Some McKean–Vlasov problems on the half-line

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Loss-dependent correlation model Contagion model

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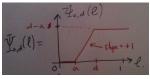


Motivation

- Initial motivation: portfolio credit derivatives
- $N \geq 1$ defaultable assets, default times $\{\tau^{i,N}\}_{1 \leq i \leq N}$,
- Care about options on proportional loss process

$$L_t^N = \frac{1}{N} \sum_{i=1}^N \mathbf{1}_{\tau^{i,N} \le t}, \qquad \text{value} = \mathbf{E} \Psi((L^N)_{t \in [0,T]})$$

Think of Ψ of form



- Correlations matter: high $\rho \implies$ higher probability of defaulting together
- But also higher chance of surviving together

Model

Basic model — Bush, Hambly, Howarth, Jin, Reisinger (2011)

$$egin{aligned} dX^i_t &= \mu dt +
ho dW_t + \sqrt{1 -
ho^2} dW^i_t \ au^i &= \inf\{t > 0: X^i_t \leq 0\} \ X^i_0 &\sim
u_0 \end{aligned}$$

- Take a limit as $N o \infty$,
- Study the empirical processes

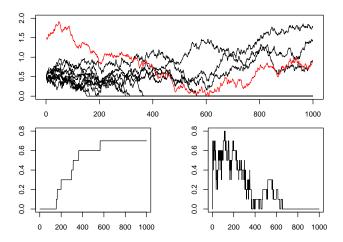
$$\nu_t^N = \frac{1}{N} \sum_{i=1}^N \mathbf{1}_{t < \tau^i} \delta_{X_t^i} \in \mathcal{M}$$

• Everything conditionally iid, so (marginal) convergence is easy $\nu_t^N(\phi) \rightarrow \nu_t(\phi) := \mathbf{E}[\phi(X_t^1)\mathbf{1}_{t < \tau^1}|W], \quad \mathcal{L}_t^N \rightarrow \nu_t(\mathbf{1}_{(0,\infty)}) = \mathbf{P}(\tau \le t|W)$

• Price with
$$L_t := \mathbf{P}(\tau \leq t | W)$$

Loss-dependent correlation model Contagion model

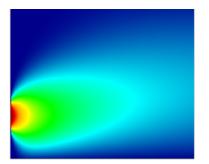
Basic model

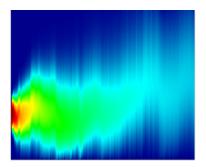


SPDE — Bush, Hambly, Howarth, Jin, Reisinger (2011)

$$d\nu_t(\phi) = \mu\nu_t(\partial_x\phi)dt + \frac{1}{2}\nu_t(\partial_{xx}\phi)dt + \rho\nu_t(\partial_x\phi)dW_t$$

$$\phi(0) = 0.$$





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Proof

Easy! Conditional independence, Linear evolution equation. *Existence*: Ito (drop μ)

$$\phi(X_t^i) = \phi(X_0^i) + \frac{1}{2} \int_0^t \phi''(X_s^i) ds + \int_0^t \rho \phi'(X_s^i) dW_s + \int_0^t \sqrt{1 - \rho^2} \phi'(X_s^i) dW_s^i$$

If $\phi(0) = 0$ stopping incorporates b.c.: $\phi(X_{t \wedge \tau^i}^i) = \phi(X_t^i) \mathbf{1}_{t < \tau^i}$. Take average over $1 \le i \le N$

$$eqn(\nu^{N})_{t} = \frac{1}{N} \sum_{i=1}^{N} \int_{0}^{t} \sqrt{1 - \rho^{2}} \phi'(X_{s}^{i}) dW_{s}^{i} = O_{\text{m.s.}}(N^{-1})$$

In limit: $eqn(\nu)_t = 0$.

Proof

Uniqueness: Smooth with heat kernel

$$T_{\varepsilon}\nu_t(x) := \int_0^\infty \frac{1}{\sqrt{2\pi\varepsilon}} \Big(e^{-\frac{(x-x_0)^2}{2\varepsilon}} - e^{-\frac{(x+x_0)^2}{2\varepsilon}} \Big) \nu_t(dx_0) \in C^\infty$$

 $eqn(T_{\varepsilon}\nu) = rem(\nu, \varepsilon)$. Manipulate classically using energy estimation

$$\mathbf{\mathsf{E}} \| T_{\varepsilon} \nu_t \|_2^2 + \mathbf{\mathsf{E}} \int_0^t \| \partial_x T_{\varepsilon} \nu_s \|_2^2 ds \le \| T_{\varepsilon} \nu_0 \|_2^2 + \mathbf{\mathsf{E}} \| \operatorname{rem}(\nu, \varepsilon) \|_2^2$$

Control remainder with the quantity

$$\mathbf{E}
u_t(0,arepsilon)^2 = \mathbf{P}(X^1_t, X^2_t \in (0,arepsilon), t < au^1 \wedge au^2)$$

need $o(\varepsilon^{3+\delta})$ control

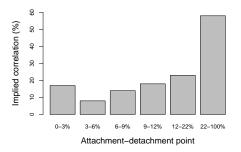
Proof

$$\mathbf{E}\nu_t(0,\varepsilon)^2 = \mathbf{P}(X_t^1, X_t^2 \in (0,\varepsilon), t < \tau^1 \wedge \tau^2)$$

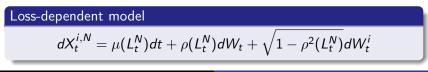
Explicit formula, or note harmonic function with zero b.c. in wedge decays like $O(r^{1+\delta})$

Extension

 Model is too simple, can't choose one ρ to match all traded tranche spreads, *correlation skew* or *smile*,



• Why not make ρ a function of the loss in the system?



Extension

• Can have diffusions, but drop for talk

Loss-dependent model

$$dX_t^{i,N} =
ho(L_t^N) dW_t + \sqrt{1 -
ho^2(L_t^N)} dW_t^i$$

- Piecewise constant ρ across tranches desirable
- Allow at least finitely many discontinuities, piecewise Lipschitz ρ
- Need 0 $\leq \rho(\ell) \leq \rho_{\max} <$ 1, stop degeneracy
- Challenges: need to deal with boundary effects but correlation too complicated to do explicit calculations,
- For convergence, discontinuous ρ bad, key to show limit points must have strictly increasing loss
- Associated SPDE is non-linear

Results

Tightness/Weak existence

The sequence of triples $(\nu^N, L^N, W)_{N \ge 1}$ are tight (with suitable topology). If (ν^*, L^*, W) realises a limiting law, then

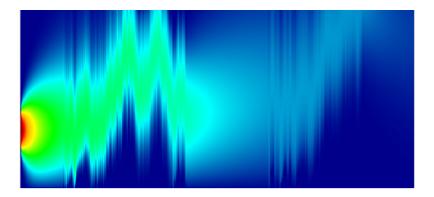
$$d\nu_t^*(\phi) = \frac{1}{2}\nu_t^*(\partial_{xx}\phi)dt + \rho(L_t)\nu_t^*(\partial_x\phi)dW_t$$
$$L_t^* = 1 - \nu_t^*(0,\infty).$$

[+ some regularity conditions.]

Pathwise uniqueness/LLN

For a given W, the SPDE has a most one solution ν . Hence there is a unique law of a solution (ν, L, W) and so the sequence converges to it.





Results

• Weak existence + pathwise uniqueness gives strong solution (on rich enough space), so

M–V problem

With (ν, L, W) be the unique soln. For any independent B.M. W^{\perp} there exists a process X satisfying

$$\begin{split} dX_t &= \rho(L_t) dW_t + \sqrt{1 - \rho(L_t)^2} \, dW_t^{\perp} \\ \tau &:= \inf\{t > 0 : X_t \le 0\} \\ \nu_t(\phi) &= \mathbf{E}[\phi(X_t) \mathbf{1}_{t < \tau} | W], \qquad \qquad L_t = \mathbf{P}(\tau \le t | W) \end{split}$$

The law of (X, W) is unique.

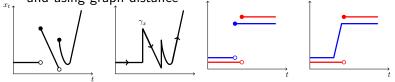
- Conditional/stochastic M–V problem
- Sznitman, Topics in propagation of chaos (1991)

Methods

Proof outline

Pick suitable topology \rightarrow prove tightness \rightarrow show limiting laws solve SPDE \rightarrow uniqueness for Lip. $\rho(\cdot) \rightarrow$ extend to all $\rho(\cdot)$.

- Skorokhod M1 topology is useful
- dist(x, y) defined on D_R by joining up discontinuity points and using graph distance



Tightness controlled by modulus of continuity:

$$w(x; \delta) = \sup_{t} \sup_{(t_1, t_2, t_3) \in \operatorname{Trip}_{t, \delta}} |x_{t_2} - [x_{t_1}, x_{t_3}]_{\mathsf{R}}|_{\mathsf{R}}$$

• Vanishes if x is monotone

Topology

- Useful for L.L.N. in queuing theory, Whitt, *Stochastic process limits* (2002)
- We extend to infinite-dim. range space,
- Work on $D_{\mathcal{S}'}$, space of distribution-valued càdlàg paths
- *M* ⊆ *S*′, recovering *f* ∈ *M* generally easy, allows for CLT (perhaps)

Tightness characteristion

 $(\nu^N)_{N\geq 1}$ tight on $(D_{\mathcal{S}'}, M1)$ iff $(\nu^N(\phi))_{N\geq 1}$ tight on $(D_{\mathbf{R}}, M1)$ for all $\phi \in C_0^{\infty}(\mathbf{R})$.

- Extends Mitoma (1983)
- Useful as

$$\nu_t^N(\phi) = \frac{1}{N} \sum_{i=1}^N \phi(X_t^{i,N}) \mathbf{1}_{t < \tau^{i,N}} = \frac{1}{N} \sum_{i=1}^N \phi(X_{t \wedge \tau^{i,N}}^{i,N}) - \phi(0) L_t^N$$

Loss-dependent SPDE

- Existence easy once tightness established, Care that topology strong enough to recover SPDE
- Also need to know $t \mapsto L_t^*$ strictly increasing, long estimates,
- For uniqueness estimates, work in space H^{-1}

$$\mathbf{E}\partial_x^{-1} \| T_{\varepsilon}\nu_t \|_2^2 + \mathbf{E}\int_0^t \| T_{\varepsilon}\nu_s \|_2^2 ds \le \|\partial_x^{-1}T_{\varepsilon}\nu_0\|_2^2 + \mathbf{E}\|\partial_x^{-1}\operatorname{rem}(\nu,\varepsilon)\|_2^2$$

- Only required $o(\varepsilon^{1+\delta})$ control on remainder,
- Enough to use trivial bound

$$\mathsf{E}\nu_t(0,\varepsilon)^2 \leq \mathsf{E}\nu_t(0,\varepsilon) = \lim_{N \to \infty} \mathsf{P}(X^{1,N}_t \in (0,\varepsilon), t < \tau^{1,N})$$

- Eliminates correlation, much easier to work with
- Use a stopping argument for Lip. and uniqueness

A neuroscience model

- Many neurons, look at typical behaviour
- Voltage level $t \mapsto X_t$
- Start at $X_0 > 0$, distributed as ν_0
- Experiences own noise, $(B_t)_{t\geq 0}$, and spikes when hits level 0
- But receives a kick towards the origin of size α times the proportion of spiking particles:

M-V problem (mean field)

$$X_t = X_0 + B_t - \alpha L_t$$

$$\tau = \inf\{t > 0 : X_t \le 0\}$$

$$L_t = \mathbf{P}(\tau \le t)$$

• (Then restarts back on $[0,\infty)$ according to ν_0 — but problem is hard enough)

Loss-dependent correlation model Contagion model

PDE and integral equation

M–V problem (mean field)

$$X_t = X_0 + B_t - \alpha L_t$$

$$\tau = \inf\{t > 0 : X_t \le 0\}$$

$$L_t = \mathbf{P}(\tau \le t)$$

- What does it mean to solve? Find L
- Can rewrite as a PDE and IE

• Let
$$u_t(\phi) := \mathsf{E}[\phi(X_t) \mathbf{1}_{t < \tau}]$$
, so $L_t = 1 - \nu_t(\mathbf{1}_{(0,\infty)})$,

PDE problem (large population distn.)

$$egin{aligned} d
u_t(\phi) &= rac{1}{2}
u_t(\partial_{xx}\phi)dt - lpha
u_t(\partial_x\phi)dL_t\ L_t &= 1 -
u_t(\mathbf{1}_{(0,\infty)}) \end{aligned}$$

PDE and integral equation

PDE problem (large population distn.)

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u_t(\partial_x\phi)dL_t\ &L_t &= 1 -
u_t(\mathbf{1}_{(0,\infty)}) \end{aligned}$$

• If solution is nice, V_t density of ν_t

PDE problem (large population distn.)

$$\partial_t V_t(x) = \frac{1}{2} \partial_{xx} V_t(x) dt + \alpha \partial_t L_t \partial_x V_t(x)$$
$$L_t = 1 - \int_0^\infty V_t(x) dx$$
$$V_t(0) = 0, \quad x \mapsto V_0(x) \text{ given}$$
$$[\quad \partial_t L_t = \partial_x V_t(0) \quad]$$

PDE and integral equation

• Or, given Brownian motion with drift $t\mapsto \ell_t$

$$X_t^\ell = X_0 + B_t - \alpha \ell_t,$$

the function $\Gamma[\ell]_t := \mathbf{P}(au^\ell \leq t)$ satisfies

$$\int_0^\infty \Phi\Big(-\frac{x-\alpha\ell_t}{t^{1/2}}\Big)V_0(x)dx = \int_0^t \Phi\Big(\alpha\frac{\ell_t-\ell_s}{(t-s)^{1/2}}\Big)d\Gamma[\ell]_t$$

- Also: hitting law of Brownian motion on boundary $t\mapsto lpha\ell_t$
- (Laplace transform on this law to get IE Volterra IE of first kind)



Solutions

Delarue, Inglis, Rubenthaler, Tanré (2015)

With $\nu_0 = \delta_{x_0}$, there exists $\alpha_0 > 0$ such that for all $\alpha < \alpha_0$ there exists a unique solution to (M–V) with $t \mapsto L_t \in C^1[0, T]$

Cáceres, Carrillo, Perthame (2011)

For any initial condition, there exists $\alpha_1 > 0$ such that for all $\alpha > \alpha_1$ no continuous function $t \mapsto L_t$ solves (M–V)

A simpler proof

Suppose a continuous solution exists. Set $\phi(x) = x$ into PDE.

$$0 < \nu_t(\phi) = \nu_0(\phi) - \alpha \int_0^t \nu_s(1) dL_s = \nu_0(\phi) - \alpha \int_0^t (1 - L_s) dL_s$$

Solutions

...A simpler proof

Can do this integral since continuous and increasing

$$\frac{\alpha}{2}(1-(1-L_t)^2) \le \nu_0(\phi).$$

By ignoring drift, easy to see $L_t
ightarrow 1$ as $t
ightarrow \infty$. Therefore

$$\frac{\alpha}{2} \leq \nu_0(\phi).$$

So $\alpha_1 = 2\nu_0(\phi)$ will do.

 \bullet Obviously not an optimal choice of $\alpha_1,$ so \ldots

Solutions

Critical value?

Fix an initial condition (come back to this!) does there exist a critical value $\alpha_c > 0$ such that

 $\alpha < \alpha_c \implies$ a continuous solution exists

 $\alpha > \alpha_c \implies$ a continuous solution cannot exist (blow-up)?

- Obvious monotonicity arguments delicate: depends on rate, not absolute value, of *L*
- Location of blow-up tricky:

Monotone?

Let $\bar{\alpha} > \alpha > \alpha_c$, does $L^{\bar{\alpha}}$ blow-up before L^{α} ?

How to build solutions

- Three ways
- First is fixed point problem:
- Set $\ell = 0$, put in $\Gamma[\ell]$, iterate $\Gamma[\Gamma[\ell]]$, ..., $\Gamma[...\Gamma[\Gamma[\ell]]...]$
- Done in [DIRT15] on subspace of C^1 with sup-norm $(W^{1,\infty})$
- ...but requires assumptions from theorem
- Second approach: delay the equation:

$$X_t^{\delta} = X_0 + B_t - \alpha L_t^{\delta}, \qquad \qquad L_t^{\delta} = \mathbf{P}(\tau^{\delta} \le t - \delta)$$

An easy problem: Initially no contribution (when t < δ), so solve problem on [0, δ), then use that information to solve on [δ, 2δ), etc...

How to build solutions

- Delay prevents blow-up, so $L^{\delta} \in C^1[0, T]$
- Limit as $\delta \rightarrow 0$ shown to converge in [DIRT15a]
- Also in that paper: Third approach: The microscopic model
- This is important as it contains the physical meaning
- The problem is that we want blow-up to occur, models synchronisation of neurons
- Should have existence and uniqueness theory that incorporates blow-up i.e. a way to restart solutions
- To solve the problem, let solutions *L* have jumps (restrict to càdlàg)
- How?

- Underspecified:
- M–V problem (mean field)

$$X_t = X_0 + B_t - \alpha L_t$$

$$\tau = \inf\{t > 0 : X_t \le 0\}$$

$$L_t = \mathbf{P}(\tau \le t)$$

what if L jumps? $\Delta L_t := L_t - L_{t-t}$

• $L_t - L_s = \mathbf{P}(X_s + \inf_{s < u < t} \{B_{s,u} - \alpha L_{s,u}\} \le 0, \tau > s)$, send $s \uparrow t$

•
$$\Delta L_t = \mathbf{P}(X_{t-} \in (0, \alpha \Delta L_t), \tau > t) = \nu_{t-}(0, \alpha \Delta L_t)$$

• So jump at t solves $J = \nu_{t-}(0, \alpha J)$, Still underspecified!

• Obvious solution: look for càdlàg solutions with jumps as small as they need to be at each time

Defn: Minimal-jump solution

If L solves (M–V) and is càdlàg, then L is a minimal-jump solution if whenever \overline{L} is another such solution agreeing with L on [0, t) then

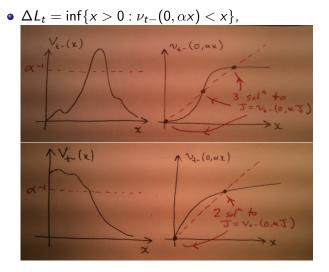
$$\Delta L_t \leq \Delta \overline{L}_t.$$

Characterisation

L is a minimal-jump solution iff L solves (M-V) and

$$\Delta L_t = \inf\{x > 0 : \nu_{t-}(0, \alpha x) < x\}, \quad \text{for all } t$$

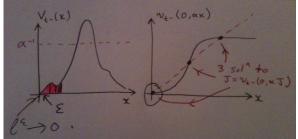
• Existence of minimal-jump solutions [DIRT2015a]



- Eat $\ell_0^{\varepsilon} = \varepsilon$ mass,
- Solution takes $\ell_1^{\varepsilon} = \varepsilon + \nu_{t-}(0, \alpha \ell_0^{\varepsilon})$
- Then takes $\ell_2^{\varepsilon} = \varepsilon + \nu_{t-}(0, \alpha \ell_1^{\varepsilon})$, ...
- $\ell^{\varepsilon} = \varepsilon + \nu_{t-}(0, \alpha \ell^{\varepsilon})$, decreasing in ε

•
$$\rightarrow \ell = \nu_{t-}(0, \alpha \ell)$$

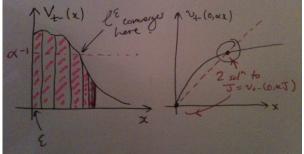
• Easy to see $\ell = \inf\{x > 0 : \nu_{t-}(0, \alpha x) < x\}$



- Eat $\ell_0^{\varepsilon} = \varepsilon$ mass,
- Solution takes $\ell_1^{\varepsilon} = \varepsilon + \nu_{t-}(0, \alpha \ell_0^{\varepsilon})$
- Then takes $\ell_2^{\varepsilon} = \varepsilon + \nu_{t-}(0, \alpha \ell_1^{\varepsilon})$, ...
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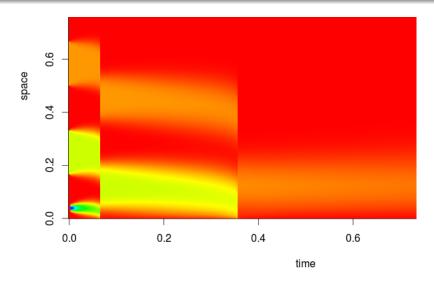
•
$$\rightarrow \ell = \nu_{t-}(0, \alpha \ell)$$

• Easy to see $\ell = \inf\{x > 0 : \nu_{t-}(0, \alpha x) < x\}$



Loss-dependent correlation model Contagion model

Global solutions



Uniqueness?

Is there a unique minimal-jump solution for a given initial condition?

 All current uniqueness arguments exploit smoothness and initial conditions that are too well-behaved— after blow-up *ν*_t(0, *x*) = *O*(*x*), √*t* singularity

$P/w C^1?$

Does the solution behave as C^1 function between jumps? Weighted space?

- Solution density decays in max value quicker than the heat equation, $t^{-1/2}$,
- So there is a last possible time for a jump to occur,

Frequency?

Is there an upper bound on the number of jumps that can occur for a given α over all possible initial conditions?

Common noise

What about adding a rough (deterministic) noise $t \mapsto z_t$

$$X_t = X_0 + B_t + z_t - \alpha L_t, \qquad L_t = \mathbf{P}_B(\tau \le t)?$$

What if not Holder-1/2?