, 0; 0, t), x \in [0, x_0])$  is absolutely continuous with respect to a standard Brownian motion with variance one, with a Radon-Nikodym derivative bounded by  $e^{cx_0^3}$  for some constant  $c > 0$ .

**Definition** (Modulus of Continuity Bound). For the directed landscape  $\mathcal{L}(p; q)$ , define the stationary version  $\mathcal{R}(x, s; y, t) = \mathcal{L}(x, s; y, t) + \frac{(x-y)^2}{t-s}$ . For two points  $u_i = (x_i, s_i; y_i, t_i)$ ,  $i = 1, 2$ , let

$$\xi = \xi(u_1, u_2) = \|(x_1, y_1) - (x_2, y_2)\|, \quad \tau = \tau(u_1, u_2) = \|(s_1, t_1) - (s_2, t_2)\|.$$

Then for any  $b \geq 2$ ,  $\epsilon \leq 1$ , and  $u_1, u_2 \in K_\epsilon^b$  with  $\tau \leq \epsilon^{3/b^3}$ , we have

$$|\mathcal{R}(u_1) - \mathcal{R}(u_2)| \leq C \left( \tau^{1/3} \log^{2/3}(\tau^{-1}) + \xi^{1/2} \log^{1/2}(4b\xi^{-1}) \right),$$

with a random constant  $C$  satisfying  $\mathbb{P}(C > m) \leq cb^{10}\epsilon^{-6}e^{-dm^{3/2}}$ , where  $c, d$  are universal constants.

**Exercise 1.** Use the Tracy-Widom tail bounds to show that

$$\mathbb{P}(|\mathcal{L}(u + (0, 0; 0, t)) - \mathcal{L}(u)| < -at^{1/3}) \leq \exp(1 - da^3)$$

for some constant  $d > 0$  and all  $u$  and  $a, t > 0$ .

**Exercise 2.** Use Brownian absolute continuity to show that for  $u = (0, 0; 0, 1)$ ,

$$\mathbb{P}(|\mathcal{L}(u + (0, 0; x, 0)) - \mathcal{L}(u)| > ax^{1/2}) \leq \exp(1 - da^2)$$

for some constant  $d > 0$  and all  $a, x > 0$ .

**Exercise 3.** Let  $X = \arg \max_x \mathcal{L}(0, 0; x, 1)$ . Show that there exists a constant  $d > 0$  such that

$$\mathbb{P}(|X| > a) \leq \exp(1 - da^3)$$

for all  $a > 0$ . Use the Tracy-Widom tail bounds to handle integer  $x$ , and Brownian absolute continuity to handle  $x$  in between.

**Exercise 4.** Show that for the unique  $(0, 0; 0, 1)$  geodesic  $\gamma$  in the directed landscape,

$$\mathbb{P}(\gamma(1/2) > a) \leq \exp(1 - da^3)$$

for some constant  $d > 0$ . (Hint: Essentially the same proof as in Exercise 3 can be applied.)

**Exercise 5.** Show that for  $u = (0, 0; 0, 1)$ ,

$$\mathbb{P}(|\mathcal{L}(u + (0, 0; 0, t)) - \mathcal{L}(u)| > at^{1/3}) \leq \exp(1 - da^{3/2})$$

for some constant  $d > 0$  and all  $a > 0$  and  $t \in [0, 1]$ . (Note: This direction is much harder than Exercise 1.)

**Exercise 6.** Use Brownian absolute continuity and scaling to show that

$$(\mathcal{L}(0, 0; x/2, t) - \mathcal{L}(0, 0; 0, t), x \geq 0)$$

converges in law to a standard Brownian motion  $(B(x), x \geq 0)$  as  $t \rightarrow \infty$ .

**Exercise 7.** Use the modulus of continuity bounds for  $L$  to show that the  $(0, 0; 0, 1)$ -geodesic  $\gamma$  is Hölder- $\alpha$  continuous for all  $\alpha < 2/3$ .