Compression via Sparse Linear Regression

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(Acknowledgements: S. Tatikonda, T. Sarkar, A. Joseph, A. Barron)

May 9, 2014



Information Theory deals with

- Communication
- Compression (Lossless and Lossy)
- Multi-terminal communication and compression: Multiple-access channels, Broadcast channels, Distributed compression, . . .
- Sharp characterization of achievable rates for many of these problems

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Textbook code constructions are based on:

- *Random coding* for point-to-point communication and compression
- Superposition and binning for multi-terminal problems
- High complexity of storage and coding: *exponential* in "n"

GOAL:

- Codes with compact representation + fast encoding/decoding
 'Fast' ⇒ polynomial in n
- In the last 20 years, many advances: LDPC/LDGM codes, Polar codes for finite-alphabet sources & channels
- We will focus on Gaussian sources and channels here

In this talk ...

- Ensemble of codes based on sparse linear regression
- *Provably* achieve rates close to info-theoretic limits with fast encoding + decoding
- Based on construction of Barron & Joseph for AWGN channel
 - Achieve capacity with fast decoding [IT Trans. '12, '14]

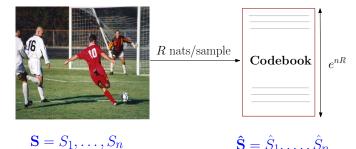
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Outline

- We'll focus on the compression problem:
 - Fundamental limits of the code (with optimal encoding)
 - Computationally efficient compression algorithm & analysis
- Extension to multi-terminal communication and compression

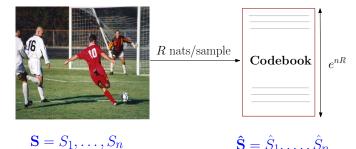
Lossy Compression



- Distortion criterion: $\frac{1}{n} \|\mathbf{S} \hat{\mathbf{S}}\|^2 = \frac{1}{n} \sum_k (S_k \hat{S}_k)^2$
- To achieve $\frac{1}{n} \|\mathbf{S} \mathbf{\hat{S}}\|^2 \le D$, need $R > R^*(D) = \min_{P_{\hat{S}|S}} I(S; \hat{S})$
- For i.i.d $\mathcal{N}(0, \sigma^2)$ source, $R^*(D) = \frac{1}{2} \log \frac{\sigma^2}{D}$, $D < \sigma^2$

 \Rightarrow Minimum possible distortion $D^*(R) = \sigma^2 e^{-2R}$

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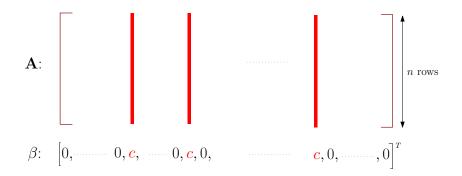
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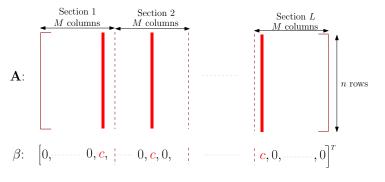
Can we achieve this with *low-complexity* algorithms?

Sparse Regression Codes (SPARC)



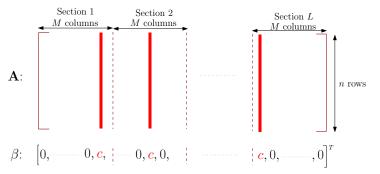
- A: design matrix or 'dictionary' with ind. $\mathcal{N}(0,1)$ entries
- Codewords $A\beta$ sparse linear combinations of columns of A

SPARC Construction



n rows, ML columns

SPARC Construction

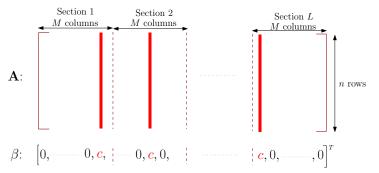


n rows, ML columns

Choosing *M* and *L*:

- For rate R codebook, need $M^L = e^{nR}$
- Choose $M = L^b$ for $b > 1 \Rightarrow bL \log L = nR$

SPARC Construction



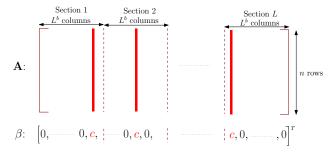
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- Choose $M = L^b$ for $b > 1 \Rightarrow bL \log L = nR$
- $L \sim n/\log n$ and $M \sim$ polynomial in n
- Storage Complexity \leftrightarrow Size of **A**: polynomial in n

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Minimum Distance Encoding



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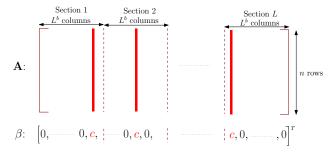
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Given source sequence **S** with variance σ^2 :

• Encoder: Find $\hat{\beta} = \arg\min_{\alpha} \|\mathbf{S} - \mathbf{A}\beta\|^2$

• Decoder: Reconstruct $\hat{\mathbf{S}} = \mathbf{A}\hat{\boldsymbol{\beta}}$

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$$P_n = P\left(\frac{1}{n} \|\mathbf{S} - \mathbf{A}\hat{\beta}\|^2 > D\right)$$

Want to show that P_n → 0 if R > ¹/₂ log ^{σ²}/_D
Also want asymptotic rate of decay (error exponent)

SPARC Rate-Distortion Function

Theorem (RV-Joseph-Tatikonda '12, RV-Tatikonda '14)

For a source with variance σ^2 , SPARCs with minimum-distance encoding achieve distortion D for all rates

$$R > \frac{1}{2}\log \frac{\sigma^2}{D}$$

when
$$b > b_{min}$$
 where

$$b_{min} = \begin{cases} \frac{2.5R}{R-1+D/\sigma^2} & \text{if } R > (1-\frac{D}{\sigma^2}) \\ \frac{40R}{\left(\frac{2R}{(1-D/\sigma^2)}-1\right)^2 \left((1-\frac{D}{\sigma^2})(2+\frac{D}{\sigma^2})-2R\right)} & \text{if } R \le (1-\frac{D}{\sigma^2}) \end{cases}$$

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Note:

$$\frac{D}{\sigma^2} \in (0.203, 1) \quad \Leftrightarrow \quad \left(1 - \frac{D}{\sigma^2}\right) > \frac{1}{2}\log\frac{\sigma^2}{D}$$

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Setting up the analysis

Call
$$\beta$$
 a *solution* if $|\mathbf{S} - \mathbf{A}\beta|^2 \leq D$

For $i = 1, \ldots, e^{nR}$, define

$$U_i = \left\{egin{array}{cc} 1 & ext{if } eta(i) ext{ is a solution }, \ 0 & ext{otherwise.} \end{array}
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The number of solutions X is

$$X = U_1 + \ldots + U_{e^{nR}}$$

Want to show $P(X > 0) \rightarrow 1$ as $n \rightarrow \infty$

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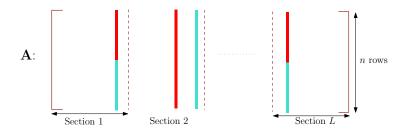
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Notice that the U_i 's are *dependent*!

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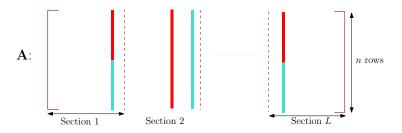
Dependent Codewords

- Each codeword sum of L columns
- Codewords $\beta(i), \beta(j)$ dependent if they have common columns



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The number of codewords sharing r common terms with any $\beta(i)$ is

$$\binom{L}{r}(M-1)^{L-r}, \quad r=0,1,\ldots,L$$

codewords dependent with $\beta(i) = M^L - 1 - (M - 1)^L$

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The Second Moment Method (2nd MoM)

$$X = U_1 + \ldots + U_{e^{nR}}$$

To show P(X > 0) w.h.p., we use the 2nd MoM:

$$P(X > 0) \geq rac{(\mathbb{E}X)^2}{\mathbb{E}[X^2]}$$

Proof: $(\mathbb{E}[XY])^2 \leq \mathbb{E}[X^2]\mathbb{E}[Y^2]$ with $Y = \mathbf{1}_{\{X>0\}}$.

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The *expected* number of solutions is

$$\mathbb{E}X = e^{nR}P(U_1 = 1) \doteq e^{n(R - \frac{1}{2}\log\frac{\sigma^2}{D})}$$

$$\mathbb{E}X o \infty$$
 if $R > rac{1}{2}\log rac{\sigma^2}{D}$, but is $X > 0$ w.h.p. ?

The Second Moment

$$\mathbb{E}[X^2] = \mathbb{E}[(U_1 + \ldots + U_{e^{nR}})^2]$$
$$= e^{nR} \sum_{r=0}^{L} {\binom{L}{r}} (M-1)^{L-r} \mathbb{E}[U_1 U_2 \mid \beta_1, \beta_2 \text{ share } r \text{ terms }]$$

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The key ratio is

$$\frac{(\mathbb{E}X)^2}{\mathbb{E}[X^2]} \doteq \left(\frac{D}{\sigma^2}\right)^n \left[\sum_{r=0}^{L} \binom{L}{r} (M-1)^{-r} \underbrace{\mathbb{E}[U_1 U_2 \mid \beta_1, \beta_2 \text{ share } r \text{ terms}]}_{\text{can compute Chernoff bound}}\right]^{-1}$$

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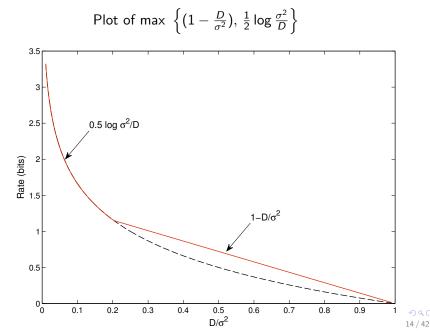
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$$P(X = 0) < L^{-\frac{1}{R}(b-b_{min})(R-(1-\frac{D}{\sigma^2}))}$$

÷

We've shown that rates $R>\max\left\{(1-rac{D}{\sigma^2}),\,rac{1}{2}\lograc{\sigma^2}{D}
ight\}$ are achievable

What we have shown ...



Key Question: For

$$(0.203) < \frac{D}{\sigma^2} < 1$$

- Is the SPARC inherently a suboptimal code?
- Or, is it a shortcoming of the proof technique?

Why does the 2nd MoM fail ?

$$\mathbb{E}[X^2] = \mathbb{E}[(U_1 + \ldots + U_{2^{nR}})^2] = \mathbb{E}[X] \mathbb{E}[X|U_1 = 1]$$

Hence
$$P(X > 0) \ge \frac{(\mathbb{E}X)^2}{\mathbb{E}[X^2]} = \frac{\mathbb{E}[X]}{\mathbb{E}[X|U_1 = 1]}$$

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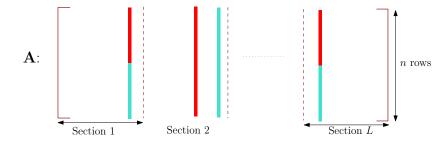
We want $\mathbb{E}[X|\beta(1) \text{ is a solution}] \sim \mathbb{E}[X]$

But when
$$\frac{1}{2} \log \frac{\sigma^2}{D} < R < (1 - \frac{D}{\sigma^2})$$
$$\frac{\mathbb{E}[X|\beta(1) \text{ is a solution}]}{\mathbb{E}[X]} \rightarrow \infty$$

- The expected number of solutions given that we have one solution blows up!
- Similar phenomenon in random hypergraph 2-colouring [Coja-Oghlan, Zdeborova '12]

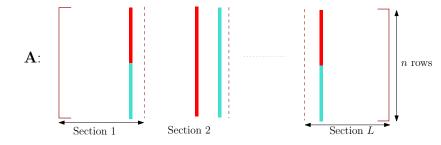
Q: Why is $\mathbb{E}[X|\beta(1) \text{ is a solution}] \gg \mathbb{E}[X]$?

- There are many codewords $\beta(i)$ that are *dependent* with $\beta(1)$
- If $\beta(1), \beta(i)$ are dependent: given that $|\mathbf{S} \mathbf{A}\beta(1)|^2 \le D$, the probability of $|\mathbf{S} - \mathbf{A}\beta(i)|^2 \le D$ increases



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• Even a *small increase* in the probability may be enough to blow up $\mathbb{E}[X|\beta(1) \text{ is a solution}]$

A Stylized Example

Assume that the number of solutions X can only take one of two values

$$X = \begin{cases} 2^n & \text{with probability } 1 - 2^{-np} \\ 2^{1.1n} & \text{with probability } 2^{-np} \end{cases}$$

Note:

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$$\mathbb{E}X = 2^{1.1n}2^{-np} + 2^n(1-2^{-np})$$

\$\approx 2^n\$ if \$p > 0.1\$

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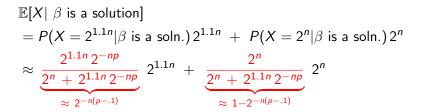
• For 2nd MoM to predict existence of solutions, we need

$$\frac{\mathbb{E}[X]}{\mathbb{E}[X|\beta \text{ is a solution}]} \approx 1$$

Example ctd.

 $\mathbb{E}[X \mid \beta \text{ is a solution}]$ = $P(X = 2^{1.1n} \mid \beta \text{ is a soln.}) 2^{1.1n} + P(X = 2^n \mid \beta \text{ is a soln.}) 2^n$

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$$\mathbb{E}[X \mid \beta \text{ is a solution}] \approx 2^{1.2n} 2^{-np} + 2^n$$
$$\approx \begin{cases} 2^n & \text{if } p > 0.2\\ 2^{1.2n-p} & \text{if } 0.1$$

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$$\approx \begin{cases} 2^n & \text{if } p > 0.2\\ 2^{1.2n-p} & \text{if } 0.1$$

When 0.1 , the 2nd MoM fails because:

• Conditioned on β being a soln., probability of $X = 2^{1.1n}$ \uparrow

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 𝔅[X | β is a solution] ≫ 𝔅X although X | β is a solution ≈ 𝔅X w.h.p

Back to SPARCs

For a *low-probability set* of design matrices:

- $\bullet\,$ Columns of β are unusually well-aligned with ${\bf S}$
- \Rightarrow lots of *neighbours* of a solution are also solutions.
- Due to these atypical matrices,

 $\mathbb{E}[X|\beta \text{ is a solution}] \gg \mathbb{E}[X]$

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Lemma

Given that β is a solution, the number of neighbours of β that are also solutions is less than $L^{-1/2} \mathbb{E}[X]$ with prob. at least $1 - L^{-2}$, when $b > b^*$

The lemma implies

 $X \mid \beta$ is a solution $\sim \mathbb{E}[X]$ with prob. at least $1 - L^{-2}$

Fixing the 2nd MoM

Call a solution β good if fewer than $L^{-1/2} \mathbb{E}[X]$ of its neighbours are also solutions

• Lemma says w.h.p any solution β is good.

$$X_{good} = V_1 + V_2 + \ldots + V_{e^{nR}}$$

where

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• Apply 2nd MoM to show that $X_g > 0$ w.h.p.

This works because $\mathbb{E}[X_{good}|\beta \text{ is a solution}] \approx \mathbb{E}X_{good} \approx \mathbb{E}X$

Summary

- To show X > 0, 2nd MoM method requires $\mathbb{E}[X|\beta] \approx \mathbb{E}X$
- This may not hold although $X|\beta \approx \mathbb{E}[X]$ w.h.p

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Two-step fix

- Show that most solutions are good, i.e., not many neighbours are solutions
- Apply 2nd MoM to count the good solutions

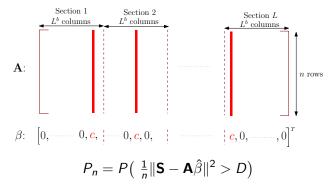
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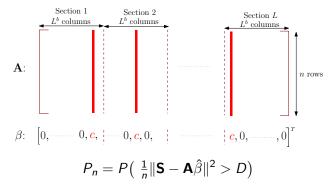
- Show that most solutions are good, i.e., not many neighbours are solutions
- 2 Apply 2nd MoM to count the good solutions
 - Similar situation in random hypergraph 2-colouring [Coja-Oghlan, Zdeberova SODA '12]
 - Step 1 is key, and is problem-specific; Step 2 generic
 - This two-step recipe potentially useful in many problems

So far ...



For any ergodic source with variance σ^2 and distortion $D < \sigma^2$, $P_n \rightarrow 0$ for all rates $R > \frac{1}{2} \log \frac{\sigma^2}{D}$, when $b > b_{min}$

So far ...

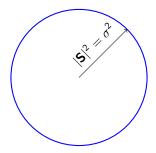


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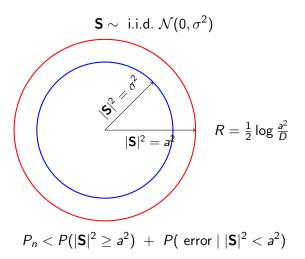
- We would also like to know the *error exponent*: $T = -\lim \sup_{n \to \infty} \frac{1}{n} \log P_n \Rightarrow P_n \lesssim e^{-nT}$
- The 2nd MoM only gives a polynomial decay of P_n in n

Refined Error Analysis for SPARC

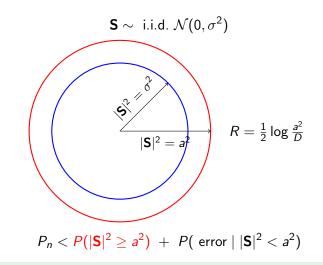
 $\mathbf{S} \sim \text{ i.i.d. } \mathcal{N}(\mathbf{0}, \sigma^2)$



 Refined Error Analysis for SPARC



 Refined Error Analysis for SPARC



• The first term $\leq \exp(-n\mathcal{D}(a^2 \parallel \sigma^2))$

• $\mathcal{D}(a^2 \parallel \sigma^2)$: KL divergence between $\mathcal{N}(0, a^2)$ and $\mathcal{N}(0, \sigma^2)$

Error Analysis

$$P_n < \underbrace{P(|\mathbf{S}|^2 \ge a^2)}_{\text{KL divergence}} + \underbrace{P(\text{ error } ||\mathbf{S}|^2 < a^2)}_?$$

$$P(ext{ error } \mid |\mathbf{S}|^2 < a^2) = P\left(X = 0 \mid |\mathbf{S}|^2 < a^2
ight)$$

where $X = \sum_{i=1}^{e^{nR}} U_i$ and

$$U_i = \begin{cases} 1 & \text{if } \beta(i) \text{ is a solution }, \\ 0 & \text{otherwise.} \end{cases}$$

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Error Analysis

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Error Analysis

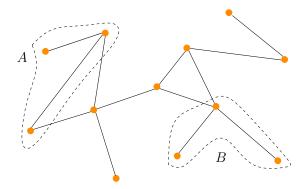
$$P_n < \underbrace{P(|\mathbf{S}|^2 \ge a^2)}_{\text{KL divergence}} + \underbrace{P(\text{ error } ||\mathbf{S}|^2 < a^2)}_?$$

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 and
 $U_i = \begin{cases} 1 & \text{if } \beta(i) \text{ is a solution }, \\ 0 & \text{otherwise.} \end{cases}$

We get a sharp bound on $P(X = 0 | |\mathbf{S}|^2 < a^2)$ using Suen's inequality

Dependency Graph



For random variables $\{U_i\}_{i \in \mathcal{I}}$, any graph with vertex set \mathcal{I} s.t: If A and B are two disjoint subsets of \mathcal{I} such that there are no edges with one vertex in A and the other in B, then the families $\{U_i\}_{i \in A}$ and $\{U_i\}_{i \in B}$ are independent.

For our problem

$$U_i = \begin{cases} 1 & \text{if } \beta(i) \text{ is a solution }, \\ 0 & \text{otherwise.} \end{cases}, \quad i = 1, \dots, e^{nR}$$

For the family $\{U_i\}$,

 $\{i \sim j : i \neq j \text{ and } \beta(i), \beta(j) \text{ share at least one common term} \}$

is a dependency graph.

Suen's correlation inequality

Let $\{U_i\}_{i\in\mathcal{I}}$, be Bernoulli rvs with dependency graph Γ . Then

$$P\left(\sum_{i\in\mathcal{I}}U_i=0\right)\leq \exp\left(-\min\left\{\frac{\lambda}{2},\frac{\lambda^2}{8\Delta},\frac{\lambda}{6\delta}\right\}\right)$$

where

$$\lambda = \sum_{i \in \mathcal{I}} \mathbb{E} U_i,$$

$$\Delta = rac{1}{2} \sum_{i \in \mathcal{I}} \sum_{j \sim i} \mathbb{E}(U_i U_j),$$

$$\delta = \max_{i \in \mathcal{I}} \sum_{k \sim i} \mathbb{E} U_k.$$

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Bounding the error

$$\begin{split} P_n &\leq P(|\mathbf{S}|^2 \geq a^2) + P\left(\sum_{i=1}^{e^{nR}} U_i = 0 \mid |\mathbf{S}|^2 < a^2\right) \\ &\leq \exp\left(-n\mathcal{D}(a^2 \parallel \sigma^2)\right) + \exp\left(-\min\left\{\frac{\lambda}{2}, \frac{\lambda}{6\delta}, \frac{\lambda^2}{8\Delta}\right\}\right) \end{split}$$

Bounding the error

$$P_n \le P(|\mathbf{S}|^2 \ge a^2) + P\left(\sum_{i=1}^{e^{nR}} U_i = 0 \mid |\mathbf{S}|^2 < a^2\right)$$
$$\le \exp\left(-n\mathcal{D}(a^2 \parallel \sigma^2)\right) + \exp\left(-\min\left\{\frac{\lambda}{2}, \frac{\lambda}{6\delta}, \frac{\lambda^2}{8\Delta}\right\}\right)$$

where for sufficiently large n

$$\lambda > e^{n\left(R - \frac{1}{2}\log\frac{a^2}{D} - \epsilon_n\right)}, \quad \frac{\lambda}{\delta} > L^{b-1}, \quad \frac{\lambda^2}{\Delta} > L^{(b-b_{\min})(1 - (1 - D/a^2)/R)}$$

- For large n, the first KL divergence term dominates P_n
- $\lambda, \frac{\lambda}{\delta}, \frac{\lambda^2}{\Delta}$ all grow polynomially in *n* for $b > b^*$ \Rightarrow second term decays *super-exponentially*
- Need to use refinement technique when $R < (1 D/a^2)$

Error Exponent of SPARC with Min-Distance Encoding

$$P_n = P\left(\frac{1}{n} \|\mathbf{S} - \mathbf{A}\hat{\beta}\|^2 > D\right)$$

Theorem (RV, Joseph, Tatikonda '12, '14)

- For $R > \frac{1}{2} \log \frac{\sigma^2}{D}$, the probability of error P_n decays exponentially in n for $b > b^*$
- 2 The error-exponent $\mathcal{D}(a^2 \parallel \sigma^2)$, with $a^2 = De^{2R}$, is optimal for Gaussian sources with squared-error distortion.

Error Exponent of SPARC with Min-Distance Encoding

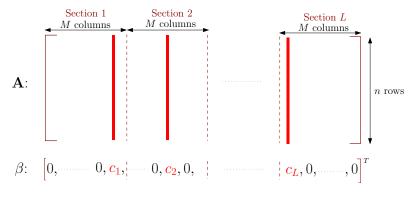
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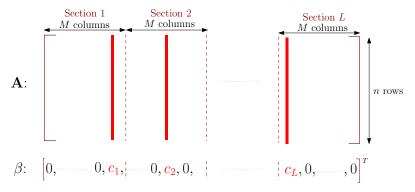
- This result shows that SPARCs are structurally good codes
- But minimum-distance encoding is infeasible what about practical algorithms?

SPARC Construction



Main Idea: Vary the coefficients across sections

SPARC Construction

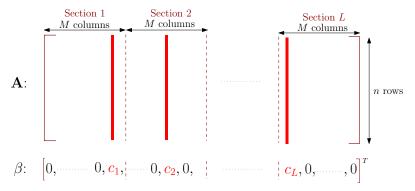


Main Idea: Vary the coefficients across sections

As before:

• For rate R codebook, need $M^L = e^{nR}$

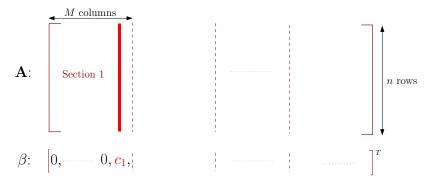
SPARC Construction



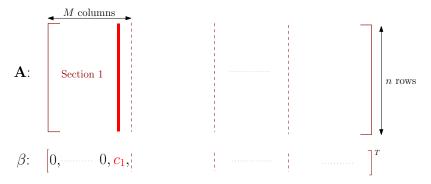
Main Idea: Vary the coefficients across sections

As before:

- For rate R codebook, need $M^L = e^{nR}$
- Choose *M* polynomial of $n \Rightarrow L \sim n/\log n$



Step 1: Choose column in Sec.1 that minimizes $\|\mathbf{S} - c_1 \mathbf{A}_j\|^2$ - $c_1 = \sqrt{2R\sigma^2/L}$

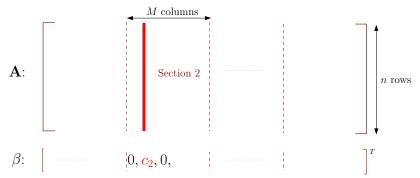


Step 1: Choose column in Sec.1 that minimizes $\|\mathbf{S} - c_1 \mathbf{A}_j\|^2$

-
$$c_1 = \sqrt{2R\sigma^2/L}$$

- Max among inner products $\langle \mathbf{S}, \mathbf{A}_j \rangle$

- Residue
$$\mathbf{R}_1 = \mathbf{S} - c_1 \hat{\mathbf{A}}_1$$

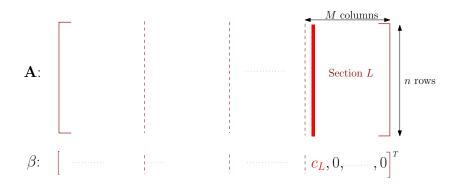


Step 2: Choose column in Sec.2 that minimizes $\|\mathbf{R}_1 - c_2 \mathbf{A}_i\|^2$

-
$$c_2 = \sqrt{\frac{2R\sigma^2}{L}\left(1-\frac{2R}{L}\right)}$$

- Max among inner products $\langle \mathbf{R}_1, \mathbf{A}_j \rangle$

- Residue
$$\mathbf{R}_2 = \mathbf{R}_1 - c_2 \hat{\mathbf{A}}_2$$



Step L: Choose column in Sec.L that minimizes $\|\mathbf{R}_{L-1} - c_L \mathbf{A}_j\|^2$

-
$$c_L = \sqrt{\frac{2R\sigma^2}{L} \left(1 - \frac{2R}{L}\right)^L}$$

- Max among inner products $\langle {f R}_{L-1}, {f A}_j
angle$

- Residue
$$\mathbf{R}_L = \mathbf{R}_{L-1} - c_L \hat{\mathbf{A}}_L$$

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Performance

Theorem (RV, Sarkar, Tatikonda '13)

For an ergodic source **S** with mean 0 and variance σ^2 , the encoding algorithm produces a codeword $\mathbf{A}\hat{\beta}$ that satisfies the following for sufficiently large M, L.

$$P\left(\;|\mathbf{S}-\mathbf{A}\hat{\beta}|^2\;>\;\sigma^2 e^{-2R}+\Delta\;\right)<\exp\left(\;-\kappa n\left(\Delta-\frac{c\log\log M}{\log M}\right)\right)$$

Deviation Δ is $O(\frac{\log \log n}{\log n})$

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Performance

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$$P\left(|\mathbf{S} - \mathbf{A}\hat{\beta}|^2 > \sigma^2 e^{-2R} + \Delta \right) < \exp\left(-\kappa n \left(\Delta - \frac{c \log \log M}{\log M}\right)\right)$$

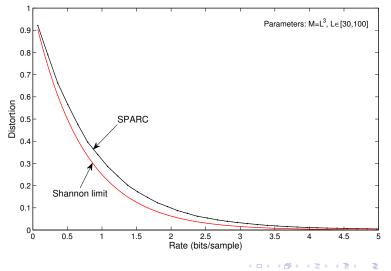
Deviation
$$\Delta$$
 is $O(\frac{\log \log n}{\log n})$

Encoding Complexity

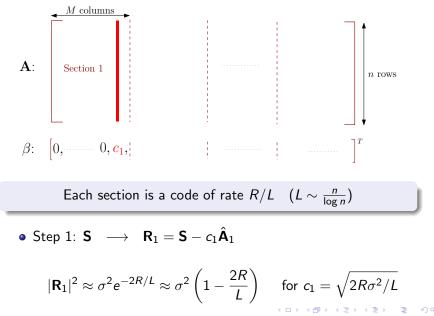
ML inner products and comparisons \Rightarrow *polynomial* in *n*

Simulation

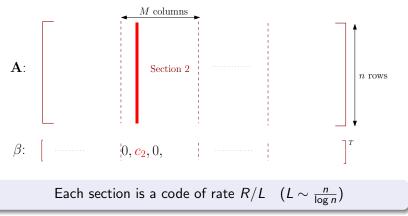
Gaussian source: Mean 0, Variance 1



Why does the algorithm work?



Why does the algorithm work?

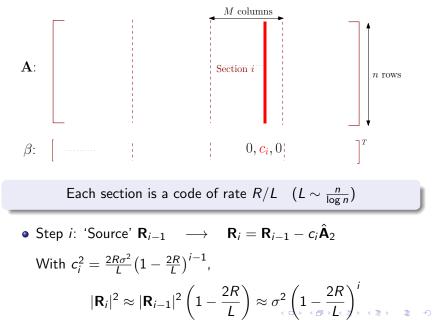


• Step 1: S
$$\longrightarrow$$
 $\mathbf{R}_1 = \mathbf{S} - c_1 \hat{\mathbf{A}}_1$

$$|\mathbf{R}_1|^2 \approx \sigma^2 e^{-2R/L} \approx \sigma^2 \left(1 - \frac{2R}{L}\right)$$
 for $c_1 = \sqrt{2R\sigma^2/L}$

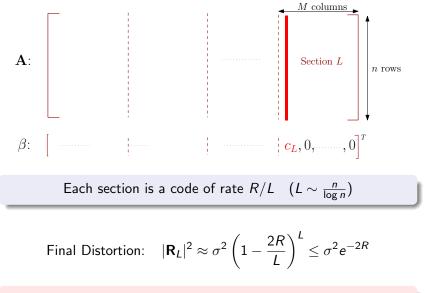
• Step 2: 'Source' $\mathbf{R}_1 \longrightarrow \mathbf{R}_2 = \mathbf{R}_1 - \stackrel{\circ}{c_2} \hat{\mathbf{A}}_2^{\circ} \stackrel{\circ}{\longrightarrow} \stackrel{\circ}{\rightarrow} \stackrel{\circ}{\rightarrow$

Why does the algorithm work?



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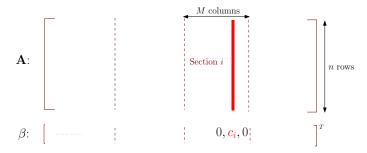
Why does the algorithm work?



L-stage successive refinement $L \sim n/\log n$

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Successive Refinement Interpretation



- The encoder successively refines the source over $\sim \frac{n}{\log n}$ stages
- The deviations in each stage can be significant!

$$|\mathbf{R}_i|^2 = \underbrace{\sigma^2 \left(1 - \frac{2R}{L}\right)^i}_{\text{'Typical Value'}} (1 + \Delta_i)^2, \quad i = 0, \dots, L$$

• KEY to result: Controlling the final deviation Δ_L

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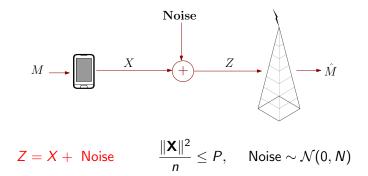
• Source:
$$|\mathbf{S}|^2 = \sigma^2 (1 + \Delta_0)^2$$

- Source: $|\mathbf{S}|^2 = \sigma^2 (1 + \Delta_0)^2$
- Dictionary columns: $|\mathbf{A}_j|^2 = 1 + \gamma_j, \quad 1 \leq j \leq ML$

- Source: $|\mathbf{S}|^2 = \sigma^2 (1 + \Delta_0)^2$
- Dictionary columns: $|\mathbf{A}_j|^2 = 1 + \gamma_j, \quad 1 \leq j \leq ML$
- Computed value:

$$\max_{j} \left\langle \frac{\mathbf{R}_{i-1}}{\|\mathbf{R}_{i-1}\|}, \mathbf{A}_{j} \right\rangle = \sqrt{2 \log M} \ (1 + \epsilon_{i}), \quad 1 \le i \le L$$

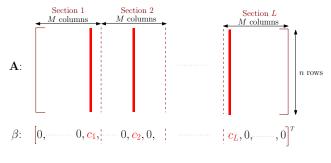
SPARCs for Communicating over Gaussian Channels



GOAL: Achieve rates close to capacity $C = \frac{1}{2} \log \left(1 + \frac{P}{N}\right)$

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Efficient Decoder



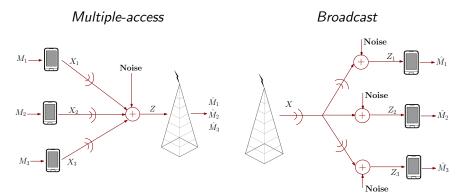
 $\mathbf{Z} = \mathbf{A}\beta + \mathsf{Noise}$

- Each β corresponds to a message $\Rightarrow M^L$ messages
- Efficient decoders proposed by [Barron-Joseph '12], [Barron-Cho '13]:

Achieve rates $R < \mathcal{C} - O\left(\frac{\log \log M}{\log M}\right)$ with $P_e < e^{-cL(\mathcal{C}-R)^2}$

Multi-terminal networks

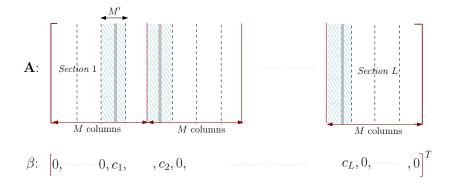
Examples:



Key ingredients

- Superposition (Multiple-access, Broadcast)
- Random binning (e.g., distributed compression, source/channel coding with side-information)

Binning with SPARCs



[RV-Tatikonda, Allerton '12]

Any random coding scheme that consists of point-to-point source and channel codes combined via binning/superposition can be implemented with SPARCs.

Summary

Sparse Regression Codes

- Rate-optimal for Gaussian compression and communication
- Low-complexity coding algorithms that provably attain Shannon limits

Future Directions

- Better channel decoders and source encoders:
 Approximate message passing, l₁ minimization etc.?
- Simplified design matrices

Can we prove that the results hold for ± 1 design matrices

- Network information theory: Multiple descriptions, Interference channels ...
- Finite-field analogues: binary SPARCs?

Papers at http://www2.eng.cam.ac.uk/~rv285/pub.html = _________