Dynamic chain graphs for high-dimensional time series: an application to real-time traffic flow forecasting

Catriona Queen Joint work with Osvaldo Anacleto ¹

Department of Mathematics and Statistics The Open University

University of Bristol Seminar February 2014

¹Now at Roslin Institute, Edinburgh University

Dynamic chain graphs for high-dimensional time series

The Managed Motorways project

Managed Motorways - motorway of the future





Step & Panalos Grap \$200019 Cove segrap.20

Dynamic chain graphs for high-dimensional time series

Traffic modelling



- Minute-by-minute data at different locations in a network.
- Online, real-time environment.
- Road managers need to take decisions given traffic conditions.

Real-time flow forecasts are crucial for road management

法国际 医耳道氏

э

- Several approaches applied to traffic modelling: mathematical models, neural networks, ARIMA, state space models...
- Usually difficult to provide real-time forecasts.
- Most models are univariate.

Challenge: develop multivariate flow forecasting models for an on-line environment

Focus: M60/M62/M602 intersection



Pictures taken from Google Maps

Dynamic chain graphs for high-dimensional time series

Focus: M60/M62/M602 intersection



Pictures taken from Google Maps

Dynamic chain graphs for high-dimensional time series

Manchester network



- Data available for 31 sites.
- Minute-by-minute flow data.
- Aggregate data to 5 min intervals.
- It takes less than five minutes to traverse the network.
- Flow modelled using occupancy, speed and headway as predictors.



Dynamic chain graphs for high-dimensional time series

Multivariate time series: observations are taken simultaneously over time.

Goal: develop a multivariate model which accommodates the interrelationships among the series

As the number of time series increases modelling becomes challenging.

Approach: graphical modelling to enable a complex problem to be split up into simpler ones.

Representing a network by a graph

Road layout example:



Directed acyclic graph (DAG):



DAG defines a set of conditional distributions: child | parents

Breaks multivariate problem into univariate conditionals: $Y_t(1)$ $Y_t(2)|Y_t(1)$ $Y_t(3)|Y_t(2)$

DAGs for traffic networks: Queen et al., ANZJS (2007),

Dynamic chain graphs for high-dimensional time series

Representing a network by a graph

Road layout example:



Directed acyclic graph (DAG):



DAG defines a set of conditional distributions: child | parents

Breaks multivariate problem into univariate conditionals: $Y_t(1)$ $Y_t(2)|Y_t(1)$ $Y_t(3)|Y_t(2)$

DAGs for traffic networks: Queen et al., ANZJS (2007)

Manchester DAG



Dynamic chain graphs for high-dimensional time series

- T-

Ξ.

Graphs allow local computations for joint probability distributions



æ

- ∢ ≣ →

- MDM is a dynamic Bayesian network.
- A DAG is used to decompose $f(\mathbf{y}_t)$ at each time t.
- Each $Y_t(i)$ |parents is a Bayesian dynamic model, i = 1, ..., n.

MDM definition

Represent multivariate time series $\mathbf{Y}_t = (Y_t(1), \dots, Y_t(n))^T$ by a DAG. Observation equations:

$$Y_t(i) = \mathbf{F}_t(i)^{\top} \theta_t(i) + v_t(i), \quad v_t(i) \sim N(0, V_t(i)), \quad i = 1, ..., n_t$$

• $\mathbf{F}_t(i)$ is function of contemporaneous values of the parents of $Y_t(i)$,

э

- MDM is a dynamic Bayesian network.
- A DAG is used to decompose $f(\mathbf{y}_t)$ at each time t.
- Each $Y_t(i)$ |parents is a Bayesian dynamic model, i = 1, ..., n.

MDM definition

Represent multivariate time series $\mathbf{Y}_t = (Y_t(1), \dots, Y_t(n))^T$ by a DAG. Observation equations:

 $Y_t(i) = \mathbf{F}_t(i)^{\top} \boldsymbol{\theta}_t(i) + v_t(i), \quad v_t(i) \sim N(0, V_t(i)), \quad i = 1, ..., n,$

System equation: $\theta_t = \mathbf{G}_t \theta_{t-1} + \mathbf{w}_t, \quad \mathbf{w}_t \sim N(0, \mathbf{W}_t)$

F_t(i) is function of contemporaneous values of the parents of Y_t(i),
G_t and W_t are block diagonal matrices,

- MDM is a dynamic Bayesian network.
- A DAG is used to decompose $f(\mathbf{y}_t)$ at each time t.
- Each $Y_t(i)$ |parents is a Bayesian dynamic model, i = 1, ..., n.

MDM definition

Represent multivariate time series $\mathbf{Y}_t = (Y_t(1), \dots, Y_t(n))^T$ by a DAG. Observation equations:

 $Y_t(i) = \mathbf{F}_t(i)^{\top} \boldsymbol{\theta}_t(i) + v_t(i), \quad v_t(i) \sim N(0, V_t(i)), \quad i = 1, ..., n,$

System equation: $\theta_t = \mathbf{G}_t \theta_{t-1} + \mathbf{w}_t$, $\mathbf{w}_t \sim N(0, \mathbf{W}_t)$ Initial information: $\theta_0 | D_0 \sim N(\mathbf{m}_0, \mathbf{C}_0)$

- $\mathbf{F}_t(i)$ is function of contemporaneous values of the parents of $Y_t(i)$,
- G_t and W_t are block diagonal matrices,
- **C**₀ also block diagonal.

- ▲ 臣 ▶ ▲ 臣 ▶ ▲ 臣 ■ ∽ � � �

- MDM is a dynamic Bayesian network.
- A DAG is used to decompose $f(\mathbf{y}_t)$ at each time t.
- Each $Y_t(i)$ |parents is a Bayesian dynamic model, i = 1, ..., n.

MDM definition

Represent multivariate time series $\mathbf{Y}_t = (Y_t(1), \dots, Y_t(n))^T$ by a DAG. Observation equations:

$$Y_t(i) = \mathbf{F}_t(i)^{\top} \boldsymbol{\theta}_t(i) + v_t(i), \quad v_t(i) \sim N(0, V_t(i)), \quad i = 1, ..., n_t$$

System equation: $\theta_t = \mathbf{G}_t \theta_{t-1} + \mathbf{w}_t$, $\mathbf{w}_t \sim N(0, \mathbf{W}_t)$ Initial information: $\theta_0 | D_0 \sim N(\mathbf{m}_0, \mathbf{C}_0)$

- $\mathbf{F}_t(i)$ is function of contemporaneous values of the parents of $Y_t(i)$,
- G_t and W_t are block diagonal matrices,
- **C**₀ also block diagonal.

э.

The MDM cont.

- $\theta_0(1), \ldots, \theta_0(n)$ independent $\Rightarrow \theta_t(1), \ldots, \theta_t(n)$ independent after observing \mathbf{y}_t .
- Each $Y_t(i)$ modelled separately by (conditional) univariate dynamic linear model (DLM) with parents as regressors.
- Separate forecast distributions for $Y_t(i)$ | parents.
- Marginal forecast moments for $Y_t(i)$ calculated separately.
- After \mathbf{Y}_t observed, each $\theta_t(i)$ updated separately.

The MDM cont.

- $\theta_0(1), \ldots, \theta_0(n)$ independent $\Rightarrow \theta_t(1), \ldots, \theta_t(n)$ independent after observing \mathbf{y}_t .
- Each $Y_t(i)$ modelled separately by (conditional) univariate dynamic linear model (DLM) with parents as regressors.
- Separate forecast distributions for $Y_t(i)$ | parents.
- Marginal forecast moments for $Y_t(i)$ calculated separately.
- After \mathbf{Y}_t observed, each $\theta_t(i)$ updated separately.
- Model computations fast and relatively straightforward, no matter how complex the network.
- DLM-related techniques can be used.

MDM: Queen and Smith, JRSSB (1993)

ヨッ イヨッ イヨッ

The MDM cont.

- $\theta_0(1), \ldots, \theta_0(n)$ independent $\Rightarrow \theta_t(1), \ldots, \theta_t(n)$ independent after observing \mathbf{y}_t .
- Each $Y_t(i)$ modelled separately by (conditional) univariate dynamic linear model (DLM) with parents as regressors.
- Separate forecast distributions for $Y_t(i)$ | parents.
- Marginal forecast moments for $Y_t(i)$ calculated separately.
- After \mathbf{Y}_t observed, each $\boldsymbol{\theta}_t(i)$ updated separately.
- Model computations fast and relatively straightforward, no matter how complex the network.
- DLM-related techniques can be used.

MDM: Queen and Smith, JRSSB (1993)

Directed acyclic graph:

$$Y_t(1) \rightarrow Y_t(2) \rightarrow Y_t(3)$$

Linear MDM consists of 3 separate univariate DLMs for:

- $Y_t(1)$: any appropriate univariate DLM.
- $Y_t(2) \mid y_t(1)$: DLM for $Y_t(2)$ with $y_t(1)$ as linear regressor.
- $Y_t(3) \mid y_t(2)$: DLM for $Y_t(3)$ with $y_t(2)$ as linear regressor.

э

MDM copes with traffic modelling problems in real-time

- Seasonality modelling in high-frequency traffic time series.
- Time-varying flow variances.
- Measurement errors.
- Use of extra variables as predictors.

An MDM restriction



Under the MDM, forecast covariance of $Y_t(1)$ and $Y_t(2)$ is 0.

Not always true in practice.

Dynamic chain graphs for high-dimensional time series

æ

An MDM restriction



Under the MDM, forecast covariance of $Y_t(1)$ and $Y_t(2)$ is 0.

Not always true in practice.



Dynamic chain graphs for high-dimensional time series



- DAG assumes a complete ordering of the time series components.
- In many cases only a partial ordering is available.
- A chain graph allows for partial orderings between time series components.

э

Motivation for a new model



- DAG assumes a complete ordering of the time series components.
- In many cases only a partial ordering is available.
- A chain graph allows for partial orderings between time series components.

Motivation for a new model



- DAG assumes a complete ordering of the time series components.
- In many cases only a partial ordering is available.
- A chain graph allows for partial orderings between time series components.



chain graph =

dynamic chain graph model (DCGM)



Chain components: $\{X_1, X_2\}$, $\{X_3, X_4\}$, $\{X_5, X_6\}$, $\{X_7\}$.

The DCGM:

- Each chain component modelled separately by (conditional) multivariate dynamic model.
- Each $Y_t(i)$ has its parents as regressors.

э



Chain components: $\{X_1, X_2\}$, $\{X_3, X_4\}$, $\{X_5, X_6\}$, $\{X_7\}$.

The DCGM:

- Each chain component modelled separately by (conditional) multivariate dynamic model.
- Each $Y_t(i)$ has its parents as regressors.
- *n*-dimensional problem broken into *N* separate multivariate problems of smaller dimensions.



Chain components: $\{X_1, X_2\}$, $\{X_3, X_4\}$, $\{X_5, X_6\}$, $\{X_7\}$.

The DCGM:

- Each chain component modelled separately by (conditional) multivariate dynamic model.
- Each $Y_t(i)$ has its parents as regressors.
- *n*-dimensional problem broken into *N* separate multivariate problems of smaller dimensions.
- MDM is special case in which all chain components are single variables.

DCGM: Anacleto and Queen, OU Statistics Group Technical Report 13/02



Chain components: $\{X_1, X_2\}$, $\{X_3, X_4\}$, $\{X_5, X_6\}$, $\{X_7\}$.

The DCGM:

- Each chain component modelled separately by (conditional) multivariate dynamic model.
- Each $Y_t(i)$ has its parents as regressors.
- *n*-dimensional problem broken into *N* separate multivariate problems of smaller dimensions.
- MDM is special case in which all chain components are single variables.

DCGM: Anacleto and Queen, OU Statistics Group Technical Report 13/02

Chain graph for the Manchester network



Form chain graph of 4 root nodes and 1 child each (and relabel):



Dynamic chain graphs for high-dimensional time series

DCGM for subnetwork



DCGM consists of 5 separate models:

- Multivariate DLM for $Y_{t1}(1), \ldots, Y_{t4}(1)$ (matrix-normal DLM),
- Univariate DLM for $Y_t(2)$ with $y_{t1}(1)$ as regressor,
- Univariate DLM for $Y_t(3)$ with $y_{t2}(1)$ as regressor,
- Univariate DLM for $Y_t(4)$ with $y_{t3}(1)$ as regressor,
- Univariate DLM for $Y_t(5)$ with $y_{t4}(1)$ as regressor.

Problem: Occupancy, Headway and Speed cannot be incorporated into model for $Y_{t1}(1), \ldots, Y_{t4}(1)!$

DCGM for subnetwork



DCGM consists of 5 separate models:

- Multivariate DLM for $Y_{t1}(1), \ldots, Y_{t4}(1)$ (matrix-normal DLM),
- Univariate DLM for $Y_t(2)$ with $y_{t1}(1)$ as regressor,
- Univariate DLM for $Y_t(3)$ with $y_{t2}(1)$ as regressor,
- Univariate DLM for $Y_t(4)$ with $y_{t3}(1)$ as regressor,
- Univariate DLM for $Y_t(5)$ with $y_{t4}(1)$ as regressor.

Problem: Occupancy, Headway and Speed cannot be incorporated into model for $Y_{t1}(1), \ldots, Y_{t4}(1)!$

- nac

Comparison: DCGM with LMDM

One-step forecasts obtained for flows in December 2010.



Manchester Evening News headline, December 2010

DCGM gives better forecasts based on the joint log-predictive likelihood of the 8 series

・ 同 ト ・ ヨ ト ・ ヨ ト

Comparison: DCGM with LMDM

One-step forecasts obtained for flows in December 2010.



Manchester Evening News headline, December 2010

DCGM gives better forecasts based on the joint log-predictive likelihood of the 8 series

< - 10 b

→ ∃ → → ∃ →

Marginal univariate forecasts



Observed flows and forecasts for Yt1(1) - 22/12/2010 (from 15:00 to 19:59)

Time of dav(Hours)

æ



Dynamic chain graphs for high-dimensional time series

In traffic modelling: direction of the flow induces a graph for traffic networks.

But...

structural learning is a key problem in many applications.

Example: gene expression modelling

- Nodes in the graph represent genes.
- Data are high-dimensional time series of gene expression levels (n << p).
- Goal: estimate relationships between different genes.

 $\mathbf{X}_t = [X_t(1), X_t(2), X_t(3), X_t(4)]^\top$: vector of gene expression levels.

Dynamic Bayesian networks seem to be useful tool.



Data observed on different time scales \Rightarrow contemporaneous relationships.



MDM possible model.

2

-∢ ⊒ →

Work in progress...



Gene $X_t(1)$ regulates $X_t(2)$ and $X_t(3)$.

2

글 🖌 🔺 글 🕨



 $X_t(1)$ may be missing from the data set.

글 > : < 글 >

Ξ.

Work in progress...



Missing common regulator can be accommodated with DCGM.

Dynamic chain graphs for high-dimensional time series

æ –

글 > : < 글 >

- Graphs can be used to simplify multivariate time series modelling.
- Multiregression dynamic model can provide on-line traffic forecasts — series represented by a DAG.
- Dynamic chain graphical models can improve forecasts by allowing partial orderings in a graph series represented by a chain graph.
- Use of the MDM and DCGM for structural learning for gene expression data seems promising.

Anacleto, O., Queen, C.M. Dynamic chain graph models for multivariate time series (osvaldoanacleto.com/DCGmodel.pdf).

Anacleto, O., Queen, C.M, Albers, C.J. (2013). Multivariate forecasting of road traffic flows in the presence of heteroscedasticity and measurement errors. *JRSS-C 62(2), March 2013.*

Anacleto, O., Queen, C.M., Albers, C.J. (2013). Forecasting multivariate road traffic flows using Bayesian dynamic graphical models, splines and other traffic variables. *Australian & New Zealand Journal of Statistics*, *62*(2), *June 2013*.